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Effects of CO$_2$ on P-wave attenuation in porous media with micro-cracks: a synthetic modelling study

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Abstract

The presence of CO$_2$ in hydrocarbon reservoirs can cause significant changes in seismic wave properties. In turn these properties can be used to map CO$_2$ saturation in hydrocarbon reservoirs or aquifers - either from natural sources or by injection from the surface. We present the results of a synthetic modelling study of the effects of supercritical CO$_2$ saturation on P-wave attenuation in a medium consisting of four horizontal layers, including a target aquifer. The target aquifer is modelled fully by an effective medium containing pores saturated with brine and/or CO$_2$ and randomly-aligned microcracks at different densities. The other layers are modelled solely by their bulk seismic velocities and densities. We first compute synthetic seismograms for a reference case where the third layer is completely isotropic with no cracks, no pores and no fluid saturation. We then calculate synthetic seismograms for finite crack densities of 0.01, 0.02 and 0.03 at varying degrees of CO$_2$ saturation in the third layer. The results of our analysis indicate that attenuation is sensitive both to CO$_2$ saturation and the crack density. For a given crack density, attenuation increases gradually with decreasing percentage of CO$_2$ saturation and reaches a maximum at around 10% saturation. The induced attenuation increases with crack density and with offset. These observations hold out the potential of using seismic attenuation as an additional diagnostic in the characterisation of rock formations for a variety of applications, including hydrocarbon exploration and production, subsurface storage of CO$_2$ or geothermal energy extraction.
Keywords: Attenuation, Seismic Quality Factor, CO₂, microcracks, fluid saturation

1.0 Introduction

CO₂ is a natural constituent of hydrocarbon reservoirs with saturations varying from 2 - 80% (Roberts, 2009). It is also often deliberately injected into hydrocarbon reservoirs to enhance production rates and sweep efficiencies, and stored in subsurface reservoirs and saline aquifers as a means of mitigating climate change from the burning of fossil fuels. At surface temperatures and pressures, CO₂ exists in the gaseous phase but exhibits supercritical behaviour above the critical point: temperature $T_c = 31.1^\circ C$ and pressure $P_c = 7.38$ MPa (David et al., 2008). White (1975) demonstrated that the presence of a gas in the rock can have a substantial influence on the seismic wave velocity and attenuation, depending on the degree of saturation, permeability, frequency and porosity. The presence of CO₂ in the reservoir either in the gaseous or supercritical state can cause significant changes in seismic properties (such as seismic wave travel time, velocity, amplitude, attenuation) and thus, an understanding of its influence could be of great importance in the study of hydrocarbon reservoir properties. For instance, Davis et al. (2003) reported that CO₂ can cause a change of 4 - 6% in P-wave velocity and 5 - 10% in S-wave velocity. Time-lapse studies for monitoring CO₂ sequestration in the subsurface have also shown that the presence of CO₂ can cause significant changes in both the P- and S-wave velocities (e.g. Arts et al., 2004; Chadwick et al., 2005, Amir and Landro, 2009). David et al. (2008) observed significant changes in the calculated bulk seismic velocity and density in CO₂-saturated porous reservoir rocks under field conditions, where the CO₂ may exist either as a supercritical fluid or as a supercritical gas. In both cases, the bulk density decreases systematically and linearly with increasing percentage of CO₂ saturation, though more distinctly for the supercritical gas case. Their results demonstrate that the P-wave velocity shows an obvious non-linear
relationship with saturation. For the supercritical fluid case, there is a remarkable decrease in the P-wave velocity between zero and 30 % CO₂ saturation and thereafter very little or no change in the velocity. For the supercritical gas case, there is even a stronger decrease in the P-wave velocity at small CO₂ saturations of < 5 - 10 % with very little or no change at higher saturations.

