XML data exchange

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XML Data Exchange: Consistency and Query Answering

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Data exchange is the problem of finding an instance of a target schema, given an instance of a source schema and a specification of the relationship between the source and the target. Theoretical foundations of data exchange have recently been investigated for relational data.

In this paper, we start looking into the basic properties of XML data exchange, that is, restructuring of XML documents that conform to a source DTD under a target DTD, and answering queries written over the target schema. We define XML data exchange settings in which source-to-target dependencies refer to the hierarchical structure of the data. Combining DTDs and dependencies makes some XML data exchange settings inconsistent. We investigate the consistency problem and determine its exact complexity.

We then move to query answering, and prove a dichotomy theorem that classifies data exchange settings into those over which query answering is tractable, and those over which it is coNP-complete, depending on classes of regular expressions used in DTDs. Furthermore, for all tractable cases we give polynomial-time algorithms that compute target XML documents over which queries can be answered.

Categories and Subject Descriptors: []:
General Terms:
Additional Key Words and Phrases:

1. INTRODUCTION

Data exchange is the problem of finding an instance of a target schema, given an instance of a source schema and a specification of the relationship between the source and the target. Such a target instance should correctly represent information from the source instance under the constraints imposed by the target schema, and should allow one to evaluate queries on the target instance in a way that is semantically consistent with the source data.

Data exchange is an old problem [Shu et al. 1977] that re-emerged as an active research topic recently due to the increased need for exchange of data in various formats, typically in e-business applications [Amer-Yahia and Kotidis 2004]. A system Clio for data exchange was built [Miller et al. 2001; Popa et al. 2002] and...
partly incorporated into the latest release of IBM’s db2 product. At about the same time, papers [Fagin et al. 2003; Fagin et al. 2003] by Fagin, Kolaitis, Miller, and Popa laid the theoretical foundation of exchange of relational data, and several followup papers studied various issues in data exchange such as schema mapping composition [Fagin et al. 2005] and query rewriting [Arenas et al. 2004; Yu and Popa 2004]. And even though practical systems such as Clio handle non-relational data (in particular, nested relations [Popa et al. 2002]), all theoretical investigation so far has concentrated on the relational case.

Our goal is to start the investigation of basic theoretical issues of data exchange for XML documents.

Example 1.1. We illustrate XML data exchange by the following example. Suppose we have the source document shown in Figure 1 (b) conforming to the DTD shown in Figure 1 (a). This DTD says that the document consists of several book elements, each having a title attribute and several author subelements; each author has attributes name and affiliation.

Suppose we want to restructure this document under the target schema shown in Figure 2 (a). This DTD says that a document has several writer elements, each having a name attribute, and several work subelements with attributes title and year. Intuitively, a restructured document should look like the XML document shown in Figure 2 (b). Note that the original document provides no data about publication year, and hence we have to invent new values for the document structured under the target schema. In data exchange terminology, these are nulls, denoted here by
$\perp_1$ and $\perp_2$. The new document forces two of them to be the same, even though their values are not known.

Even in the relational case there could be different target databases that satisfy all the constraints of a data exchange setting [Fagin et al. 2005]. So if we are given source document shown in Figure 1 (b) and a query over the new DTD, shown in Figure 2 (a), how can we answer it? If our query is, for example, *Who is the writer of the work named “Computational Complexity”?*, the answer is Papadimitriou regardless of a particular document that was created for the target DTD. Notice that even though the answer would be the same in every correctly constructed document that conforms to the new DTD, we can deduce this just by looking at a single document shown above. As another example, consider a query *What are the works written in 1994?*. This query cannot be answered with certainty in this scenario.

Our main goals here are the following:

—We propose a formalism for XML data exchange settings, and investigate its basic properties, and
—We study the problem of query answering in XML data exchange contexts, and analyze its complexity, and develop query evaluation algorithms.

Before we describe the main contributions of the paper, we recall briefly the setting of relational data exchange and query answering [Fagin et al. 2005; Fagin et al. 2005]. A relational data exchange setting is a triple $(S, T, \Sigma_{ST})$, where $S$ is a source schema, $T$ is a target schema, and $\Sigma_{ST}$ is a set of source-to-target dependencies, or STDs, that express the relationship between $S$ and $T$. Sometimes a set of constraints on the target schema is also added to the setting. Such a setting gives rise to the data exchange problem: given an instance $I$ over the source schema $S$, find an instance $J$ over the target schema $T$ such that $I$ together with $J$ satisfy the STDs in $\Sigma_{ST}$ (when target dependencies are used, $J$ must also satisfy them). Such an instance $J$ is called a solution for $I$. STDs are usually of the form

$$\psi_T(\bar{x}, \bar{z}) \leftarrow \varphi_S(\bar{x}, \bar{y}),$$

where $\varphi_S$ and $\psi_T$ are conjunctions of atomic formulae over $S$ and $T$, respectively. The pair $(I, J)$ satisfies this dependency if whenever $\varphi_S(\bar{a}, \bar{b})$ is true in $I$, for some tuple $\bar{c}$, $\psi_T(\bar{c}, \bar{y})$ is true in $J$.

In general, there may be many different solutions for a given source instance $I$, and under target constraints, there may be no solutions at all [Fagin et al. 2005; Fagin et al. 2005]. If one poses a query $Q$ over the target schema, and a source instance $I$ is known, the usual semantics in data exchange uses certain answers [Abiteboul et al. 1991; Imielinski and Lipski 1984]: we let certain$(Q, I)$ be the intersection of all $Q(J)$'s over all possible solutions $J$. A key problem in data exchange is to find a particular solution $J_0$ so that certain$(Q, I)$ can be obtained by evaluating some query (a rewriting of $Q$) over $J_0$. Some answers to this question were given in [Fagin et al. 2005; Fagin et al. 2005]: e.g., if $Q$ is a union of conjunctive queries, certain$(Q, I)$ can be computed by evaluating $Q$ over a special kind of solution called canonical that can be constructed in polynomial time. In general, however, work on query rewriting and incomplete information tells us that the complexity of finding
certain answers can be intractable [Abiteboul and Duschka 1998; Abiteboul et al. 1991].

Coming back to XML data exchange, we have to define XML data exchange settings. By analogy with the relational case, they should have source and target schemas, and source-to-target dependencies. We shall use DTDs as schemas, but it is not immediately clear what formalism to use for STDs, although intuitively they should correspond to conjunctive queries in some relational representation of XML. This intuition gives rise to a very natural question whether we can “reduce” XML data exchange problem to relational data exchange by using some relational representation of XML documents [Krishnamurthy et al. 2003] (for example, as trees with the child and next-sibling relations, as well as attribute values). The problem with this naive approach is that DTDs impose rather expressive constraints on target trees, that can talk about reachability as well as regular expressions. Therefore, their expressiveness is well beyond first-order logic, and yet results on relational data exchange have only considered limited first-order constraints on the target so far.

Thus, as is often the case with transferring results from relational databases to XML, we do have to reinvent most basic notions and prove new results. We now summarize our main results and outline the structure of the paper.

—Basic definitions (XML documents, DTDs) are given in Section 2.
—In Section 3, we define data exchange settings based on STDs which show how
patterns in the source tree translate into patterns in the target tree.

—In Section 4, we study the consistency problem of XML data exchange. We want to exclude inconsistent data exchange settings, in which target instances cannot be constructed. Our first result, Theorem 4.1, shows that the complexity of checking consistency of XML data exchange settings is EXPTIME-complete. In addition, we show that many reasonable restrictions remain computationally hard (complete for PSPACE or NP). However, for a practically relevant class, which subsumes non-relational data exchange settings handled by Clio, consistency can be checked in \( O(nm^2) \), where \( n \) is the size of the DTDs, and \( m \) is the size of the STDs (Theorem 4.5).

—In Section 5, we study the problem of query answering in XML data exchange. Since for a given source document \( T \) there could be many documents \( T' \) that satisfy all the STDs (solutions), we define query answers as those that are true in all solutions, i.e., certain answers. We look at queries that produce sets of tuples of values so that the notion of certain answers be well-defined.

Our first result (Theorem 5.5) is a coNP upper bound on the complexity of query answering. For XML data exchange, this bound is much harder to achieve than for relational data exchange.

Our next result delineates the boundary of intractability for query answering in data exchange. We show that if tree patterns over the target in STDs use one of three features – the descendant relation, the wildcard, or patterns that do not start at the root – then query answering could be coNP-hard even for very simple DTDs (Theorem 5.11). Thus, from that point on, we deal with target patterns that start at the root, use only the child relation, and do not use the wildcard.

—For such patterns, called fully-specified, in Section 6, we prove a dichotomy theorem which says that depending on the class of regular expressions used in DTDs, query answering is either tractable or coNP-complete (Theorem 6.2). Regular expressions in the class that guarantees tractability are called univocal. It is decidable if a regular expression is univocal (Proposition 6.10). For tractable cases, which subsume nonrelational data exchange handled by Clio [Popa et al. 2002], we provide algorithms for constructing target documents over which queries can be answered.

2. NOTATIONS

We view XML documents as node-labeled unranked trees. We assume countably infinite sets \( El \) of names of element types and \( Att \) of attribute names, as well as a domain \( Str \) of possible attribute values (normally considered to be strings). Attribute names are preceded by a “@” to distinguish them from element types. Given finite sets \( E \subset El \) and \( A \subset Att \), an XML tree \( T \) over \( (E,A) \) is a finite ordered directed tree \( (N, <_{\text{child}}, <_{\text{sib}}, \text{root}) \) where \( N \) is the set of nodes, \( <_{\text{child}} \) is the child relation, \( <_{\text{sib}} \) is the next-sibling relation (for each node \( v \) it orders its children \( v_1 <_{\text{sib}} \ldots <_{\text{sib}} v_m \)), and \( \text{root} \) is the root, together with

— a labeling function \( \lambda_T : N \rightarrow E \) (if \( \lambda_T(v) = \ell \), we say that \( \ell \) is the element type of \( v \));

— a partial function \( \rho_a : N \rightarrow Str \) for every @\( a \in A \) assigning some nodes of \( T \) values of attribute @\( a \).
A DTD (Document Type Definition) over \((E, A)\) is defined as a triple \((P, R, \underline{r})\) where

\[P\] is a function from \(E\) to regular expressions over \(E\) defined by the grammar

\[
e ::= \varepsilon \mid \ell, \ell \in E \mid e|e \mid ee \mid e^*,
\]

(\(\varepsilon\) is the empty string, and \(e\), \(e\) and \(e^*\) stand for the union, concatenation and the Kleene star);

\[R : E \rightarrow 2^A\] associates with each element type \(a\) (possibly empty) set of attribute names; and

\[\underline{r} \in E\] is the distinguished element type of the root, which cannot be used in regular expressions \(P(\ell)\) and cannot have any attributes \((R(\underline{r}) = \emptyset)\).

We also use the standard shorthands \(e^+\) for \(ee^*\) and \(e^+\) for \(e\), and we often write \(\ell \rightarrow e\) instead of \(P(\ell) = e\) as is common for DTDs. Furthermore, we do not consider \texttt{PCDATA} elements in XML documents since they can always be represented by attributes.

**Example 2.1.** For the source DTD shown in Figure 1 (a), \(E = \{db, book, author\}, A = \{@title, @name, @aff\}\), \(P\) is given by \(P(db) = book^*\) (that is, \(db \rightarrow book^*\)), \(P(book) = author^*\), \(P(author) = \varepsilon\); and \(R(db) = \emptyset\), \(R(book) = \{@title\}\), and \(R(author) = \{@name, @aff\}\). Furthermore, \(db\) is the element type of the root.

An XML tree \(T\) conforms to \(D = (P, R, \underline{r})\), denoted by \(T \models D\), if:

1. For every node \(v\) in \(T\) with children \(v_1, \ldots, v_m\) such that \(v_1 <_{\text{sib}} \ldots <_{\text{sib}} v_m\), if \(\lambda_T(v) = \ell\), then the string \(\lambda_T(v_1) \ldots \lambda_T(v_m)\) is in the language defined by the regular expression \(P(\ell)\);
2. For every node \(v\) in \(T\) with \(\lambda_T(v) = \ell\), \(\rho_{\ell a}(v)\) is defined iff \(@a \in R(\ell)\);
3. \(\lambda_T(\text{root}) = \underline{r}\).

We write \(\text{SAT}(D)\) for the set of XML trees \(T\) that conform to \(D\). It is a folklore result that checking whether \(\text{SAT}(D) \neq \emptyset\) can be done in linear time. We say that a DTD \(D\) is consistent if for every element type \(\ell\) in \(D\), there exists a tree \(T\) conforming to \(D\) and having a node of type \(\ell\). From now on, we assume that every DTD is consistent. This can be done without loss of generality due to the following easy observation.

**Lemma 2.2.** Given a DTD \(D\) with \(\text{SAT}(D) \neq \emptyset\), one can construct, in polynomial time, a consistent DTD \(D'\) such that \(\text{SAT}(D) = \text{SAT}(D')\).

**Proof.** Let \(A_D\) be an unranked nondeterministic finite tree automaton (UNFTA) that accepts \(\text{SAT}(D)\) (see Appendix A for some basic facts about ranked and unranked tree automata). We assume that each transition is represented by an NFA, that is, \(\delta(q, a)\) is an NFA over \(Q\). For each \(\ell\) in \(E\), let \(A_\ell\) be a constant-size UNFTA that tests if \(\ell\) occurs in a tree. Then \(L(A_D \times A_\ell)\) is nonempty iff there is a tree that conforms to \(D\) in which an \(\ell\)-node occurs. Furthermore, this test can be done in polynomial time in the size of \(A_D\) (and hence of \(D\)).