The attenuation of seismic wave energy in rocks depends on the physical state of the rocks and on the degree and type of fluid saturation in the pore space. For instance, P-wave attenuation has been shown to be greater in partially-saturated rocks compared to fully-saturated rocks (e.g. White, 1975; Toksoz et al., 1979; Johnson et al., 1979; Winkler and Nur, 1982; Klimentos, 1995). Despite the intensive effort in research and development related to the effects that CO₂ might have on seismic wave response (e.g. Rubino et al., 2011a and Rubino et al., 2011b, Rossi et al., 2011, Müller et al., 2015), there is still a lack of adequate understanding of the effects of CO₂ on seismic wave attenuation, especially at varying degrees of saturation. Thus, a concerted effort is still needed for a fuller understanding of these complex processes. In this paper, we examine the effects of CO₂ held in the pore space of the rock on seismic attenuation, through synthetic modelling. To provide a realistic scenario for the modelling study, we use the published bulk moduli of both brine and CO₂ measured in the Sleipner gas field in the North Sea (Chadwick et al., 2005). Our main aim is to examine the changes caused by the presence of CO₂ at varying percentages of saturation on P-wave attenuation in a layered medium where the target layer contains randomly-aligned microcracks. Our theoretical model consists of four horizontal isotropic layers, where the third layer is the target layer. The layer is modelled as a fully poro-elastic medium containing brine with different crack densities and different amounts of injected CO₂. The model accounts for anelastic losses due to the squirt-flow mechanism, which in turn depends on the crack density and fluid properties. To simplify the treatment, we assume the other layers can be characterised solely by their isotropic bulk velocities and densities. We first
calculate a reference model for the case that the third layer has zero crack density, no pores and no fluid saturation. We then consider a case in which the third layer in the model is saturated with CO$_2$ at concentrations varying from 0 to 100 % and crack densities of 0.01, 0.02 and 0.03 respectively. We used the classical spectral ratio method to compute the induced attenuation from the synthetic data. Our results demonstrate the sensitivity of attenuation to CO$_2$ saturation, providing a fuller understanding into the effects of the pattern of seismic attenuation caused by CO$_2$ in fluid-saturated porous rocks and especially validating the practical utility of using attenuation characteristics as an additional diagnostic in the characterisation of rock formations for a variety of applications, including hydrocarbon exploration and production, subsurface storage of CO$_2$ or geothermal energy extraction.

2.0 Chapman’s poro-elastic model

The poro-elastic model of Chapman (2003) considers the pore space of a rock to consist of a lattice configuration of spherical pores, randomly oriented ellipsoidal micro-cracks and aligned ellipsoidal fractures. The radius of the micro-cracks and spherical pores is identified with the grain size. The fracture size is assumed to be much larger than the grain size but smaller than the seismic wavelength. Since the fractures have preferential alignment, the resulting medium has hexagonal symmetry (transverse isotropy). Wave-induced pressure gradients cause fluid exchange between adjacent elements of pore space in the rock. The fluid exchange between two adjacent voids ‘a’ and ‘b’ for instance is described by the formula (Chapman 2003):

$$\partial_t m_a = \frac{\rho_o K \zeta}{\eta} (p_b - p_a)$$

(1)

where $\rho_o$ is the fluid density, $K$ is the permeability, $\zeta$ is the grain size, $\eta$ is the fluid viscosity, $p_a$ is the pressure in element a, $m_a$ is the mass of fluid in element a and $p_b$ is the pressure in element b. Each element of pore space is assumed to be connected to six other
elements and the resulting flows can be added linearly. The fractures are connected to a
greater number of elements since they are larger than the micro-cracks and the pores. For the
purpose of ensuring that there is some spacing between the fractures, the model assumes that
each micro-crack or pore is connected to at most one fracture and that the fractures are not
connected to each other. These last assumptions require that the number of micro-cracks and
pores greatly exceeds the number of fractures. The effective elastic tensor, $C$ given by
Chapman (2003) is of the form:
\[
C = C^{(0)} - \phi_p C^{(1)} - \varepsilon_c C^{(2)} - \varepsilon_f C^{(3)}
\]  
(2)
where $C^{(0)}$ is the elastic tensor of the isotropic rock matrix with Lame’s parameters $\lambda$ and $\mu$,
$C^{(1)}$, $C^{(2)}$ and $C^{(3)}$ are the additional contributions from pores, micro-cracks and fractures,
respectively, multiplied by the porosity $\phi_p$, the crack density $\varepsilon_c$ and the fracture density $\varepsilon_f$.
These additional contributions are functions of the Lamé parameters, fluid and fracture
properties, frequency and relaxation times associated with squirt flow.

Chapman’s (2003) original model is restricted to very low porosity since the elastic constants
are calculated based on Eshelby’s (1957) interaction energy approach which is only valid for
dilute concentrations of inclusions (Maultzsch et al., 2003). In cases of high porosities, the
calculation of the corrections using the grain moduli $\lambda$ and $\mu$ might result in significant errors.
Furthermore, it is not ideal to use moduli which cannot be obtained from measured velocities.
To address these issues, Chapman et al. (2003) slightly adapted the model to make it more
applicable to real data by using Lame’s parameters $\lambda^o$ and $\mu^o$ derived from the density $\rho$ and
measured P-wave velocity $V_{p}^o$ and S-wave velocity $V_{s}^o$ of the un-fractured rock for the
corrections. Also, $C^{(0)}(\Lambda,M)$ is defined in such a way that the measured isotropic velocities
are obtained by applying the pore and crack corrections at a specific frequency $f_o$ (Chapman
et al., 2003 and Maultzsch et al., 2003). Thus:
\[ \Lambda = \lambda^o + \phi_{c,p} \left( \lambda^o, \mu^o, f_o \right), \quad M = \mu^o + \phi_{c,p} \left( \lambda^o, \mu^o, f_o \right), \] 

(3)

where \( \phi_{c,p} \) refers to corrections to the elastic tensor which are proportional to crack density and porosity.

\[ \lambda^o = \rho \left( V^o_p \right)^2 - 2 \mu^o; \quad \mu^o = \rho \left( V^o_e \right)^2 \] 

(4)

Equation 2 can then be re-written as:

\[ C = C^{(0)}(\Lambda, M, \omega) - \phi_1 C^{(1)}(\lambda^o, \mu^o, \omega) - \varepsilon_2 C^{(2)}(\lambda^o, \mu^o, \omega) - \varepsilon_3 C^{(3)}(\lambda^o, \mu^o, \omega) \] 

(5)

The form of Equation 5 allows the corrections for pores, micro-cracks and fractures which describe the frequency dependence and anisotropy of a material to be obtained from measurements of the velocities (Maultzsch et al., 2003). Chapman et al. (2003) further simplified the model by setting the crack density to zero in the case of high porosity. The influence of this parameter however is not significant for modelling the effects of fractures provided the spherical porosity is much greater than the crack porosity (Maultzsch et al., 2003).

Fluid flow in Chapman’s (2003) model occurs at two scales; the grain scale (associated with the micro-cracks and spherical pores) and the fracture scale. This results in two characteristic frequencies and corresponding relaxation times. The relaxation time, \( \tau_m \) associated with fluid flow between the micro-cracks and spherical pores are related to the squirt-flow frequency, \( f^c_m \) as (Murphy, 1985; Winkler, 1986; Lucet and Zinszner, 1992; Sothcott et al., 2000):

\[ f^c_m = \frac{1}{\tau_m} \] 

(6)

\[ \tau_m = \frac{c \eta (1 + K_c)}{\sigma_c \kappa \varrho c_1} \] 

(7)
where \( c_v \) is the volume of an individual crack, \( \sigma_c \) is the critical stress and \( c_1 \) is the number of connections to other voids. \( \sigma_c \) and \( K_c \) are defined by:

\[
\sigma_c = \frac{\pi \mu r}{2(1 - \nu)}
\]

(8)

\[
K_c = \frac{\sigma_c}{\kappa_f}
\]

(9)

where \( r \) is the aspect ratio of the cracks, \( \nu \) is the poiseuille's ratio of the matrix and \( \kappa_f \) is the fluid bulk modulus. Fluid flow in and out of the fractures is associated with a lower characteristic frequency or a higher corresponding relaxation time \( \tau_f \) which is dependent on the size of the fractures. The relaxation time associated with the grain scale and that associated with the fracture scale are both related by the equation (Chapman, 2003):

\[
t_f = \frac{a_f \tau_m}{\zeta}
\]

(10)

where \( a_f \) is the fracture radius. From Equation 10, it can be inferred that larger fractures will result in higher relaxation times (or lower characteristic frequencies). These larger relaxation times lead to velocity dispersion and attenuation in the seismic frequency range. Thus, in the general case the resulting anisotropy is frequency dependent.