When this procedure is applied to all symbols \(\ell \in E\), we have them partitioned into two classes \(E = E_1 \cup E_2\), where element types from \(E_1\) appear in trees
SAT(D) and those from $E_2$ do not. Then, for each regular expression $r$, construct an expression $r'$ by replacing each $\ell \in E_2$ with the symbol $\emptyset$. Then define the following function $\rho$ on regular expressions expanded with the $\emptyset$ symbol: $\rho(\emptyset) = \emptyset$, $\rho(\varepsilon) = \varepsilon$, $\rho(\ell) = \ell$, and 

$$\rho(r_1 r_2) = \begin{cases} \rho(r_1) \rho(r_2) & \text{if } \rho(r_1) \neq \emptyset, \rho(r_2) \neq \emptyset \\ \emptyset & \text{otherwise;} \end{cases}$$

$$\rho(r^*) = \begin{cases} \rho(r)^* & \text{if } \rho(r) \neq \emptyset \\ \varepsilon & \text{otherwise;} \end{cases}$$

$$\rho(r_1 | r_2) = \begin{cases} \rho(r_1) | \rho(r_2) & \text{if } \rho(r_1) \neq \emptyset, \rho(r_2) \neq \emptyset \\ \rho(r_1) & \text{if } \rho(r_1) \neq \emptyset, \rho(r_2) = \emptyset \\ \rho(r_2) & \text{if } \rho(r_2) \neq \emptyset, \rho(r_1) = \emptyset \\ \emptyset & \text{if } \rho(r_1) = \rho(r_2) = \emptyset. \end{cases}$$

Now in $D$ we eliminate all symbols $\ell \in E_2$ and for each $\ell \in E_1$, replace $r = P(\ell)$ with $\rho(r')$. Let $D'$ be the resulting DTD. A straightforward induction shows that $\text{SAT}(D) = \text{SAT}(D')$, and the transformation was polynomial-time. Since $D'$ only uses symbols from $E_1$, for each element type that occurs in $D'$ there is a tree in $\text{SAT}(D')$ that uses it, proving consistency. 

3. XML DATA EXCHANGE SETTINGS

Recall [Fagin et al. 2005; Fagin et al. 2005] that a relational data exchange setting is a triple $(S, T, \Sigma_{ST})$, where $S$ and $T$ are source and target relational schemas, and $\Sigma_{ST}$ is a family of source-to-target dependencies, that is, expressions of the form

$$\psi_T(x, z) : \prec \psi_S(x, y),$$

where $\psi_T$ (resp., $\psi_S$) is a conjunction of atomic formulae over $T$ (resp., $S$). Instances $I$ of $S$ and $J$ of $T$ satisfy this dependency if whenever $\psi_S(a, b)$ holds in $I$, one can find a tuple $\bar{c}$ such that $\psi_T(\bar{a}, \bar{c})$ holds in $J$.

Now we need to extend this setting to XML data. Instead of source and target schemas $S$ and $T$, we shall use source and target DTDs $D_S$ and $D_T$. But what do we have in place of relational STDs? A natural idea is to extend relational source-to-target dependencies to XML trees considered as relational structures. But one needs to add the descendant relation and, worse yet, make the logical formalism two-sorted in order to deal with both nodes and values. This would make the formalism rather cumbersome. Instead, we present XML source-to-target dependencies in a formalism that is much closer to XML languages such as tree patterns and XPath [Amer-Yahia et al. 2002; Benedikt et al. 2003].

Essentially our STDs say that if a certain pattern occurs in the source, another pattern has to occur in the target. Thus, formulae used in STDs will be very similar to those used, for example, in [Amer-Yahia et al. 2002; Benedikt et al. 2003; Neven and Schwentick 2003; Deutsch and Tannen 2001; Wood 2003]. One difference though is that while XPath formulae select nodes from a tree, we also need to collect values of attributes that need to be assigned to nodes in the target trees. Thus, as in [Deutsch and Tannen 2001; Neven and Schwentick 2003], we shall use variables; in our case, they will range over possible attribute values.

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1In [Fagin et al. 2005; Fagin et al. 2005], STDs are written as FO sentences but here we prefer a rule-based formalism.
3.1 Tree-pattern formulae

The basic component of our language for source-to-target dependencies is attribute formulae. Assume that * is a wildcard symbol not included in $E \cup A$. Given sets $E \subset El$ of element types and $A \subset Att$ of attributes, attribute formulae over $(E, A)$ are defined by

$$\alpha := \ell \mid \ell(a_1 = x_1, \ldots, a_n = x_n),$$

where $\ell \in E \cup \{\cdot\}$, $a_1, \ldots, a_n \in A$ and $x_1, \ldots, x_n$ is a set of (non necessarily distinct) variables. In the second case, variables $x_1, \ldots, x_n$ are the free variables of $\alpha$. For example, the formula $\ell(\cdot)\ell(a = x, \cdot)\ell(b = y)$ has free variables $x$ and $y$, while the formula $\ell(\cdot)\ell(a = z, \cdot)\ell(b = z)$ has $z$ as its only free variable. An attribute formula is evaluated in a node of a tree, and values for free variables come from $Str$. If $T$ is an XML tree over $(E, A)$ and $v$ a node of $T$, then

$$\vdash T, v \models \varphi$$

iff

$$\vdash T, v \models \lambda \ell(v) = \alpha, \text{ for } \ell \in E;$$

$$\text{if } \sigma : \{x_1, \ldots, x_n\} \to \text{Str assigns to each variable } x_i \text{ a string value } (i \in \{1, n\}) \text{, then}$$

$$\vdash T, v \models \ell(\cdot)\ell(a_1 = \sigma(x_1), \ldots, a_n = \sigma(x_n)) \text{ iff } \vdash T, v \models \ell \text{ and } \rho_{a_j}(v) = \sigma(x_j), \text{ for every } j \in \{1, n\}. $$

Tree-pattern formulae over $(E, A)$ are defined by

$$\varphi := \alpha \mid \alpha[\varphi, \ldots, \varphi] \mid \text{ // } \varphi,$$

where $\alpha$ ranges over attribute formulae over $(E, A)$. The free variables of a tree-pattern formula $\varphi$ are the free variables in all the attribute formulae that occur in it. For example, the formula $db[\text{book[@title = x]}][\text{author[@name = y]}]$ has free variables $x$ and $y$. We write $\varphi(\bar{x})$ to indicate that free variables of $\varphi$ are $\bar{x}$. We evaluate tree-pattern formulae in an XML tree. Given a tree $T$, a tree-pattern formula $\varphi(\bar{x})$, and a tuple $\bar{s}$ from Str, $\varphi(\bar{s})$ is true in $T$ (written $T \models \varphi(\bar{s})$) if there is a witness node $v$ for $\varphi(\bar{s})$. Intuitively, the witness node is the node at which the pattern is satisfied, with $\bar{s}$ being the values of attributes. Formally, we define $v$ in $T$ to be a witness node for $\varphi(\bar{s})$ as follows:

$$\vdash v \text{ is a witness node for } \alpha(\bar{s}), \text{ where } \alpha \text{ is an attribute formula, } (T, v) \models \alpha(\bar{s}).$$

$$\vdash v \text{ is a witness node for } \alpha(\bar{s})[\varphi_1(\bar{s}_1), \ldots, \varphi_k(\bar{s}_k)] \text{ iff } (T, v) \models \alpha(\bar{s}) \text{ and there are } k \text{ (not necessarily distinct) children } v_1, \ldots, v_k \text{ of } v \text{ such that each } v_i \text{ is a witness node for } \varphi_i(\bar{s}_i), \text{ for every } i \leq k.$$

$$\vdash v \text{ is a witness node for } \text{ // } \varphi(\bar{s}) \text{ if there is a descendant } v' \text{ of } v \text{ in } T \text{ which is a witness node for } \varphi(\bar{s}).$$

For example, let $\psi(x, y)$ be the formula $\text{book[@title = x]}[\text{ author[@name = y]}]$, referring to the example from the introduction (see DTD in Figure 1 (a)). Then $\psi(s, s')$ is true iff $s$ is a title of a book and $s'$ is one of its authors, with the corresponding $\text{book}$ element being the witness.

Notice that every tree-pattern formula can be translated into a conjunctive query in a two-sorted logic over XML trees considered as structures in the language of $<_{\text{child}}$ and $<_{\text{child}}$ (descendant), being the second sort values of attributes. Thus, we are in principle in the same category of formulae for defining data exchange.
setting as in the relational case; however, we avoid the two-sorted formalism by using tree-pattern formulae.

3.2 Data exchange settings

We now define XML data exchange settings using tree-pattern formulae. Essentially, a data exchange setting consists of source and target DTDs, and source-to-target dependencies, which are rules of the form (1) in which both \( \varphi \) and \( \psi \) are tree-pattern formulae.

**Definition 3.1. (Source-to-target dependencies).** Given finite sets \( E_S, E_T \subset E \) of element types and \( A_S, A_T \subset Att \) of attributes, a source DTD \( D_S \) over \( (E_S, A_S) \) and a target DTD \( D_T \) over \( (E_T, A_T) \), a source-to-target dependency (STD) between \( D_S \) and \( D_T \) is an expression of the form:

\[
\psi_T(\bar{x}, \bar{z}) := \varphi_S(\bar{x}, \bar{y})
\]

where \( \varphi_S(\bar{x}, \bar{y}) \) and \( \psi_T(\bar{x}, \bar{z}) \) are tree-pattern formulae over \( (E_S, A_S) \) and \( (E_T, A_T) \), respectively, and tuples \( \bar{y} \) and \( \bar{z} \) have no variables in common.

**Definition 3.2. (Data Exchange Setting).** An XML data exchange setting is a triple \((D_S, D_T, \Sigma_{ST})\), where \( D_S \) is a source DTD, \( D_T \) is a target DTD, and \( \Sigma_{ST} \) is a set of STDs between \( D_S \) and \( D_T \).

**Definition 3.3. (Solutions).** Given a data exchange setting \((D_S, D_T, \Sigma_{ST})\) and an XML tree \( T \) conforming to \( D_S \), a tree \( T' \) conforming to \( D_T \) such that \( \langle T, T' \rangle \) satisfies all STDs in \( \Sigma_{ST} \) is called a solution for \( T \).

**Example 3.4.** Referring again to the data exchange scenario from the introduction (see Figures 1 and 2), the STD that specifies how to transform \( book/author \) pairs into \( writer/work \) pairs is given by \( \psi_T(x, y, z) := \varphi_S(x, y) \) where \( \varphi_S(x, y) \) and \( \psi_T(x, y, z) \) are

\[
\text{db}[\text{book}(\text{@title} = x)\text{[author}(\text{@name} = y)\text{)]]} \quad \text{and} \\
\text{bb}[\text{writer}(\text{@name} = y)\text{[work}(\text{@title} = x, \text{@year} = z)\text{)]},
\]

respectively. For example, we know that the source document from the introduction satisfies

\[
\varphi_S(\text{Combinatorial Optimization, Papadimitriou}).
\]

Thus, in a solution \( T' \) for \( T \), we would have a \textit{writer} child of the root with the \text{@name} attribute \text{Papadimitriou}, and a \textit{work} child with two attributes \text{@title} and \text{@year}. The value of \text{@title} is \text{Combinatorial Optimization}, but the source document provides no information about the value of the \text{@year} attribute. In a solution therefore one has to invent a null value (shown as \( \perp \) in the example) for this attribute. \( \square \)

As in other papers on data exchange [Fagin et al. 2005; Fagin et al. 2005], we assume that the domain \( \text{Str} \) of attributes is partitioned into two countably infinite
sets $\text{Const}$ and $\text{Var}$. The set $\text{Const}$ contains all values that may occur in source trees, and, following data exchange terminology, we call them constants. Elements of $\text{Var}$ are called nulls, and they are used to populate target trees.

4. CONSISTENT DATA EXCHANGE SETTINGS

It is known that even in the relational case some data exchange settings are inconsistent due to constraints on the target instance [Fagin et al. 2005; Fagin et al. 2005]. DTDs, being very close in expressiveness to monadic second-order logic [Vianu 2001], may impose a variety of restrictions on possible solutions, sometimes making data exchange settings inconsistent. For example, consider an STD $\sigma[\ell_1[\ell_2(@a = x)]] : \neg \sigma$. If the target DTD is $\tau \rightarrow \ell_1 \ell_2$, $\ell_1, \ell_2 \rightarrow \varepsilon$, then there is no source XML tree $T$ for which a solution exists. In other words, no matter what the source DTD is, the data exchange setting would be inconsistent.

In this section, we investigate consistency of XML data exchange settings. We impose an additional restriction on tree patterns over the source that all variables used in each tree pattern formula are distinct. The intuition behind this restriction is that we collect values of attributes that occur in patterns that only specify a tree structure, not statements about equality of attributes. For example, a tree pattern formula $\varphi = \ell(@a_1 = x, @a_2 = x)$ is satisfied in a node with attributes $@a_1$ and $@a_2$ that have the same value. Since our goal for source patterns is to collect values, we disallow formulae of this kind over the source, instead using formulae like $\varphi' = \ell(@a_1 = x_1, @a_2 = x_2)$, saying that the value of $@a_1$ should be recorded in $x_1$, and the value of $@a_2$ in $x_2$. Patterns like $\varphi$ are essentially a conjunction of $\varphi'$ and an equality statement $x_1 = x_2$, and we do not consider those over the source. We do, however, allow them over the target: while our goal is to collect values over the source, in populating target documents we can use values more than once. For example, $\varphi$ could be used as a target formula: $\ell(@a_1 = x, @a_2 = x) : \neg \ell'(@a = x)$ says that for each value $x$ of an attribute $@a$ of element type $\ell'$ in the source, we must have a node of type $\ell$ where both attributes $@a_1$ and $@a_2$ are assigned the same value $x$.

The proviso that variables in source tree-pattern formulae are distinct only applies in this section; we shall not need it when we deal with query answering.