2.0 Theoretical model and experimental set-up

The theoretical model is made up of four horizontal isotropic layers (Figure 1). To investigate the effects of CO\(_2\), a porous fluid-saturated material is introduced into the third layer and squirt flow between the pores in the matrix is taken into consideration. The material is saturated with brine and CO\(_2\) (in the supercritical state) at different degrees of concentrations. The elastic properties of the porous material are computed using the poroelastic model of Chapman (2003). However, to model the effect of fluid saturation in a porous but unfractured medium, we set the fracture density to zero so that the model returns to the earlier
model of Chapman et al. (2002). The bulk moduli of the brine and CO$_2$ are based on the data from the Sleipner field in the North Sea (Chadwick et al., 2005). The field is a site for large scale CO$_2$ injection project specifically designed as a greenhouse gas mitigation measure (Chadwick et al., 2005). Millions of tonnes of CO$_2$ have been injected since 1996 into the Utsira Sand, which constitutes a major saline aquifer in the field (Chadwick et al., 2005; Bickle et al., 2007; Arts, et al., 2008) with over 11 million tonnes by 2010 (Chadwick et al., 2010). The Utsira sand has a thickness of 200 - 300m and CO$_2$ exists in the reservoir in the supercritical phase (Chadwick et al., 2005). Details of the model parameters used are given in Table 1.

A uniform saturation of the pores and cracks with two types of fluids (brine and CO$_2$ in this case) will result in a change of the effective fluid bulk modulus, viscosity and density (Chapman and Liu 2006 and David et al., 2008). The resulting attenuation is sensitive to the changes in the effective fluid bulk modulus as well as the fluid viscosity (Chapman and Liu, 2006; Maultzsch et al., 2007). For partial saturation conditions with homogeneous mixing of brine and CO$_2$, the effective fluid bulk modulus $K_{eff}$ could be computed using Wood’s formula as (Mavko et al., 2009, pp 282):

$$\frac{1 - S_w}{K_{eff}} = \frac{S_w}{K_w} + \frac{1 - S_w}{K_c}$$

(11)

where $K_w$ is the bulk modulus of brine, $K_c$ is the bulk modulus of CO$_2$ and $S_w$ is the percentage of brine saturation. Wood’s formula is valid for the low frequency limit, where there is sufficient time for fluid pressure gradients to relax and equilibrate to a constant pressure. The equilibrium is reached due to the fact that only grain scale is considered in the model where the relaxation times are much smaller than those expected if fractures were to be present. The pressure gradient generated by a seismic wave propagating in a medium leads
to exchange of fluid between the microcracks and the surrounding pore space, resulting in attenuation. This attenuation is sensitive to the fluid effective modulus in this case.

Firstly, we considered a pure isotropic model with zero porosity, no fluid saturation and no microcracks to provide a reference model and computed the synthetic data from the theoretical model using the ‘ANISEIS’ software which makes use of the reflectivity method (Taylor, 2001). Aniseis is a commercial software package for modelling seismic wave propagation in anisotropic media and is a far field approximation. We then introduced brine and CO\(_2\) (in the supercritical state) into the third layer at 90 % and 10 % respectively for crack densities of 0.01, 0.02 and 0.03 to examine the attenuation effects caused by CO\(_2\) on the P-waves generated. We finally examined the sensitivity of the induced attenuation to CO\(_2\) saturation by considering the case in which the third layer is saturated with brine and CO\(_2\) at different degrees of concentrations ranging from 0 to 100 %. A zero percent (0 %) CO\(_2\) saturation implies that the material is fully saturated with brine while 100 % CO\(_2\) saturation means that the material is fully saturated with CO\(_2\). The effective fluid bulk moduli of the fluid saturation were computed using Equation 11. At lower brine saturation, the effective fluid bulk modulus is dominated by the bulk modulus of CO\(_2\). The reverse is the case at higher brine saturation.