We call a data exchange setting $(D_S, D_T, \Sigma_{ST})$ inconsistent if no tree $T \models D_S$ has a solution. Otherwise, the setting is consistent. Obviously one should only work with consistent settings. But how hard is it to test consistency? To answer this, we study the following problem:

<table>
<thead>
<tr>
<th>PROBLEM:</th>
<th>DATA-EXCHANGE-CONSISTENCY</th>
</tr>
</thead>
<tbody>
<tr>
<td>INPUT:</td>
<td>Data exchange setting $(D_S, D_T, \Sigma_{ST})$.</td>
</tr>
<tr>
<td>QUESTION:</td>
<td>Is $(D_S, D_T, \Sigma_{ST})$ consistent?</td>
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</table>

A particular case of this problem is satisfiability of tree-pattern formula which asks whether there exists a tree $T$ that conforms to a DTD $D$ and satisfies a tree pattern.

\[To avoid any potential confusion with the conference version of the paper caused by a slight notational difference, we should point out that in the conference version [Arenas and Libkin 2005], the distinct variables assumption was not spelled out as directly as here, and was enforced by using distinct variables in patterns.\]
formulas \( \psi \). Indeed, this happens iff the setting \((D_{\Sigma}, D, \{\psi : \underline{\ell}\})\) is consistent, where \(D_{\Sigma} \) has only one rule \( \underline{\ell} \rightarrow \varepsilon \). It is known that satisfiability of tree-patterns may be intractable [Lakshmanan et al. 2004] although precise complexity was not known. Results on XPath containment in the presence of DTDs [Neven and Schwentick 2003; Wood 2003] also suggest high complexity for data exchange consistency. We now determine its exact complexity.

**Theorem 4.1.** The problem **Data-Exchange-Consistency** is EXPTIME-complete.

**Proof.** For membership, we first show that it suffices to consider STDs in which all attribute formulae are of the form \( \psi \). Then, for each STD \( \psi : \varphi \) we construct an unranked tree automaton that accepts a tree whose root has two children iff whenever the subtree rooted at the left child satisfies \( \varphi \), then the subtree rooted at the right child satisfies \( \psi \). We show that the product of all these automata can be constructed in exponential time. Then we take the product of this automaton with an automaton defining the DTDs; the setting is consistent iff such an automaton accepts a tree. The latter can be done in polynomial time in the size of the automaton [Neven 2002].

More precisely, suppose we are given a data exchange setting \((D_S, D_T, \Sigma_{ST})\). For each attribute formula \( \alpha \), define a formula \( \alpha^o \) as follows:

- If \( \alpha = \ell \) with \( \ell \in E \cup \{\underline{\ell}\} \), then \( \alpha^o = \alpha \);
- If \( \alpha = \ell(\@a_1 = x_1, \ldots, \@a_n = x_n) \), then \( \alpha^o = \ell \).

For a tree formula \( \varphi \), we let \( \varphi^o \) denote a formula obtained from \( \varphi \) by replacing each attribute subformula \( \alpha \) with \( \alpha^o \). We define \( \Sigma_{ST}^{\varphi^o} \) as the result of replacing each \( \psi : \varphi \) in \( \Sigma_{ST} \) with \( \psi^o : \varphi^o \). Notice that formulae of the form \( \varphi^o \) do not have free variables.

**Claim 4.2.** A data exchange setting \((D_S, D_T, \Sigma_{ST})\) is consistent iff \((D_S, D_T, \Sigma_{ST}^{\varphi^o})\) is consistent.

**Proof.** One direction is immediate from the observation that \( T \models \varphi^o \) iff \( T \models \varphi(s) \) for some values \( s \). For the other direction, suppose \((D_S, D_T, \Sigma_{ST}^{\varphi^o})\) is consistent, with \( T' \models D_T \) being a solution for \( T \models D_S \). Fix a string \( s_0 \) and assign it as values of all attributes in \( T \) and \( T' \), resulting in trees \( T(s_0) \) and \( T'(s_0) \). Clearly, \( \langle T(s_0), T'(s_0) \rangle \) witness the consistency of \((D_S, D_T, \Sigma_{ST})\). This proves the claim. \(\square\)

We remark that the restriction on source tree-pattern formulae is essential here. Consider for example, a source DTD \( \underline{\ell} \rightarrow \ell_0, \ell_0 \rightarrow \ell_1, \ell_1 \rightarrow \varepsilon \), with \( \ell_i \)'s all having an attribute \( \@a \), a target DTD with just the root \( \underline{\ell} \) and an STD \( \underline{\ell}[b] : \underline{\ell}[\ell_0(\@a = x)] [\ell_1(\@a = x)] \). This setting is consistent: for example, a source tree with different values of \( \@a \) at \( \ell_0 \) and \( \ell_1 \) makes a witness, together with the only possible target. But \( \Sigma_{ST} \) is not consistent: it has a single STD \( \underline{\ell}[b] : \underline{\ell}[\ell_0[\ell_1]], \) and since every tree that conforms to the source DTD satisfies the pattern \( \underline{\ell}[\ell_0[\ell_1]] \), the resulting setting is inconsistent.

Since the transformation from \( \Sigma_{ST} \) to \( \Sigma_{ST}^{\varphi^o} \) is linear-time, we can assume without loss of generality that in our data exchange settings all attribute subformulae are of the form \( \ell \) with \( \ell \in E \cup \{\underline{\ell}\} \). To prove membership in EXPTIME, we need...
the following result. Recall that an UFTA(DFA) is a unranked deterministic tree automaton where all transitions are represented by deterministic tree automata (see Appendix A for some basic facts about ranked and unranked tree automata).

**Claim 4.3.** For every tree-pattern formula $\phi$ without free variables, one can compute in exponential time a deterministic UFTA(DFA) $A_\phi$ with a set $F$ of accepting states such that for every tree $T$ and a node $v$,

$$\text{run}_{A_\phi}(v) \in F \iff v \text{ is a witness for } \phi \text{ in } T.$$  

**Proof.** We construct $A_\phi$ inductively on the structure of $\phi$. If $\phi = \ell$, the automaton has one state which is accepting. If $\phi = \ell$, then it has an accepting state $q_\ell$ and a rejecting state $q_\ell$ and transitions $\delta(q_\ell, \ell) = \{q_\ell, q_\ell\}^*$, $\delta(q_\ell, \ell) = \emptyset$, $\delta(q_\ell, \ell') = \emptyset$ and $\delta(q_\ell, \ell') = \{q_\ell, q_\ell\}^*$ for every $\ell' \neq \ell$.

Now assume we have an automaton $A_{\psi} = (Q, \delta, F)$ for $\psi$. The set of states of $A_{\psi}^{\phi}$ will be $Q \times \{q_\ell^{/\phi}, q_\ell^{/\phi}, q_\ell^{/\phi}\}$. The set of accepting states will be $Q \times \{q_\ell^{/\phi}\}$.

Intuitively, each run of the new automaton simulates a run of $A_{\phi}$ with the extra component being:

- $q_\ell^{/\phi}$ until an accepting state of $A_{\phi}$ has been seen;
- $q_\ell^{/\phi}$ once the run of $A_{\phi}$ enters an accepting state, assuming that the last component was $q_\ell^{/\phi}$;
- $q_\ell^{/\phi}$ once the last component $q_\ell^{/\phi}$ has been seen.

It is straightforward to define this transition function; since it involves constructing products of given DFAs with a fixed automaton, it is done in polynomial time.

The last case is that of $\psi = \ell[\phi_1, \ldots, \phi_m]$. Assume that we have already constructed $A_{\phi_i} = A_{\phi_i} = (Q_i, \delta_i, F_i)$ for each $\phi_i$. The set of states of $A_{\phi}$ will be $Q = Q_1 \times \ldots \times Q_m \times \{q_\ell^{/\phi}, q_\ell^{/\phi}, q_\ell^{/\phi}\}$; the accepting states are those where the last component is $q_\ell^{/\phi}$. The transition function of $A_{\phi}$ is defined as follows. Let $A_m$ be a deterministic string automaton over the alphabet $Q$ which accepts strings $s$ such that for each $i \leq m$, there is a letter $(q_1, \ldots, q_m, q) \in s$ with $q_i \in F_i$. We make it deterministic so that we could use both $A_m$ and its complement. Then we simply let $\delta((q, q_\ell), \ell)$ be given by $A_m$, $\delta((q, q_\ell), \ell)$ be given by $A_m$’s complement, $\delta((q, q_\ell), \ell)$ be empty, and $\delta((q, q_\ell), \ell')$ be $Q^*$ for all $\ell' \neq \ell$.

Clearly $A_{\phi}$ enters a state $(q, q_\ell)$ iff $\psi$ holds in a given node. Thus, we have to show how to compute $A_m$. Notice that our inductive construction shows that the number of states of each $A_{\phi_i}$ is $3^{3^{|q_i|^\phi}}$ at most. The set of states of $A_m$ is $q_Y$ for $Y$ ranging over subsets of $\{1, \ldots, m\}$. Being in $q_Y$ means that so far $\phi_i$ with $i \in Y$, and only them, have been witnessed. If $A_m$ is in $q_Y$ and reads a letter $q$ in which precisely $q_j, j \in Y$, are in $F_j$’s, then it enters $q_{Y \cup Y'}$. Such a transition table would have size $O(2^m \times 3^m)$ and clearly can be computed in exponential time by simply enumerating appropriate subsets. This concludes the proof of the claim.  

Suppose we have an automaton $A_\phi$ for a tree-pattern formula. Then we can straightforwardly transform $A_\phi$ into a UFTA(DFA) $A(\phi)$ such that $T \models \phi$ iff

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3We shall often use notation $\| \cdot \|$ applied to trees, automata, formulae, etc., referring to their size in some reasonable encoding (the exact encoding, up to a linear factor, is irrelevant).
T ∈ L(A(ϕ)). This is done by letting A(ϕ) stay in an accepting state once an accepting state of Aϕ has been seen; this can be done in polynomial time. Thus, A(ϕ) can also be constructed in exponential time in the size of ϕ.

We now show how to solve DATA-EXCHANGE-CONSISTENCY in EXPTIME. Let ΣST be {ψi := ϕi | 1 ≤ i ≤ n}. Recall that these formulae are assumed not to have free variables. Let AS and AT be automata for source and target DTDs; those can be computed in polynomial time (see Appendix A). Then, for every subset I ⊆ {1, . . . , n} we do the following:

1. Check if the product automaton

      \[ A_S \times \prod_{i \in I} A(\psi_i) \times \prod_{j \notin I} \bar{A}(\varphi_j) \]

     accepts a tree. Here \( \bar{A} \) refers to the automaton that accepts the complement of \( L(A) \). This product automaton accepts a tree \( T \) iff \( T|_D = D_S \), \( T|_\psi = \psi_i \) for all \( i \in I \), and \( T|_\varphi \neq \varphi_j \) for \( j \notin I \).

2. Check if the product automaton

      \[ A_T \times \prod_{i \in I} A(\psi_i) \]

     accepts a tree. This product automaton accepts a tree \( T' \) iff \( T'|_D = D_T \) and \( T'|_\psi = \psi_i \) for all \( i \in I \).

Then the data exchange setting \( (D_S, D_T, \Sigma_{ST}) \) is consistent iff for some \( I \), both of the above automata accept a tree (the pair of trees accepted by them witnesses consistency). Hence, it remains to verify that steps 1 and 2 above can be carried out in exponential time. It is known that checking nonemptiness of a product \( A_1 \times \ldots \times A_k \) can be done in time \( O(\|A_1\| \times \ldots \times \|A_k\|) \) [Comon et al. 2007]. We saw that each \( A(\varphi) \) can be constructed in time \( O(c^{\|\varphi\|}) \) for some constant \( c \). Furthermore, \( \bar{A}(\varphi) \) can also be constructed in time \( O(c^{\|\varphi\|}) \) because \( A(\varphi) \) is deterministic and we simply have to reverse accepting and rejecting states. Thus, testing nonemptiness of the automaton in 1. can be done in time bounded by

\[
c_1 \cdot \|D_S\| \cdot \prod_{i \leq n} c^{\|\varphi_i\|} = O\left(2^{\|D_S\| + \|\Sigma_{ST}\|} \right)
\]

for some appropriately chosen constants \( c_1 \) and \( k \). Likewise, step 2. is also exponential in the size of \( D_T \) and \( \Sigma_{ST} \), thus proving membership in EXPTIME.

Next, we move to proving EXPTIME-hardness. For this, it suffice to reduce to the following problem: Given a nondeterministic finite tree automaton (NFTA) \( A \), is there a tree \( T \notin L(A) \) [Seidl 1990]. The idea of the encoding is that \( D_S \) codes both a tree \( T \) and a run. In the target document we copy rejecting states of \( A \). The STDs ensure that our coding is correct, and consistency would tell us that every run on \( T \) has to end in a rejecting state.

Let \( \Gamma = \{a_1, \ldots , a_k\} \) be the alphabet, and let \( A = (Q, q_0, \delta, F) \) where \( Q = \{q_0, \ldots , q_n\} \), and \( q_1, \ldots , q_m \) enumerate states in \( Q \setminus F \) (rejecting states). Source and target DTDs are constructed by using the set of element types
The target DTD $D_T$ is simply $r \rightarrow q_i; \ldots; q_m;$, with all the productions $q_i \rightarrow \epsilon$. The intuition is that $vr$-nodes of a tree that conforms to $D_S$ form a binary tree over which we run $A$; then $q_i$ for a given node will lead to a yes if there is a run in which this node is in $q_i$. This is ensured by STDs saying that if we have two nodes in which states $q_i$ and $q_j$ respectively have children yes, and their parent node has label $a$, and $q_k$ has no as its child while $q_k \in \delta(a,q_i,q_j)$, then we enforce $r[f]$ in the target which is inconsistent with the target DTD. That is, $\Sigma_{ST}$ has an STD:

$$r[f] := vr[q_i, no], label[a], left[vr[q_i,yes]], right[vr[q_j,yes]].$$

Similarly we handle the case of leaves so that the yes-states are those in which a leaf with a given label can be in a run of $A$, that is, for every $q_i \in \delta(a,q_0,q_0)$, $\Sigma_{ST}$ has an STD:

$$r[f] := vr[q_i, no], label[a], leaf.$$  

Finally, $\Sigma_{ST}$ has an STD

$$r[q_i] := r[vr[q_i,yes]].$$

that copies every “yes” state of the root into the target.