A Ricker wavelet with a centre frequency of 25 Hz and a start time of 100 ms was used as the source wavelet. The resulting wavefield was calculated at some 21 positions at the surface of layer 1, at a regular spacing of 100 m, and a minimum source - receiver spacing of 100 m was maintained. The synthetic data were recorded with a time step of 1 ms and a total sampling time of 3 s. Sample synthetic gathers are shown in Figure 2 with the reflections from the top and bottom of the third layer highlighted by the red and green arrows respectively. These reflections are proportional to the time derivative of the source Ricker wavelet. The very low amplitude hyperbolic event that arrives after the reflection from the bottom of the third layer
is the P-S converted wave which was not analysed in this work. There is no significant difference between Figures 2a and b as a result of the auto scaling of the software used in generating the plots. The software scales the amplitude based on the maximum amplitude on the first trace in the gather. Our modelling studies examine only the fluid bulk modulus effect and the effect of viscosity is not considered at this stage.

**Figure 1**: Experimental set-up. The model comprises four horizontal layers. $E_S$ is the source placed at a distance of 100 m from the first receiver R. The receiver spacing is 100 m.

<table>
<thead>
<tr>
<th>Layer parameters</th>
<th>saturated layer parameters (layer 3)</th>
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**Table 1**: Theoretical model parameters
Figure 2: Sample synthetic data (a) pure isotropic model with no cracks and no fluid saturation (b) model with crack density 0.01 and CO$_2$ saturation 10% in the third layer. The red and green arrows indicate the top and bottom of the third layer reflections respectively. The trace spacing is 100 m

3.0 Attenuation measurements

Measurement of seismic attenuation from seismic data is usually made through the estimation of the inverse of the seismic quality factor, Q. In practice, the use of the spectral ratio method
is very common to estimate $Q$ from seismic data partly as a result of its ease of use and stability (e.g. Hauge 1981; Pujol and Smithson 1991; Dasgupta and Clark 1998), and also because it removes the effects of geometric spreading in an uncomplicated manner. Consequently, any measurement of attenuation can be attributed exclusively to internal energy dissipation or ‘intrinsic attenuation’, at least for relatively uniform media where multiple scattering can be neglected.

In this paper, we used the spectral ratio method to estimate the seismic quality factor from the synthetic data. In each gather, the first trace from the top model reflection at an offset of 0 m was used as the reference trace for comparison of the spectral ratios. For each trace in the gather and for the top and bottom reflections from the third layer (fluid-saturated layer), we formed the spectral ratios in accordance with Equation 12 and performed a simple least-squares regression of the Log of the Power Spectral Ratios (LPSR) against frequency. We used a constant FFT time window of 180 ms to compute the power spectra.

$$\ln \frac{A_2}{A_1}^2 = \ln \frac{P_2}{P_1} = 2 \ln (R_e G) - \frac{2 \pi f}{Q} (t_2 - t_1)$$

f is frequency, $R_e$ is the reflectivity term, $G$ is the geometrical spreading factor, $A_1$ is the spectral amplitude of the reference trace i.e. for the case of zero crack density, $A_2$ is the spectral amplitude of the target reflection (top or bottom of fractured-layer) while $P_1$ and $P_2$ are the respective spectral powers (square of amplitudes), $t_1$ and $t_2$ are the corresponding travel times, $Q$ is the seismic quality factor down to the reflector.

Sample power spectra are shown in Figure 3 for selected percentages of CO$_2$ saturation and crack density of 0.02 at a fixed offset of 900 m. There is a significant drop in the power spectral density for the bottom layer reflection with decreasing percentage of CO$_2$ saturation from 100% to a minimum at 10% saturation. However, the power density is a maximum at
0% CO₂ saturation when the material is 100% saturated with brine. These observations are indicative of the sensitivity of the wave attenuation to the varying degrees of CO₂ saturation. The far field pulse shape is proportional to the time derivative of the input Ricker wavelet. Lange and Almoghrabi (1988) and Chung and Lawton (1995) have shown that given a Ricker wavelet with centre frequency \( f_0 \), the peak frequency \( f_p \) of the derivative of the wavelet is given as:

\[
\frac{f_p}{f_0} = \sqrt{\frac{3}{2}}
\]

Equation 13 explains why the peak frequency of the far field response is greater than that of the input Ricker wavelet. Samples plots of the Log Power Spectral Ratios (LPSR) against frequency are shown in Figure 4 for the pure isotropic model with no fluid saturation and crack density and for 10% CO₂ saturation and crack density of 0.01 respectively. For the top layer reflection (red colour), the plots are approximately horizontal, indicating that there is no attenuation in the overlying layer (layer 2) as expected since it is isotropic. For the pure isotropic model with no fluid saturation (Figure 4a), the plot for the bottom reflection (blue colour) is also horizontal indicating no attenuation in the model. However, this is not the same for the fluid saturated case (Figure 4b). The plot for the bottom layer is not horizontal, indicating that attenuation is induced by the saturated CO₂. Figure 5 shows sample plots of the Log Power Spectral Ratios (LPSR) against frequency for the third layer for the three values of crack densities considered at 10% CO₂ saturation (Figure 5a) and various degrees of CO₂ saturation at crack density of 0.02 (Figure 5b) at 1100m offset. For the top layer reflection (blue colour), the plots are horizontal, indicating that there is no attenuation in the overlying layer. However, for the three crack densities, the plot for the bottom layer has varying slopes indicating varying magnitudes of attenuation respectively with crack density of 0.03 having the highest magnitude. Also, the plots for the bottom layer reflections for the
various degrees of saturation considered have varying slopes with 10\% saturation having the highest slope, implying varying attenuation magnitudes in the layer with highest magnitude at 10\% saturation. All the plots however are approximately linear between the frequency bandwidth of 20 - 90 Hz. This frequency bandwidth was used for all the traces analysed. Sample least-squares regression plots of the LPSR against frequency for the chosen bandwidth are shown in Figure 6 for the top (blue colour) and bottom (red colour) reflections from the third layer at selected percentages of CO$_2$ saturation and a fixed offset of 1100 m respectively with their corresponding coefficient of determination ($R^2$) values. The plots show good fit of the spectral ratios, indicating a linear relationship as predicted by Equation (12) even though attenuation is frequency dependent in the model (Equation 10). The plot for 0 \% CO$_2$ saturation has a slope which is less than that for 100 \% CO$_2$ saturation, indicating that CO$_2$ causes more attenuation than brine.

We then computed the Q value down to the reflector for a given offset from the slope $p$ of the least-squares regression given by:

$$p = \frac{-2\pi(t_2-t_1)}{Q}$$

(14)

This model assumes Q is frequency-independent. While this is not the case for the model used to construct the synthetic medium, it provides a good approximation to the synthetic data within the restricted bandwidth used in the regression fit. With the pair of Q values computed for the top and bottom of the third layer, we used the layer-stripping method of Dasgupta and Clark (1998) to compute the interval Q$_i$ value in the layer using the equation:

$$Q_i = \frac{[t_2-t_1]}{t_2/Q_2-t_1/Q_1}$$

(15)
where $Q_1$ and $Q_2$ are the seismic quality factors down to top and bottom of the third layer respectively. The entire procedure was repeated for all the traces in the gather following the hyperbolic travel path and the average interval $Q$ in the third layer was computed from the mean of all the computed interval $Q_i$ values in the layer.

**Figure 3:** Power spectra at 900 m offset for the fluid-saturated layer reflections (a) top layer: 0.02 crack density (b) bottom layer: 0.02 crack density. $S$ is the degree of saturation of CO$_2$. The saturation of brine is $(100 - S)$ %.

**Figure 4:** Samples plots of the Log Power Spectral Ratios (LPSR) against frequency at a fixed offset of 1100 m for the third layer (a) zero porosity, no fluid saturation and no microcracks or fractures (b) 10% CO$_2$ saturation and crack density of 0.01. The red and blue lines indicate the top and bottom layer reflections respectively.
Figure 5: Samples plots of the Log Power Spectral Ratios (LPSR) against frequency at a fixed offset of 1100 m for the third layer (a) 10 % CO₂ saturation at different crack densities (cd) (b) crack density of 0.02 and different percentage of CO₂ saturation (s). TLR is top layer reflection while BLR is bottom layer reflection.

Figure 6: Sample least-squares regression plots for the third layer at a fixed offset of 1100m. The blue colour indicates the top layer reflection while the red colour indicates the bottom layer reflection. S is the degree of saturation of CO₂. The saturation of brine is (100 - S) %.