Assume that the setting is consistent, and we have a pair $(T, T')$ that witnesses its consistency. Let $T$ be the binary tree of nodes of type $vr$ extracted from $T$. For each node of $T$, the corresponding $q_i$ sibling that can be assigned to that node of $T$ in some run of $A$ will always have a yes child (otherwise an inconsistent $f$ child would have been forced in the target). Thus, the yes-states of the root include all the possible states in which $A$ is when it reaches the root, and since there is a solution for $T$, we conclude that they all are rejecting. Hence, every run on $T$ ends in a rejecting state, meaning that $T \not\in L(A)$.

Conversely, suppose we have a tree $T \not\in L(A)$. Then extend it to a tree $T$ that conforms to $D_S$ simply by annotating $T$ with all the runs of $A$ on $T$. But then such a $T$ has a solution in the data exchange setting: since $T \not\in L(A)$ every run coded in $T$ ends in a rejecting state and, thus, a target tree that has all the rejecting states as children of the root is a solution for $T$. Therefore, our data exchange setting, which was constructed in polynomial time from $A$, is consistent iff there is a tree not accepted by $A$. This completes the proof of the hardness case. □
The proof of Theorem 4.1 shows that Data-Exchange-Consistency remains EXPTIME-complete even if all formulae in all STDs have no free variables. In fact, this problem remains intractable under some other strong restrictions. Recall that a DTD $D$ is recursive if there is a cycle in the graph $G(D)$ defined as $\{(ℓ, ℓ') \mid ℓ'$ is mentioned in $P(ℓ)\}$, and non-recursive otherwise. We define path-pattern formulae as restrictions of tree-pattern formulae given by the grammar:

$$\varphi := \alpha \mid \alpha[\varphi] \mid //\varphi.$$ 

In other words, in such formulae one can talk only of one child or one descendant of a given node. They are closely related to the child-descendant fragment of XPath.

For each fixed DTD $D_T$, we consider the restriction Data-Exchange-Consistency($D_T$) of Data-Exchange-Consistency, whose input is $(D_S, \Sigma_{ST})$ with all formulae in $\Sigma_{ST}$ being path-pattern formulae. The question is whether $(D_S, D_T, \Sigma_{ST})$ is consistent. The next proposition shows that checking consistency remains intractable even with a fixed target DTD and restricted source DTDs (the proof of this proposition is given in Appendix B.1).

**Proposition 4.4.** Fix an arbitrary nonrecursive DTD $D_T$ that does not use the Kleene star. Then:

a) The problem Data-Exchange-Consistency($D_T$) for non-recursive source DTDs $D_S$ that do not use the Kleene star is PSPACE-complete.

b) The problem Data-Exchange-Consistency($D_T$) for non-recursive source DTDs $D_S$ in which all regular expressions are of the form $ℓ \to ℓ_1 | \ldots | ℓ_m$ or $ℓ \to ε$ is NP-complete.

We finally identify a class for which consistency is tractable. This class is relevant in practical applications of data exchange such as those addressed by Clio [Miller et al. 2001; Popa et al. 2002]. One extension of relational data exchange that is enabled by Clio is to nested relational schemas. Nested relations can naturally be represented by XML documents. In that case all the rules in DTDs are of the form $ℓ \to ℓ_1 \ldots ℓ_m^* \ldots ℓ_m^+ \ldots ™_{m+k}$, with all the $ℓ_i$’s distinct. We shall extend this, and consider nested-relational DTDs defined as non-recursive DTDs in which all rules are of the form

$$ℓ \to \vec{ℓ}_0 \ldots \vec{ℓ}_m,$$

where all $ℓ_i$’s are distinct, and each $\vec{ℓ}_i$ is one of the following: $ℓ_i$, or $ℓ_i^*$, or $ℓ_i^+$, or $ℓ_i^?$ = $ℓ_i | ε$. Such DTDs have also been looked at in the context of handling partial information in XML [Abiteboul et al. 2001].

**Theorem 4.5.** Data-Exchange-Consistency is solvable in polynomial time if both source and target DTDs are nested-relational. Specifically, it can be solved in time $O(nm^2)$, where $n$ is the size of the DTDs and $m$ is the size of the source-to-target dependencies.

**Proof.** As in the proofs of Theorem 4.1 and Proposition 4.4, we assume without loss of generality that the DTDs do not have attributes and all formulae in STDs have no free variables (see Claim 4.2). We consider two linear-time transformations of DTDs. Recall that $\vec{ℓ}$ is one of $ℓ$, or $ℓ^*$, or $ℓ^+$, or $ℓ^?$. For each nested-relational
DTD $D$, we define DTDS $D^\circ$ and $D^*$ in which each $\ell$ is replaced according to the following rules:

<table>
<thead>
<tr>
<th>In $D$ $\ell$ is</th>
<th>replace in $D^\circ$ by</th>
<th>replace in $D^*$ by</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\ell$</td>
<td>$\ell$</td>
<td>$\ell$</td>
</tr>
<tr>
<td>$\ell?\epsilon$</td>
<td>$\epsilon$</td>
<td>$\ell$</td>
</tr>
<tr>
<td>$\ell+$</td>
<td>$\ell$</td>
<td>$\ell$</td>
</tr>
<tr>
<td>$\ell^*$</td>
<td>$\epsilon$</td>
<td>$\ell$</td>
</tr>
</tbody>
</table>

We now need the following result.

**Claim 4.6.** If $D_S$ and $D_T$ are nested relational, then $(D_S, D_T, \Sigma_{ST})$ is consistent iff $(D_S^\circ, D_T^\circ, \Sigma_{ST})$ is consistent.

**Proof.** If $D$ is nested relational and $T \models D^\circ$ or $T \models D^*$, then $T \models D$. Hence, if $(D_S^\circ, D_T^\circ, \Sigma_{ST})$ is consistent, then $(D_S, D_T, \Sigma_{ST})$ is consistent.

For the opposite direction, assume that $(D_S, D_T, \Sigma_{ST})$ is consistent, and let $(T_1, T_2)$ witness it: that is, $T_1 \models D_S, T_2 \models D_T$, and $(T_1, T_2) \models \Sigma_{ST}$. Let $T \models D_S$ and let $T^\circ$ be the tree obtained from $T$ as follows: if $v$ is a node of $T$ labeled $\ell$, its parent is labeled $\ell'$, and $\ell$ occurs in $P(\ell')$ as $\ell? \epsilon$ or $\ell^*$ (one of two cases corresponding to replacement by $\epsilon$ in the definition of $D^*$), we delete the entire subtree rooted at $v$. This transformation results in a tree $T^\circ$ that conforms to $D_S^\circ$. Furthermore, if $T^\circ \models \varphi$, where $\varphi$ is a tree formula, then $T \models \varphi$ (tree formulae are monotone which can be shown by a straightforward inductive argument or by translation into conjunctive FO queries). This implies that $(T_1^\circ, T_2^\circ) \models \Sigma_{ST}$: if $\psi \vdash \varphi$ is an STD from $\Sigma_{ST}$ and $T_1^\circ \models \varphi$, then $T_1 \models \varphi$ and from $(T_1, T_2) \models \Sigma_{ST}$ we conclude $T_2 \models \psi$. Hence, we proved that $(D_S^\circ, D_T^\circ, \Sigma_{ST})$ is consistent.

Next, let $D_\ell$ denote the restriction of $D$ to element types reachable from $\ell$ in $G(D)$; in particular, $\ell$ becomes the root of $D_\ell$. (Recall that $G(D)$ is the graph of $D$: there is an edge from $\ell$ to $\ell'$ if $\ell'$ occurs in a string in the language given by $P(\ell)$.) We write $\text{cons}(D, \varphi)$ if there is tree $T \models D$ such that $T \models \varphi$. We now show that if $D$ is nested relational, then for every tree-pattern formula $\varphi$ and every $\ell$,

$$\text{cons}(D_\ell, \varphi) \iff \text{cons}(D_\ell^*, \varphi). \quad (3)$$

Notice that this implies that $(D_S^\circ, D_T^\circ, \Sigma_{ST})$ is consistent since $(D_S^\circ, D_T^\circ, \Sigma_{ST})$ is consistent and there is only one tree conforming to $D_T^\circ$.

We prove (3) by induction on $\ell$ starting with those that do not have outgoing edges in $G(D)$, and in each step using another inner induction on $\varphi$. Notice that since $T \models D^*$ implies $T \models D$, one has to verify only the implication $\text{cons}(D_\ell, \varphi) \Rightarrow \text{cons}(D_\ell^*, \varphi)$. Suppose $\ell$ does not have any outgoing edges in $G(D)$: that is, $D$ contains $\ell \rightarrow \epsilon$. In this case $D_\ell = D_\ell^*$. Now assume that we have an element type $\ell$ such that $D$ contains

$$\ell \rightarrow \ell_1^{l_1^1} \ldots \ell_{n_1}^{l_1^2} (\ell_2^{l_2^1})^{+} \ldots (\ell_{n_2}^{l_2})^{+} (\ell_3^{l_3^1})^{*} \ldots (\ell_{n_3}^{l_3})^{*} \ell_1^4 \ldots \ell_{n_4}^4,$$

such that the equivalence (3) holds for all the $\ell_i$'s. In the DTD $D^*$ we have

$$\ell \rightarrow \ell_1^{l_1^1} \ldots \ell_{n_1}^{l_1^2} \ell_1^{l_2^1} \ldots \ell_{n_2}^{l_2} \ell_1^{l_3^{l_3^1}} \ldots \ell_{n_3}^{l_3} \ell_1^{l_4} \ldots \ell_{n_4}^4,$$

The proof of the equivalence (3) is now by induction on the formulae. For formulae $\varphi$ and $\ell'$, where $\ell' \in E_1$, this is immediate. For formulae $\varphi/\ell'$ this follows from
the induction hypothesis and the observation that the regular expressions corresponding to \( \ell \) in \( D \) and \( D^* \) contain exactly the same element types. Now let \( \varphi \) be \( \ell'[\varphi_1, \ldots, \varphi_k] \). Assume that \( \ell' \neq \ell \) and \( \ell' \neq \_ \). Then \( \ell' \) must be one of \( \ell_j \)'s or a descendant of one of these nodes to ensure consistency and the statement is true by the induction hypothesis. The case of \( \ell' = \_ \) is simply a disjunction of the cases \( \ell' = \ell \) (proved below) and \( \ell' = \ell_j' \) or \( \ell' \) is a descendant of \( \ell_j' \). Thus, the remaining case to consider is \( \ell' = \ell \). Suppose \( T \) is a tree that witnesses \( \text{cons}(D_\ell, \varphi) \). Then the root \( v \) of \( T \) is of type \( \ell \), and it has children \( v_1, \ldots, v_k \) (not necessarily distinct) that witness \( \varphi_1, \ldots, \varphi_k \), respectively. Let \( v_m \) be labeled by \( \ell_m \) (where \( \ell_m \) is one of \( \ell_j', i \leq 4, j \leq n_i \)). Since we have \( \text{cons}(D_{\ell_m}, \varphi_m) \), by the induction hypothesis we have \( \text{cons}(D_{\ell_m}', \varphi_m) \). But \( D_{\ell_m}' \) has only one tree that conforms to it. Thus, if in \( T \) we replace each subtree rooted at a child of \( v \) of type \( \ell_m \) by the tree that conforms to \( D_{\ell_m}' \), we obtain a tree \( T_1 \) which satisfies \( \varphi \). But now subtrees of \( T_1 \) rooted at any two children of \( v \) that are labeled \( \ell_m \) are identical and hence we can keep only one of them for each label, and still satisfy \( \varphi \). This results in a tree \( T_2 \) that satisfies \( \varphi \). We note that \( T_2 \) does not necessarily conform to \( D_\ell^* \) since it could be the case that for some element type \( \ell_j' \), the root of \( T_2 \) does not have any children of type \( \ell_j' \). It is easy to solve this problem to generate from \( T_2 \) a tree \( T_3 \) conforming to \( D_\ell^* \) and satisfying \( \varphi \). Hence, we proved \( \text{cons}(D_{\ell_m}', \varphi) \).

This concludes the proof of (3) and thus proves the claim. \( \square \)

Using this lemma, we can prove the theorem as follows. First, construct \( D_S^\_ \) and \( D_T^\_ \) in linear time. In them, all the rules are of the form \( \ell \to \ell_1 \ldots \ell_k \), where all \( \ell_i \)'s are distinct, or \( \ell \to \varepsilon \), and hence each admits only one tree (since they are non-recursive).

If \( D \) is an arbitrary DTD of the above form, \( T \) is the only tree that conforms to it, and \( \varphi \) is a tree-pattern formula, then one can check \( T \models \varphi \) in time \( O(|D| \cdot |\varphi|^2) \).

This can be seen by induction on the structure of \( \varphi \). Specifically, as in the proof of Proposition 4.4, we enumerate all the subformulae \( \varphi' \) of \( \varphi \) and for each element type \( \ell \) that occurs in \( D \) we verify that the formula is true in the subtree whose root is that element.

That is, we keep, with each node, an array of \( m \) Boolean values, where \( m \) is the number of subformulae of \( \varphi \). For the basis step, formulae \( \ell \) and \( \_ \) are true in a node labeled \( \ell \). If we have a formula \( \_ \varphi' \), we search the graph of the DTD \( G(D) \) and for each node from which a node with \( \varphi' \) being true is reachable we put a 1 into the array position corresponding to \( \_ \varphi' \). This takes linear time in the size of \( D \).

For the formula \( \ell[\varphi_1, \ldots, \varphi_k] \), we compute, for each element type \( \ell' \), the Boolean or of the arrays associated with the element types \( \ell_1 \ldots \ell_s \) where \( \ell' \to \ell_1 \ldots \ell_s \) is the rule in the DTD for \( \ell' \). If the result has 0 in at least one position corresponding to \( \varphi_1, \ldots, \varphi_k \), we put 0 in the position corresponding to \( \varphi \) in the array for \( \ell' \). Otherwise, if the result has 1 in all positions corresponding to \( \varphi_1, \ldots, \varphi_k \), we put 1 in the position corresponding to \( \ell[\varphi_1, \ldots, \varphi_k] \) in the array associated with \( \ell' \) if \( \ell' = \ell \) or \( \ell = \_ \) and 0 otherwise. Thus, for each subformula of \( \varphi \) of the form \( \ell[\varphi_1, \ldots, \varphi_k] \), we have to take a disjunction of \( k \) arrays. Hence, the complexity is quadratic in the size of the formula.