4.0 Results and analysis

The results of our study demonstrate a strong sensitivity of attenuation to CO₂ saturation. For the pure isotropic model (zero porosity, no microcracks and no fluid saturation), there is no attenuation in the model as expected (pink colour in Figure 7). However, the presence of CO₂
in the model causes attenuation. The induced attenuation depends on the degree of saturation. Higher Q values (low attenuation) are obtained in the fluid-saturated layer at 0% CO\textsubscript{2} saturation and lower Q values (high attenuation) at 100% CO\textsubscript{2} saturation for the three crack densities considered (Figure 7). The Q values are observed to decrease gradually with decreasing percentages of CO\textsubscript{2} saturation from 100% to 10% for a given crack density, implying more attenuation with decreasing percentages of saturation. The Q values are also observed to decrease systematically both with increasing crack density and offset (Figure 7). This implies that the induced P-wave attenuation increases with crack density and offset.

Figure 8 shows the attenuation (1/Q) profile against percentages of CO\textsubscript{2} saturation. The attenuation exhibits a non-linear relationship with CO\textsubscript{2} saturation. For the ranges of saturations considered, the attenuation peaks at 10% saturation after which there is a gradual and steady decrease in attenuation with increasing percentage of saturation. This gradual decrease appears to be sharper for saturation ranges of around 10 – 50% than higher percentage saturations. A maximum attenuation of up to 0.13 occurs at 10% CO\textsubscript{2} saturation.

Although our study is limited only to the effects of crack density and CO\textsubscript{2} saturation, it is useful to show how these factors influence attenuation characteristics to gain a fuller understanding of these effects and gain more confidence in using P-wave attenuation in deciphering information on hydrocarbon fluid properties.
**Figure 7**: Q profile against CO$_2$ saturation for different degree of saturations and crack densities. Q decreases systemically with saturation and crack density and is minimum around 10% saturation.

**Figure 8**: 1/Q profile against CO$_2$ saturation for different crack densities. No attenuation occurs in the pure isotropic case with no cracks and no fluid saturation (pink colour). The induced attenuation is a maximum at 10% CO$_2$ saturation.
5.0 Discussion and conclusion

Seismic attenuation depends not only on the physical state of the rocks, but also on the nature of the fluid saturation in the pores of the rock. Based on the mean-field poro-elastic model of Chapman et al (2002 and 2003), we have investigated the effects of two types of fluid saturation (brine and CO₂ in the supercritical state) on P-wave attenuation, with particular interest in the effects of CO₂ using the CO₂ properties at the Sleipner gas field in the North Sea. Our results demonstrate the sensitivity of P-wave attenuation to the presence of CO₂.

The induced attenuation is influenced by the effective fluid bulk modulus which in turn is dependent on the percentages of saturation of the two fluids (CO₂ and brine). The attenuation is very sensitive to the percentage of CO₂ saturation and is higher for 100% CO₂ saturation than for 0% saturation, implying that the CO₂ causes more attenuation than brine. This could possibly be attributed to the fact that the properties of CO₂ in the supercritical phase where it behaves as a liquid were used in the modelling. Another factor that affects the magnitude of the induced attenuation is the crack density. The attenuation increases with increasing crack density as well as with offset. The attenuation occurs as a result of the relaxation of the fluid-pressure gradients generated by the propagation of seismic waves between the cracks and the surrounding pore space in the rock. The fluid mobility in this case is assumed to be the effective mobility of the two fluids and viscosity effects are not taken into consideration. The results show that the P-wave attenuation is even more sensitive to CO₂ saturation than velocity, most especially at higher concentrations when compared to the results of the study of David et al (2008). The attenuation results are also consistent with the results of Rossi et al (2011) who demonstrated the sensitivity of attenuation to CO₂ saturation in real field data example from the Sleipner Field. Thus, our findings further demonstrate the sensitivity of attenuation to CO₂ saturation, providing a fuller understanding into attenuation characteristics.
in fluid saturated rocks and especially validating the practical utility of using attenuation characteristics as an additional diagnostic in the characterisation of rock formations for a variety of applications, including hydrocarbon exploration and production, subsurface storage of CO$_2$ or geothermal energy extraction.

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**References**


Highlights

Used poro-elastic model to examine effect of CO₂ on P-wave attenuation

P-wave attenuation is sensitive to CO₂ saturation

Attenuation increases with decreasing percentage of CO₂ saturation

P-wave attenuation is sensitive to crack density and offset

CO₂ causes more attenuation than brine