Let \( T_S \) be the tree that conforms to \( D_S^\_ \) and \( T_T \) the tree that conforms to \( D_T^\_ \). To verify consistency of \( (D_S^\_, D_T^\_, \Sigma_{ST}) \), we check for each STD \( \psi \models \varphi \in \Sigma_{ST} \) if
$T_S \models \varphi$ and $T_T \models \psi$. This is done in time $O((\|D_S\| + \|D_T\|) \cdot (\|\varphi\|^2 + \|\psi\|^2))$. The setting is consistent iff there is no STD such that $T_S \models \varphi$ and $T_T \not\models \psi$. Hence consistency is checked in $O((\|D_S\| + \|D_T\|) \cdot \|\Sigma_{ST}\|^2)$.

5. QUERY ANSWERING

Our goal is to define the concept of query answering in the XML data exchange scenario. Since we need to compute certain answers (which are defined as intersections of query results over all solutions), we consider queries which return tuples of values as opposed to arbitrary trees.

We already know from results on relational data exchange that answering general FO queries over target instances is problematic [Arenas et al. 2004; Fagin et al. 2005], and most positive results have been proved for conjunctive or monotone queries [Fagin et al. 2005; Fagin et al. 2005]. Thus, for our query language, we shall use the closure of tree-pattern formulae under conjunction and existential quantification. This is similar to conjunctive queries over child and descendant as defined in [Gottlob et al. 2006], again with the main difference being the use of free variables to collect attribute values, as opposed to outputting nodes of trees. A query language $CTQ//\cup$ is defined by

$$Q := \varphi \mid Q \land Q \mid \exists x Q,$$

where $\varphi$ ranges over tree-pattern formulae. The semantics of $\land$ and $\exists$, as well as the definition of free variables, is standard. We note that as in the case of tree-pattern formulae, $CTQ//\cup$-formulae are evaluated in an XML tree.

Notation $CTQ//\cup$ stands for “conjunctive tree queries with descendant.” If we do not allow descendant in queries, we obtain a fragment denoted by $CTQ$. For example, consider a $CTQ$ query $\psi(x)$ given by $\exists y \text{book[@title = } x]\}[\text{author[@name = } y]$]. Then the source document from the introduction, shown in Figure 1 (b), satisfies $\psi(\text{Computational Complexity})$. We shall also consider unions of conjunctive queries. By $CTQ//\cup$ we denote the class of queries of the form $Q_1(\bar{x}) \lor \ldots \lor Q_m(\bar{x})$, where each $Q_i$ is a query from $CTQ//\cup$. By disallowing descendant in the $Q_i$’s we obtain a restriction denoted by $CTQ\cup$.

5.1 Certain answers

Assume that we are given a data exchange setting $(D_S, D_T, \Sigma_{ST})$, a source XML tree $T$ that conforms to $D_S$, and a $CTQ//\cup$ query $Q(\bar{x})$. What does it mean to answer $Q$? As in the case of relational data exchange [Fagin et al. 2005; Fagin et al. 2005], since there may be many possible solutions to the data exchange problem, we define the semantics of $Q$ in terms of certain answers:

$$\text{certain}(Q, T) = \bigcap_{T' \text{ is a solution for } T} Q(T').$$

Thus, a tuple $\bar{s}$ of strings is in $\text{certain}(Q, T)$ if $\bar{s} \in Q(T')$ for every solution $T'$ for $T$. If $Q$ is a Boolean query (a sentence), then $\text{certain}(Q, T) = \text{true}$ if and only if for every solution $T'$ for $T$, we have $T' \models Q$.

Let $(D_S, D_T, \Sigma_{ST})$ be a data exchange setting. The main problem we study is:
and the problem is to verify whether $\text{children}(Q,T)$ is a Boolean query ($m = 0$) then the input to the problem is an XML tree $T$ and the problem is to verify whether $\text{Const}(Q,T) = \text{true}$. Notice that as in the relational case, only tuples from $\text{Const}$ could belong to $\text{Const}(Q,T)$.

5.2 Unordered trees

Our query answering algorithms take advantage of temporarily “forgetting” about the sibling order. That is, we construct a target tree which does not conform to the target DTD but could be rearranged into one conforming to the DTD simply by imposing a correct sibling order. To capture this, we introduce a class of languages which are permutations of regular languages, and the notion of satisfaction of DTDs imposing a correct sibling order. To capture this, we introduce a class of languages which are permutations of regular languages, and the notion of satisfaction of DTDs by unordered trees.

Given a regular expression $r$ over an alphabet $\Gamma$, we let $L(r)$ stand for the language denoted by $r$. Then we define $\pi(r) \subseteq \Gamma^*$ as the set of all strings $w$ which are permutations of strings in $L(r)$. For example, if $r = (ab)^*$, then $\pi(r)$ has strings in which the number of $a$’s equals the number of $b$’s. Thus, $\pi(r)$ need not be regular; in fact it may not even be context-free because $\pi((abe)^*) \cap L(a^nb^n)$ is a permutation of some string in the language of $P(\ell)$.

An unordered XML tree is defined as a directed tree $(N, <\text{child}, \text{root})$ (that is, it excludes the sibling order $<_{\text{sub}}$). Given an unordered XML tree $T$ and a DTD $D$, we say that $T$ conforms to $D$, denoted by $T \models D$, if for every node $v$ in $T$ with children $v_1, \ldots, v_m$ and $\lambda_T(v) = \ell$, the string $\lambda_T(v_1) \ldots \lambda_T(v_m)$ is in $\pi(P(\ell))$, and items 2 and 3 of the definition of $T \models D$ are true. That is, $\lambda_T(v_1) \ldots \lambda_T(v_m)$ is a permutation of some string in the language of $P(\ell)$.

We say that an unordered XML tree $T'$ is a solution for an XML tree $T$ in a data exchange setting $(D_S, D_T, \Sigma_{ST})$ if $T' \models D_T$ and $(T, T')$ satisfies all the STDs from $\Sigma_{ST}$. As in the case of ordered trees, we define the semantics of $CTQ^{\downarrow, \uparrow}$-queries in terms of certain answers, that is, given an unordered XML tree $T \models D_S$, a $CTQ^{\downarrow, \uparrow}$-query $Q(\bar{x})$ over $D_T$ and a tuple $\bar{s}$ of strings, we say that $\bar{s} \in \text{certain}^un(Q,T)$ if and only if $\bar{s} \in Q(T')$ for every unordered solution $T'$ for $T$. The following proposition allows one to forget about the sibling ordering while computing certain answers and, in particular, it allows one to use unordered trees when proving lower bounds for this problem.

Proposition 5.1. Given an XML data exchange setting $(D_S, D_T, \Sigma_{ST})$, an XML tree $T \models D_S$ and a $CTQ^{\downarrow, \uparrow}$-query $Q(\bar{x})$, we have

$$\text{certain}(Q,T) = \text{certain}^un(Q,T).$$

Furthermore, tractable query answering algorithms in this paper will be constructing a certain unordered solution $T^*$ satisfying $\text{certain}^un(Q,T) = Q(T^*)$. This can be done without loss of generality since every unordered solution can be turned

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*The notion of satisfaction of a tree-pattern formula by an unordered tree is defined exactly as in the case of (ordered) XML trees.*
into an ordered solution, and this can be done in polynomial time, as the following result shows. Given an unordered tree $T$ and a sibling ordering $\prec_{\text{sib}}$, let $T^{\prec_{\text{sib}}}$ be the resulting ordered tree. Then:

**Proposition 5.2.** Suppose $T \equiv D$. Then one can compute, in polynomial time in the size of $T$, a local sibling ordering $\prec_{\text{sib}}$ on $T$ such that $T^{\prec_{\text{sib}}} \equiv D$.

Before proving this proposition, we need to establish complexity bounds for checking whether a string $w$ is in $\pi(r)$. Since the Parikh image of a regular language is a semilinear set, this reduces to integer linear programming, which is in NP in general, and in polynomial time if dimension is fixed [Lenstra 1983]. This gives us the following.

**Proposition 5.3.** The problem of checking whether $w$ is in $\pi(r)$ for a string $w$ and a regular expression $r$ is NP-complete. For each fixed $r$, checking whether $w$ is in $\pi(r)$ can be done in polynomial time.

**Proof.** Clearly checking if $w \in \pi(r)$ is in NP: we simply guess a permutation $w'$ of $w$ and verify if it is in $L(r)$. For NP-hardness, we reduce from a simplified version of Integer Linear Programming (ILP), which is known to be NP-complete [Garey and Johnson 1979]. The input consists of an $n \times m$ matrix $A$ and an $n$-vector $b$ of 0s and 1s; the question is whether there is an $m$-vector $x$ of 0s and 1s such that $Ax = b$.

As the string $w$, we choose $w = a_{k_1} \cdots a_{k_\ell}$, where $\{k_1, \ldots, k_\ell\}$ is the set of all indexes $j \in [1, n]$ for which $a_{j,i} = 1$. Then we define $r_A = r_{k_1}^1 \cdots r_{k_\ell}^\ast$. The instance of ILP has a solution if and only if $w \in \pi(r_A)$, proving NP-hardness.

Finally, we show that if $r$ is fixed, then checking whether $w$ is in $\pi(r)$ can be done in polynomial time. To prove this we need to use what is known as Pilling normal form [Kozen 2002]:

**Lemma 5.4.** For every regular expression $r$ over an alphabet $\Gamma$, there exist regular expressions $s_1, \ldots, s_n$ such that $\pi(r) = \pi(s_1 \cdots s_n)$ and each $s_i$ ($i \in [1, n]$) is of the form $w_0(w_1)^* \cdots (w_m)^*$, where each $w_j \in \Gamma^* (j \in [0, m])$.

If $r$ is fixed, then we can compute in polynomial time the regular expressions $s_1, \ldots, s_n$ mentioned in Lemma 5.4. Thus, if we show that it is possible to check in polynomial time whether $w \in \pi(s)$ with $s$ being of the form $w_0w_1^\ast \cdots w_m^\ast$, then we conclude that it is possible to check in polynomial time whether $w \in \pi(r)$. Let $\#_a(w)$ be the number of occurrences of symbol $a$ in a string $w$. Then $w \in$ Journal of the ACM, Vol. V, No. N, Month 20YY.
\(\pi(w_0w_1^* \ldots w_k^*)\) if there exist nonnegative integers \(x_1, \ldots, x_k\) such that for every alphabet symbol \(a\):

\[
\#_a(w) = \#_a(w_0) + \sum_{i=1}^{k} x_i \cdot \#_a(w_i).
\]

Thus, to check \(w \in \pi(w_0w_1^* \ldots w_k^*)\) we need to solve an instance of ILP, but in this time the dimension \(k\) is fixed. But it is well-known that ILP is solvable in PTIME in fixed dimension [Lenstra 1983].

**Proof of Proposition 5.2.** Clearly it suffices to show that for each fixed regular expression \(r\), the following can be solved in polynomial time in the size of string \(w\): assuming that \(w \in \pi(r)\), find a permutation \(w'\) of \(w\) such that \(w' \in L(r)\).

Let \(\Gamma = \{\sigma_1, \ldots, \sigma_m\}\) be the alphabet of \(r\). Let \(A_r\) be an NFA for \(r\), with \(Q\) being its set of states. Let \(r_q\) be the regular expression such that \(L(r_q)\) consists of exactly the strings which are accepted by \(A_r\) in which \(q\) becomes the new initial state. It follows from Proposition 5.3 that there is a polynomial \(p\) such that for every string \(w'\) and every \(q \in Q\) one can test whether \(w'\) is in \(\pi(r_q)\) in time \(p(|w'|)\).

Let \(n\) be the length of \(w\). The algorithm works as follows. At each step \(i\) of the algorithm, we have a string \(w_i\) of length \(i\), a string \(w^i\) of length \(n - i\), and a state \(q_i\) of \(A\) such that

1. \(w_i w^i\) is a permutation of \(w\);
2. there is a run of \(\mathcal{A}\) on \(w_i\) that ends in \(q_i\), and
3. \(\mathcal{A}_{q_i}\) accepts a permutation of \(w^i\).

The algorithm starts with \(w_0 = \varepsilon\), \(w^0 = w\), and \(q_0\) being the initial state of \(\mathcal{A}\). Then \(\mathcal{A}_{q_0} = \mathcal{A}\) accepts a permutation of \(w\) by the assumption that \(w \in \pi(r)\). At the end, we have a permutation \(w_n\) of \(w\) and a run of \(\mathcal{A}\) on it that ends in a state \(q_n\) such that \(\mathcal{A}_{q_n}\) accepts \(\varepsilon\) that is, \(q_n\) is a final state of \(\mathcal{A}\). In other words, \(w_n\) is a permutation of \(w\) that belongs to \(L(r)\). Thus, an algorithm satisfying 1, 2, and 3 will correctly compute a permutation of \(w\).

At each step of the algorithm, we do the following. For each letter \(\sigma_j\) present in \(w^i\), we check if there is a state \(q\) such that \(q \in \delta(A(q_i, \sigma_j))\) and a string \(w^i_{\sigma_j}\) obtained from \(w^i\) by eliminating one occurrence of \(\sigma_j\) belongs to \(\pi(r_q)\). By assumption 3, for at least one state \(q\) this condition will be satisfied. We then take \(w_{i+1} = w_i \sigma_j, w^{i+1} = w^i_{\sigma_j}\), and \(q_{i+1} = q\). Conditions 1, 2, 3 are clearly satisfied. It remains to check the complexity. For each \(i\), we have to check whether \(w^i_{\sigma_j}\) is in \(\pi(r_q)\). This by the assumption can be done in time \(p(n)\). The number of such tests is at most \(|\Gamma| \times |Q|\) and hence does not depend on \(n\). Therefore the overall running time is \(O(np(n))\). This proves the proposition.

**5.3 First complexity results: upper bound and some hard cases**

Our goal is to determine the complexity of computing certain answers. A priori it is not even clear if the problem is decidable, but we can prove the following upper bound.
Theorem 5.5. If \( Q \) is a CTQ\(^{\cup,\cup} \)-query, then Certain-Answers\((Q)\) is in coNP.

Proof. Fix a data exchange setting \((D_S, D_T, \Sigma_{ST})\) and a query \( Q \). To prove that the complexity of finding certain answers is in coNP it suffices to show that there exists a polynomial \( p \) that depends only on the data exchange setting and on \( Q \) such that the following is true. If for a tree \( T \) and a tuple \( s \) of strings from Const it is the case that \( s \notin \text{certain}(Q,T) \), then there exists a solution \( T' \) for \( T \) such that \( s \notin Q(T') \) and the size of \( T' \) is at most \( p(\|T\|) \) where \( \|T\| \) is the size of \( T \). Indeed, then checking whether \( s \notin \text{certain}(Q,T) \) is in NP, and hence Certain-Answers\((Q)\) is in coNP. In fact, by Proposition 5.1, it suffices to show that there exists an unordered tree \( T' \) that weakly conforms to \( D_T \) and such that \( \langle T, T' \rangle \models \Sigma_{ST}, \|T'\| \leq p(\|T\|) \) and \( s \notin Q(T') \). We prove the existence of such a polynomial-size tree in two steps: we first show that all the paths in the tree are of polynomial size and then we reduce the size of a tree without long paths.

Now for an arbitrary tree \( T \), a node \( v \), a tree-pattern formula \( \varphi(x) \) and a tuple \( a \), we inductively define a set \( \text{witness}_v(T, \varphi, a) \) of witnesses to \( \varphi(a) \) starting at \( v \) as follows.

—If \( v \) does not witness \( T \models \varphi(a) \), then \( \text{witness}_v(T, \varphi, a) = \emptyset \).
—Otherwise:
   —if \( \varphi \) is an attribute formula, then \( \text{witness}_v(T, \varphi, a) = \{v\} \);
   —if \( \varphi = \psi \varphi' \) and \( v' \) is an arbitrarily chosen descendant of \( v \) such that \( v' \) witnesses \( \varphi' \), then \( \text{witness}_v(T, \varphi, a) = \{v, v', v''\} \cup \text{witness}_{v'}(T, \varphi', a) \), where \( v'' \) is the child of \( v \) lying between \( v \) and \( v' \);
   —if \( \varphi = \alpha[\varphi_1, \ldots, \varphi_k] \) with each \( \varphi_i \) being witnessed by a child \( v_i \) of \( v \), then
     \[ \text{witness}_v(T, \varphi, a) = \{v\} \cup \bigcup_{i=1}^{k} \text{witness}_{v_i}(T, \varphi_i, a). \]

Intuitively, we collect all the nodes at which \( \varphi \) and its subformulae are witnessed, and with each descendant subformula we also include the child on the way to that descendant. Clearly the cardinality of \( \text{witness}_v(T, \varphi, a) \) is linear in the size of \( \varphi \). We then define \( \text{witness}(T, \varphi, a) \) as \( \text{witness}_v(T, \varphi, a) \) for an arbitrarily chosen witness \( v \) for \( T \models \varphi(a) \) (and \( \emptyset \) if no witness exists). Note that the definition of \( \text{witness}(T, \varphi, a) \) is nondeterministic but it suffices to pick an arbitrary one.

Let \( T' \) be a solution to \( T \) in the data exchange setting \((D_S, D_T, \Sigma_{ST})\). For each STD \( \psi(x, z) : \varphi(x, y) \in \Sigma_{ST} \), and for each \( a, b \) such that \( T \models \varphi(a, b) \), we have a tuple \( \bar{c}_{\varphi(a, b)} \) such that \( \psi(a, \bar{c}_{\varphi(a, b)}) \) holds in \( T' \). We then define

\[ \text{witness}_{\Sigma_{ST},T}(T') = \bigcup_{\psi(x, z) : \varphi(x, y) \in \Sigma_{ST}} \bigcup_{a, b : T \models \varphi(a, b)} \text{witness}(T', \psi, a\bar{c}_{\varphi(a, b)}). \]

If \( \Sigma_{ST} \) and \( T \) are clear from the context we write just \( \text{witness}(T') \). This set collects all the witnesses to satisfaction of all the formulae that have to hold in the solution \( T' \) due to the source-to-target constraints. We finally define \( \text{witness}''(T') \) to contain \( \text{witness}(T') \) and all the greatest lower bounds for all the subsets of \( \text{witness}(T') \). Since \( T' \) is a tree, the size of \( \text{witness}''(T') \) is at most quadratic in the size of
witness($T'$). Furthermore, the size of witness($T'$) is polynomial in the size of $T$, and hence the size of witness*($T'$) is polynomial in the size of $T$.

Let $T$ and $T'$ be two XML trees, $V$ a subset of nodes of $T$. We call a map $h : T \rightarrow T'$ a $V$-preserving embedding if $h$ is one-to-one map that preserves labels and all attribute values of nodes, preserves the descendant relation, and, furthermore, preserves the child relation restricted to $V$. That is, if $v'$ is a child of $v$ in $T$ and $v, v' \in V$, then $h(v')$ is a child of $h(v)$ in $T'$.

From now on, when we say “solution”, we mean a weak solution, that is a tree $T'$ that weakly conforms to the target DTD and satisfies all STDs. The following claim is immediate from the definitions and will be used several times in the proof.

Claim 5.6. Suppose $T'$ is a solution for $T$. Assume that a tree $T''$ conforms to $D_T$ and has a subset $V$ of nodes and a $V$-preserving embedding $h : T'' \rightarrow T'$ such that $h(V) = \text{witness}^*(T')$. Then $T''$ is a solution for $T$.

Notice that Claim 5.6 holds because $V$ witnesses right-hand sides of all the STDs. In particular, $V = \text{witness}^*(T')$.

Suppose $\bar{s} \notin \text{certain}(Q, T)$ for a tuple $\bar{s}$ from $\text{Const}$. Then there is a solution $T_0$ such that $\bar{s} \notin Q(T_0)$. Our first lemma lets us restrict the length of paths in a solution.

Lemma 5.7. There exists a polynomial $p_0$ that depends on the data exchange setting ($D_S, D_T, \Sigma_{ST}$) and the query $Q$ such that, for every tree $T$ and a solution $T_0$ satisfying $\bar{s} \notin Q(T_0)$, one can construct another solution $T_1$ satisfying $\bar{s} \notin Q(T_1)$ in which all paths have length at most $p_0(\|T\|)$.

Proof. Since $Q(\bar{x})$ is a $CTQ$ query, it is a union of queries of the form $\exists y \bigwedge_i \psi_i(\bar{x}, y)$, with all the $\psi_i$’s being tree-pattern formulae. We let $\beta_1(\bar{x}, y), \ldots, \beta_m(\bar{x}, y)$ enumerate all the tree-pattern formulae and their subformulae that occur in $Q$. Let $m'$ be the number of element types used in the target DTD. We define $M$ to be $2^{m'} + 1$. Let $V_0 = \text{witness}^*_{\Sigma_{ST}}(T_0)$. Construct a tree $T_0'$ in which all nodes except those in $V_0$ are given new attribute values, which are fresh and distinct values from $\text{Var}$. Clearly $T_0'$ is still a solution because $V_0$ witnesses all the STDs. Also notice that $\bar{s} \notin Q(T_0')$. Indeed, otherwise we would have $T_0' \models \exists y \bigwedge_i \beta_i(\bar{s}, y)$ for some collection of $\beta_i$’s and thus $T_0' \models \bigwedge_i \beta_i(\bar{s}, c'_0)$ for some tuple $c'_0$. Then, if $c_0$ is a tuple obtained by changing, in $c'_0$, newly created attribute values in $T_0$ to those they replaced, we would have $T_0 \models \bigwedge_i \beta_i(\bar{s}, c_0)$, contradicting $\bar{s} \notin Q(T_0)$.

Now consider an arbitrary path $v_1 \ldots v_p$ of length $p \geq M + 5$ in $T_0'$ such that the only descendants of $v_1$ that belong to $V_0$ are also descendants of $v_p$. In other words, all nodes from $V_0$ in the subtree rooted at $v_1$ are descendants of the last node on the path, $v_p$. For each node $v_i$, let $B(v_i) \subseteq \{1, \ldots, m\}$ be the set of indexes $j$ such that $v_i$ has a child at which $\exists y \beta_j(\bar{s}, y)$ holds. Because of the bound on $M$, there exist two indexes $2 < i_1 < i_2 < p - 2$ such that:

\[
\lambda_{T_0'}(v_{i_1}) = \lambda_{T_0'}(v_{i_2}) \quad \text{and} \quad B(v_{i_1}) = B(v_{i_2}).
\]

Let $T_0''(v_{i_1} \leftarrow v_{i_2})$ be the tree that results from replacing the tree rooted at $v_{i_1}$ with the tree rooted at $v_{i_2}$. Because of our assumption on the path, we have that $V_0 = \text{witness}^*(T_0''(v_{i_1} \leftarrow v_{i_2}))$. Furthermore, $T_0''(v_{i_1} \leftarrow v_{i_2})$ still conforms to $D_T$. 

since $\lambda_T(v_1) = \lambda_T(v_2)$ and, hence, it is a solution for $T$. Finally, $s \notin Q(T_0(v_1 \leftarrow v_2))$. Indeed, if $v$ is a witness for some tree-pattern formula $\beta_i(s, y_0)$, $i \leq m$, in the tree $T_0(v_1 \leftarrow v_2)$, then $v$ would be a witness for $\beta_i(s, y_1)$ in $T_0$, where $y_1$ differs from $y_0$ only in positions corresponding to values from $\text{Var}$ that appear only once in $T_0$. A simple induction on formulae then shows that $s \in Q(T_0(v_1 \leftarrow v_2))$ would imply $s \notin Q(T_0).

Thus, every path $v_1 \ldots v_p$ in $T_0$ satisfying the conditions that $p \geq M + 5$ and the only descendants of $v_1$ that belong to $V_0$ are descendants of $v_p$ can be shortened in such a way that the resulting tree is still a solution and $s$ is not in the output of $Q$ on it. Applying this inductively, we obtain a tree in which every path of length $\geq M + 5$ has an intermediate node with a descendant in $V_0$ that is not a descendant of the last node on the path. Since $M$ does not depend on $T$, this shows that we can have a solution $T_1$ such that $s \notin Q(T_1)$ and all paths in $T_1$ are of length at most in $|V_0|$, and thus polynomial in $|T|$. This proves the lemma. □

Now we need the last two ingredients to complete the proof of membership in coNP. Recall that $\#_a(w)$ is the number of occurrences of symbol $a$ in a string $w$. Given strings $w_1$ and $w_2$, we say that $w_1 \preceq w_2$ if $\#_a(w_1) \leq \#_a(w_2)$, for all alphabet symbols $a$. Furthermore, given a regular expression $r$, we define $|r|$ as follows. If $r = \varepsilon$, then $|r| = 0$. If $r = a$, where $a$ is an element type, then $|r| = 1$. If either $r = r_1r_2$ or $r = r_1^*$, then $|r| = |r_1| + |r_2|$. Finally, if $r = r_1^*$, then $|r| = |r_1|.

Lemma 5.8. Let $r$ be a regular expression of the form $r_1 \ldots r_m$, where each $r_i$ $(i \in [1, m])$ is of the form $u_0(w_1)^* \ldots (w_n)^*$, being $w_j$ a string $(j \in [0, n])$, and let $p_r(x)$ be polynomial $|r| \cdot (x + 1)$. If $w_0 \preceq w$ and $w \in \pi(r)$, then there exists a string $w'$ such that $w_0 \preceq w' \preceq w$ and $|w'| \leq p_r(|w_0|).

Proof. Assume without loss of generality that $w \in \pi(r_1)$ and $r_1 = u_0u_1^* \ldots u_n^*$. Since $w \in \pi(r_1)$, there exist natural numbers $\ell_1, \ldots, \ell_n$ such that $w = u_0u_1^{\ell_1} \ldots u_n^{\ell_n}$. Define $q_i$ as min$\{\ell_i, |u_0|\}$, for every $i \in [1, n]$, and $w'$ as $u_0u_1^{q_1} \ldots u_n^{q_n}$. It is easy to see that $w_0 \preceq w' \preceq w$. Furthermore, $w' \in \pi(r_1)$ and $|w'| \leq |u_0| + \sum_{i=1}^{n} |u_i| \cdot |u_0| \leq |u_0| \cdot (|u_0| + 1) + \sum_{i=1}^{n} |u_i| \cdot (|u_0| + 1) \leq |r_1| \cdot (|u_0| + 1)$. This concludes the proof of the lemma. □

Since in this proof the target DTD $D_T$ is assumed to be fixed, in what follows we assume, by Lemma 5.4, that every regular expression in $D_T$ is of the form mentioned in the statement of Lemma 5.8.

Notice that in the absence of elements of $V_0 = \text{witness}_{\text{Str}, T}(T_0)$, the proof of Lemma 5.7 and Lemma 5.8 imply the following statement.

Lemma 5.9. Let $D$ be an arbitrary DTD, and $\beta_i(x, y), i \in I$, a collection of tree-pattern formulae. Then one can find a number $N$ that depends on $D$ and the collection $\{\beta_i\}$ such that for every tuple $\bar{s}$ from $\text{Str}$, if there is a tree $T$ such that $T \models D$ and $T \not\models \exists y\beta_i(\bar{s}', y)$ for all $i \in I$, then there is a tree $T'$ with this property such that the size of $T'$ is at most $N$.

Proof. Let $T$ be a tree such that $T \models D$ and $T \not\models \exists y\beta_i(\bar{s}', y)$ for all $i \in I$. If we just disregard points in the witness set in the proof of 5.7, then we obtain a tree $T''$ such that $T'' \models D$, $T'' \not\models \exists y\beta_i(\bar{s}', y)$ for all $i \in I$, and all paths in $T''$ are of length at most $N'$, where $N'$ is a constant that depends only on $D$ and the collection $\{\beta_i\}$. □

Then in $T''$ we look at every node $v$ to construct tree $T'$. Let $v_1, \ldots, v_p$ be the children of $v$, $w = \lambda_{T'}(v_1) \cdots \lambda_{T'}(v_p)$ and $w_0 = a_1 \cdots a_t$, where $\{a_1, \ldots, a_t\}$ is the set of alphabet symbols mentioned in $w$. By Lemma 5.8, we can assume, without loss of generality, that there is $t' \leq p\tau(t) = \|r\| \cdot (t + 1) \leq (\|r\| + 1)^2$, where $r$ is the regular expression corresponding to $\lambda_{T'}(v)$, such that

$$w_0 \preceq \lambda_{T''}(v_1) \cdots \lambda_{T''}(v_p) \in \pi(r).$$

Thus, if we remove subtrees rooted at $v_{p+1}, \ldots, v_p$, the resulting tree still conforms to $D$. Let $T'$ now denote the tree obtained by applying this procedure to all nodes in $T''$. It is easy to see that $T'$ conforms to $D$. Furthermore, by monotonicity of each formula $\beta_i$, we conclude that $T' \not\preceq \exists \gamma \beta_i(s', y)$ for all $i \in I$ (otherwise we would have $T'' \not\preceq \exists \gamma \beta_i(s', y)$).

Given that for each node $v$ in $T'$, the number of children of $v$ is at most $(\|r\| + 1)^2$, where $r$ is the regular expression in $D$ corresponding to $\lambda_{T'}(v)$, and that the length of each path in $T'$ is at most $N'$, we conclude that there exists a constant $N$ that depends only on $D$ and the collection $\{\beta_i\}$ such that the size of $T'$ is at most $N$. This concludes the proof of the lemma. \(\Box\)

We now prove the existence of a polynomial-size solution (in the size of $T$) that witnesses $T' \not\preceq Q(s)$. Suppose a solution $T_0$ is given in which $Q(s)$ does not hold. Then, by Lemma 5.7, we replace it by a solution $T_1$ in which all paths are of length at most $p_0(\|T\|)$ such that $s \not\in Q(T_1)$. Let $V_1 = \text{witness}^*(T_1)$. We know that the size of $V_1$ is polynomial in $\|T\|$. Next, by Lemma 5.9, we replace every subtree rooted at a node $v$ that does not contain an element of $V_1$ by a fixed-size subtree in such a way that for the resulting tree, say $T_2$, it is still the case that $s \not\in Q(T_2)$. This can be done simply by making sure that none of subformulae used in $Q$ becomes true in the new fixed-size tree. Finally, in $T_2$ we look at every node $v$ such that the subtree rooted at $v$ contains elements of $V_1$. Let $v_1, \ldots, v_p$ be the children of $v$ and assume, without loss of generality, that $v_1, \ldots, v_t, t \leq p$, are the only children of $v$ having as descendants nodes in $V_1$. Let $w_0 = \lambda_{T_2}(v_1) \cdots \lambda_{T_2}(v_t)\|$ and $w = \lambda_{T_2}(v_1) \cdots \lambda_{T_2}(v_p)$. By Lemma 5.8, we can assume, without loss of generality, that there is $t' \leq p\tau(t)$, where $r$ is the regular expression corresponding to $\lambda_{T_2}(v)$, such that

$$w_0 \preceq \lambda_{T_2}(v_1) \cdots \lambda_{T_2}(v_p) \in \pi(r).$$

Thus, if we remove subtrees rooted at $v_{p+1}, \ldots, v_p$, the resulting tree still conforms to $D_{T_2}$. Let $T_3$ now denote the tree obtained by applying this procedure to all nodes in $T_3$ that are in $V_1$ or have a descendant in $V_1$.

The set $V_1$ still belongs to $T_3$, and $T_3$ conforms to $D_{T_2}$, and thus it is a solution for $T$. Furthermore, by monotonicity of $Q$ we have $s \not\in Q(T_3)$ (otherwise we would have $s \in Q(T_2)$). Thus, it remains to calculate the size of $T_3$.

In $T_3$, the following holds: (1) every path is of length at most $p_0(\|T\|)$; (2) every node in $V_1$ or has a descendant in $V_1$ has at most $p_{T_2}(\|V_1\|)$ children, where $p_{T_2}$ is the maximum of $p_T$ given by Lemma 5.8 over all regular expressions $r$ used in $D_{T_2}$, and (3) every subtree rooted at a node that is not in $V_1$ and does not have a descendant in $V_1$ has size bounded by a fixed number $N$. Thus, the size of $T_3$ is bounded by

$$O(\|V_1\| \cdot p_0(\|T\|) \cdot p_{T_2}(\|V_1\|) \cdot N),$$

and hence is polynomial in \( \|T\| \) since so is the cardinality of \( V_1 = \mathrm{witness}_{\Sigma_{\text{ST}}}^T(T_3) \). Thus, we have a solution \( T_3 \) of polynomial size which witnesses \( s \notin \text{certain}(Q, T) \), which shows that \text{Certain-Answers} is in \text{coNP}. This concludes the proof of Theorem 5.5.

We would like to identify tractable cases of the \text{Certain-Answers} problem. We note that in a source-to-target dependency \( \psi_T(x, z) :\neg \varphi_S(x, y) \) is fully-specified if \( \psi_T \) is of the form \( \exists r[\varphi_1, \ldots, \varphi_k] \), where \( r \) is the type of the root and \( \varphi_i \)'s do not use descendant // and wildcard *.

For example, the following source-to-target dependency is fully-specified:

\[
\text{bib}[\text{writer}\{\text{name} = y\}][\text{work}\{\text{title} = x\}] :- \\
\text{book}\{\text{title} = x\}[\text{author}\{\text{name} = y\}].
\]

The definition of fully-specified STDs puts three restriction on target formulae: they are witnessed at the root, there is no descendant, and no wildcard. By relaxing those, we can get three cases of STDs, in which target formulae satisfy only two of the three restrictions. We denote them by STD\((\varepsilon//)\) (wildcard and descendant are forbidden), STD\((\varepsilon//)\) (formulae \(\exists r[\varphi_1, \ldots, \varphi_k] \) in which descendant is forbidden), and STD\((\varepsilon//)\) (formulae \(\exists r[\varphi_1, \ldots, \varphi_k] \) in which wildcard is forbidden).

We call a regular expression \( r \) simple if either \( r = \varepsilon \) or \( r = (a_1|a_2|\cdots|a_n)^* \), where \( n \geq 1 \) and \( a_1, a_2, \ldots, a_n \) are pairwise distinct symbols. Simple regular expressions are the simplest expressions that can be used in DTDs, as they impose restrictions neither on the cardinalities nor on the ordering of children, they just specify their types.

**Theorem 5.11.** For each of the three classes \( \text{STD}(\varepsilon//), \text{STD}(\varepsilon//), \text{and} \text{STD}(\varepsilon//) \) one can find a data exchange setting in which all STDs belong to that class, and a CTQ-query \( Q \) such that \text{Certain-Answers}(Q) \) is \text{coNP}-complete, even if all regular expressions used in source and target DTDs are simple.

**Proof.** For the sake of readability, here we consider only the case of \( \text{STD}(\varepsilon//) \), and the other two cases are considered in Section B.2.

We define a data exchange setting \((D_S, D_T, \Sigma_{\text{ST}})\) and a Boolean CTQ-query \( Q \) such that both \( D_S \) and \( D_T \) are simple DTDs, \( \Sigma_{\text{ST}} \) is a set of source-to-target dependencies in \( \mathrm{STD}(\varepsilon//) \) and 3SAT can be reduced to the complement of \text{Certain-Answers}(Q), that is, for every propositional formula \( \theta \) in 3-CNF, there exists a \text{PTIME} constructible XML tree \( T_\theta \) conforming to \( D_S \) such that \( \theta \) is satisfiable if and only if \( \text{certain}(Q, T_\theta) = \text{false} \). Simple DTD \( D_S \) is defined as follows. Let
\[ E_S = \{ K, C, L \} \] be a set of element types and \( A_S = \{ @f, @s, @t, @p, @n \} \) be a set of attributes. Then \( D_S = (P_S, R_S, K) \) is a DTD over \( (E_S, A_S) \), where \( P_S \) is defined as:

\[ P_S(K) = C^* L^*, \quad P_S(C) = \varepsilon, \quad P_S(L) = \varepsilon. \]

and \( R_S \) is defined as:

\[ R_S(K) = \emptyset, \quad R_S(C) = \{ @f, @s, @t \}, \quad R_S(L) = \{ @p, @n \}. \]

XML trees conforming to \( D_S \) are used to represent propositional formulae. Let \( \theta = (x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4) \). To construct tree \( T_\theta \), first we assign a distinct natural number to each literal, say

\[
\begin{align*}
    x_1 &\mapsto 1, & x_2 &\mapsto 3, & x_3 &\mapsto 5, & x_4 &\mapsto 7, \\
    \neg x_1 &\mapsto 2, & \neg x_2 &\mapsto 4, & \neg x_3 &\mapsto 6, & \neg x_4 &\mapsto 8.
\end{align*}
\]

Then we represent each clause of \( \theta \) as a node of type \( C \), being the values of attributes \( @f, @s, @t \) the first, second and third literal of that clause, respectively. For each propositional variable \( x \) in \( \theta \), we use the attributes \( @p, @n \) of a node of type \( L \) to store the values assigned to \( x \) and \( \neg x \), respectively. Tree \( T_\theta \) is shown in Figure 3.

Simple DTD \( D_T \) is defined as follows. Let \( E_T = \{ K, L, G_1, G_2, G_3, H_1, H_2, H_3 \} \) be a set of element types and \( A_T = \{ @\ell, @p, @n \} \) a set of attributes. Then \( D_T = (P_T, R_T, K) \) is a DTD over \( (E_T, A_T) \), where \( P_T \) is defined as:

\[
\begin{align*}
P_T(K) &= G_1^* L^*, \quad P_T(G_1) = H_1^* G_2^*, \quad P_T(H_1) = H_2^*, \\
P_T(H_2) &= H_3^*, \quad P_T(H_3) = \varepsilon, \quad P_T(G_2) = H_1^* G_3^*, \\
P_T(G_3) &= H_1^*, \quad P_T(L) = \varepsilon.
\end{align*}
\]

and \( R_T \) is defined as:

\[
\begin{align*}
    R_T(K) &= \emptyset, \quad R_T(G_1) = \emptyset, \quad R_T(H_1) = \{ @\ell \}, \\
    R_T(H_2) &= \{ @\ell \}, \quad R_T(H_3) = \{ @\ell \}, \quad R_T(G_2) = \emptyset, \\
    R_T(G_3) &= \emptyset, \quad R_T(L) = \{ @p, @n \}.
\end{align*}
\]

Finally, \( \Sigma_{ST} \) is defined as follows. The first rule of \( \Sigma_{ST} \) is defined as:

\[
K[L(@p = x, @n = y)] := K[L(@p = x, @n = y)].
\]
This rule says that every node of type \( L \) in a source tree \( T \) must appear in every solution for \( T \). The second rule of \( \Sigma_{ST} \) is defined as:

\[
H_1(\@t = x)[H_2(\@t = y)[H_3(\@t = z)]] \quad \leftarrow \quad K[C(\@f = x, \@s = y, \@t = z)].
\]

Notice that this rule is not fully-specified since it does not say whether the parent of \( H_1 \) is a node of type either \( G_1 \) or \( G_2 \) or \( G_3 \). Also notice that in this rule we use neither descendant // nor wildcard \( {} \).

The previous rule says that for every \( C \)-node \( v \) of a source tree \( T \), the values \( i, j, k \) of attributes \( \@f, \@s, \@t \) of \( v \) must appear in every solution for \( T \) in a subtree of the form shown in Figure 4 (a). For example, every solution for tree \( T_0 \) shown in Figure 3 must have a subtree of the form shown in Figure 4 (b) since \( T_0 \) has a \( C \)-node with values 1, 3, 6 in attributes \( \@f, \@s, \@t \).

When constructing a solution for \( T_0 \), we are actually constructing a truth assignment for \( \theta \). For example, let \( v \) be the \( C \)-node of \( T_0 \) with values 1, 3, 6 in attributes \( \@f, \@s, \@t \). To construct a solution \( T' \) for \( T \) we have to instantiate the second dependency of \( \Sigma_{ST} \) on values 1, 3 and 6, and then we have to construct a subtree of the form shown in Figure 4 (b) and place it in \( T' \), that is, we have to choose the type of the parent of the node of type \( H_1 \). The three alternatives for the type of this parent are shown in Figures 4 (c), (d) and (e). These alternatives represent three different ways of satisfying the clause stored in the children of \( v \).

We say that a literal \( i \) has been assigned value 1 if \( i \) is the value of attribute \( \@f \) of a great-grandchild of a node of type \( G_1 \). Thus, in Figure 4 (c), literal 6 (corresponding to \( \neg x_3 \)) has been assigned value 1 since 6 is the value of attribute \( \@s \) of a great-grandchild (of type \( H_3 \)) of a node of type \( G_1 \). On the other hand, in Figure 4 (d), literal 3 (corresponding to \( x_2 \)) has been assigned value 1 since 3 is the value of attribute \( \@f \) of a great-grandchild (of type \( H_2 \)) of a node of type \( G_1 \), and in Figure 4 (e), literal 1 (corresponding to \( x_1 \)) has been assigned value 1 since 1 is the value of attribute \( \@s \) of a great-grandchild (of type \( H_1 \)) of a node of type \( G_1 \).

Notice that when constructing a truth assignment for \( \theta \), it is possible to choose value 1 for two complementary literals. For example, we can choose value 1 for \( x_2 \) when considering the first clause in \( T_0 \), and we can choose value 1 for \( \neg x_2 \) when considering the second clause in this tree. To take care of this problem we use the following Boolean CTQ-query \( Q \):

\[
\exists x \exists y (L(\@p = x, \@n = y) \land G_1[\llbracket \neg(\@f = x) \rrbracket] \land G_1[\llbracket \neg(\@s = y) \rrbracket]).
\]

Intuitively, query \( Q \) says that there exists two complementary literals \( x \) and \( y \) such that both \( x \) and \( y \) have been assigned value 1, that is, \( x \) and \( y \) are both values of attribute \( \@f \) of great-grandchildren of nodes of type \( G_1 \). Notice that if \( Q \) does not hold, then we have constructed a well defined truth assignment.

Now we prove that for every 3-CNF propositional formula \( \theta \), we have that \( \theta \) is satisfiable if and only if \( \text{certain}(Q, T_0) = \text{false} \), where \( T_0 \) is constructed from \( \theta \) in \( \text{PTIME} \) as shown above.

\((\Rightarrow)\) Assume that \( \theta \) is satisfiable and let \( \sigma \) be a truth assignment satisfying \( \theta \). Define a solution \( T' \) for \( T_0 \) as follows. The structure of the \( L \)-nodes of \( T' \) is copied from \( T_0 \). The structure of the \( G_1 \)-nodes of \( T' \) is defined as follows. For every \( C \)-node \( v \) in \( T_0 \) having \( i, j, k \) in attributes \( \@f, \@s, \@t \), let \( T_v \) be the tree shown in Figure 4 (a), and let \( v' \) be the node identifier of the root of this tree \( v' \) is of type
To place $T_v$ into $T'$, we have to decide what is the type of the parent of $v'$. If $\sigma$ makes true the third literal of the clause stored in $v$, then $T'$ has a node of type $G_1$ having $v'$ as its only child. If $\sigma$ makes true the second literal of the clause stored in $v$, then $T'$ has a node of type $G_1$ having only one child (of type $G_2$) and $v'$ as its only grandchild. If $\sigma$ makes true the first literal of the clause stored in $v$, then $T'$ has a node of type $G_1$ having only one child (of type $G_2$), only one grandchild (of type $G_3$) and $v'$ as its only great-grandchild. It is straightforward to prove that $T'$ conforms to $D_T$ and satisfies $\Sigma_{ST}$. Furthermore, $T' \not\models Q$ since $\sigma$ is well defined and, therefore, for every propositional variables $x$, either $x$ or $\neg x$ is not assigned value 1. We conclude that $\text{certain}(Q, T_0) = \text{false}$ since $T'$ is a solution for $T_0$.

($\Leftarrow$) Assume that $\text{certain}(Q, T_0) = \text{false}$ and let $T'$ be a solution for $T_0$ such that $T' \not\models Q$. We define a truth assignment for the propositional variables of $\theta$ as follows. For every clause in $\theta$, find the values $i, j, k$ assigned in $T_0$ (as values of attributes $@f$, $@s$ and $@t$) to the literals of that clause. Then find in $T'$ a subtree of the form shown in Figure 4 (a). Let $v'$ be the root of this tree. If the parent of $v'$ is of type $G_1$, then $\sigma$ assigns value 1 to the third literal of the clause. If the parent of $v'$ is of type $G_2$, then $\sigma$ assigns value 1 to the second literal of the clause. If the parent of $v'$ is of type $G_3$, then $\sigma$ assigns value 1 to the first literal of the clause. Since $T' \not\models Q$, we have that $\sigma$ is well defined. Thus $\theta$ is satisfiable since $\sigma$ satisfies this formula by definition. This concludes the proof of the theorem.

Thus, from now one we concentrate on fully-specified STDs. We note that STDs handled by Clio [Miller et al. 2001; Popa et al. 2002] are fully-specified. Our goal is to provide a classification of data exchange settings for which computing certain answers is tractable.
6. COMPUTING CERTAIN ANSWERS: CLASSIFICATION AND DICHOTOMY

**Proviso:** throughout this section, all source-to-target dependencies are fully-specified. As was shown earlier, outside of this class one cannot avoid coNP-hardness even for very simple source and target DTDs.

Our goal now is to classify the complexity of the\textsc{Certain-Answers} problem. As was explained earlier, it depends heavily on target DTDs. We shall classify target DTDs and prove a dichotomy theorem which states that depending on a class of regular languages used in DTDs, computing certain answers is either tractable or coNP-complete. If $C$ is a class of regular expressions, we say that a DTD $D$ is a $C$-DTD if all regular expressions in $D$ belong to $C$.

**Definition 6.1.** Given a class $C$ of regular expressions, and a class $Q$ of queries, we say that

- $C$ is tractable for $Q$ if for every data exchange setting $(D_S, D_T, \Sigma_{ST})$ with $D_T$ being a $C$-DTD, and every $Q \in Q$, the problem \textsc{Certain-Answers}(Q) is in PTIME;
- $C$ is coNP-complete for $Q$ if there exists a data exchange setting $(D_S, D_T, \Sigma_{ST})$ with $D_T$ being a $C$-DTD, and a query $Q \in Q$ such that \textsc{Certain-Answers}(Q) is coNP-complete;
- $C$ is strongly coNP-complete for $Q$ if the above holds when $D_S$ is simple and $Q$ is a Boolean query.

We want our classes of regular expressions to have some degree of uniformity: that is, we want to disallow classes that contain just a finite number of regular expressions, or only regular expressions that generate finite languages. We thus impose the constraint that all classes $C$ contain at least all simple regular expressions (recall that these are of the form $(a_1|a_2|\cdots|a_n)^*$ or $\epsilon$). Such classes will be called admissible.

**Theorem 6.2. (Dichotomy)** Let $C$ be an admissible class of regular expressions and $Q$ be one of $CT_Q$, $CT_Q^//=\cup$ and $CT_Q^//=\cup$-$\cup$. Then $C$ is either tractable, or strongly coNP-complete for $Q$-queries.

Furthermore, for each data exchange setting it is decidable if it falls in the tractable case, and in this case there is a polynomial time algorithm that for each source tree $T$ checks whether there exists a solution for $T$, and if this holds then produces a solution $T^*$ such that $\bar{s} \in \text{\textsc{certain}}(Q, T)$ iff $\bar{s} \in Q(T^*)$ for every tuple $\bar{s}$ from Const.

In the rest of the section, we prove this result and present the polynomial-time algorithm. We introduce a class $C_U$ of regular expressions that is tractable for $CTQ^//=\cup$-queries (and thus also for $CTQ^-$, $CTQ^//=\cup$ and $CTQ^//=\cup$-queries). Then we show that every admissible class of regular expressions $C \not\subseteq C_U$ is strongly coNP-complete for $CTQ$-queries (and thus also for $CTQ^//=\cup$, $CTQ^//=\cup$- and $CTQ^//=\cup$-queries).

### 6.1 The tractable case

We explain how to compute a \textit{canonical} tree $T^*$ over which $CTQ^//=\cup$-queries can be evaluated to produce $\text{\textsc{certain}}(Q, T)$. The restrictions on the class $C_U$ guarantee that the construction is done in PTIME.
Fix a data exchange setting \((D_S, D_T, \Sigma_{ST})\), where \(D_T = (P_T, R_T, \ell)\). For every tree-pattern formula \(\varphi(x)\) not mentioning descendant \(\triangledown\) and wildcard \(\_\) and for every tuple \(s\) of strings, there exists an unordered tree \(T_{\varphi(s)}\) naturally associated with \(\varphi(s)\). It is constructed inductively: if \(\varphi(s) = \ell(\triangledown a_1 = s_1, \ldots, \triangledown a_n = s_n)[\varphi_1(s_1), \ldots, \varphi_k(s_n)]\), then the root of \(T_{\varphi(s)}\) is a node \(v_0\) of type \(\ell\) that has attributes \(a_1, \ldots, a_n\) with values \(s_1, \ldots, s_n\), and \(k\) distinct children \(v_1, \ldots, v_k\), with \(v_i\) being the root of tree \(T_{\varphi_i(s_i)}\), for \(i \leq k\).

Recall that an STD \(\psi_T(x, z) := \varphi_S(x, \bar{y})\) is fully-specified if \(\psi_T\) is of the form \(\bigwedge[\varphi_1, \ldots, \varphi_k]\), where \(\bigwedge\) is the type of the root and \(\varphi_i\)'s do not use descendant \(\triangledown\) and wildcard \(\_\). Now we introduce the notion of canonical pre-solution. Given a source tree \(T\) conforming to \(D_S\), the canonical pre-solution for \(T\), denoted by \(\text{cps}(T)\), is an XML tree defined as follows. Let \(X\) be a set of XML trees such that for every fully-specified STD \(\psi_T(x, z) := \varphi_S(x, \bar{y})\) in \(\Sigma_{ST}\) and for every pair of tuples \(s, s'\) of strings such that \(|s| = |x|, |s'| = |\bar{y}|\) and \(T \models \varphi_S(s, s')\), we have that \(X\) includes \(T_{\psi_T(s, s')}\), where \(s''\) is an arbitrary tuple of length \(|z|\) of fresh distinct null values. Assume that \(X = \{T_1, \ldots, T_m\}\) and let \(v_1, \ldots, v_m\) be the root nodes of \(T_1, \ldots, T_m\). Then \(\text{cps}(T)\) is generated from \(T_1, \ldots, T_m\) by replacing \(v_1, \ldots, v_m\) by a single root node \(v_0\).

**Example 6.3.** Assume \(\Sigma_{ST}\) contains rules \(\psi_1(x, y, z) := \varphi(x, y, z)\) and \(\psi_2(y) := \varphi(x, y, z)\), where:

\[
\psi_1(x, y, z) = \bigwedge[A(\triangledown \ell = x), B(\triangledown a = y, \triangledown m = z)], \\
\psi_2(y) = \bigwedge[B(C, D, E(\triangledown m = y)], \\
\varphi(x, y, z) = \bigwedge[A(\triangledown a = x, \triangledown b = y, \triangledown c = z)],
\]

and assume that \(T\) is the source tree shown in Figure 5 (a). To construct \(\text{cps}(T)\), we instantiate the variables \(x, y, z\) in the right hand sides of the STDs on values 4, 5 and 6, respectively, and we generate the XML trees associated to \(\psi_1(4, 5, 6)\) and \(\psi_2(5)\), shown in Figures 5 (b) and (c). Then we merge the roots of \(T_{\psi_1(4, 5, 6)}\) and \(T_{\psi_2(5)}\) into a single node, generating the canonical pre-solution for \(T\), shown in Figure 5 (d).

Canonical pre-solutions can be computed in PTIME; the problem is that they may not conform to the target DTD. For example, if \(D_T\) contains a rule \(P_T(\ell) = \)

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(ABE)*, then the canonical pre-solution shown in Figure 5 (d) does not conform to \(D_T\). We present an algorithm for computing a canonical solution for a tree \(T\) from \(cps(T)\). The key is to find a “repair” every time we have a violation of constraints imposed by the target DTD. Given a node \(v\) of an unordered target tree \(T'\), we say that \((T',v)\) violates \(D_T\) if \(v\) does not have the right attributes or the children of \(v\) do not have the right types, that is, if \(\{r:a | \rho_a(v)\ \text{is defined in} \ T'\} \neq R_T(\lambda_T(v))\) or \(\lambda_T(children(v)) \notin \pi(P_T(\lambda_T(v)))\), where \(\lambda_T(children(v))\) refers to the string \(\lambda_T(v_1)\ldots\lambda_T(v_n)\), and \(v_1,\ldots,v_n\) are the children of \(v\).

The “easy” violations are those when nodes do not have the right attributes: if they miss some, we add them and give them fresh values from \(\text{Var}\); if they have extra attributes, the repair algorithm fails. More precisely, repairing function \(\text{ChangeAtt}\) receives as parameters a target tree \(T'\) and a node \(v\) such that \(\{r:a | \rho_a(v)\ \text{is defined in} \ T'\} \neq R_T(\lambda_T(v))\). This function fails if there exists an attribute \(r:a\) such that \(\rho_a(v)\ \text{is defined in} \ T'\) and \(\rho_a \notin R_T(\lambda_T(v))\), since in this case \(\Sigma_T\) forces \(v\) to have attribute \(r:a\) while \(D_T\) does not allow \(v\) to have such an attribute. Otherwise, for every \(r:a \in R_T(\lambda_T(v))\) such that \(\rho_a(v)\ \text{is not defined}\), \(\text{ChangeAtt}\) assigns a fresh value from \(\text{Var}\) to \(\rho_a(v)\). The “hard” violations are those when sequences of children do not satisfy the constraints imposed by regular expressions in DTDs. Repairing function \(\text{ChangeReg}\) (defined later) tries to repair these violations: It receives as parameters a target tree \(T'\) and a node \(v\) such that \(\lambda_T(children(v)) \notin \pi(P_T(\lambda_T(v)))\), and it either fails or returns a tree \(T''\) such that \(\lambda_T'(children(v)) \in \pi(P_T(\lambda_T'(v)))\).

Functions \(\text{ChangeAtt}\) and \(\text{ChangeReg}\) are applied to \(cps(T)\), in no particular order, until we reach a tree \(T^*\) that either conforms to \(D_T\) or is not reparable (that is, the repair algorithm fails). In the first case we say that \(T^*\) is a canonical solution for \(T\).

**Example 6.4.** Let \(D_S\) and \(D_T\) be the DTDs shown in Figures 6 (a) and (b). Notice that in the latter DTD, \(P_T(C) = (BC)^*, P_T(B) = \epsilon, P_T(C) = D, R_T(B) = \{\@m\}\) and \(R_T(C) = \emptyset\). Assume that \(T\) is the source tree, conforming to \(D_S\), shown in Figure 6 (c), and assume that \(\Sigma_T\) is given by the fully-specified STD \(\Sigma_T = A(\@e = x)\). Then the canonical pre-solution for \(T\) is the tree shown in Figure 6 (d), and a canonical solution for \(T\) is shown in Figure 6 (e). \(\square\)

For the class \(C_U\) (to be defined shortly) we prove:

**Lemma 6.5.** If \(D_T\) is a \(C_U\)-DTD, then for every source tree \(T\):

(a) There exists a solution for \(T\) iff there exists a canonical solution for \(T\).

(b) If \(T^*\) is a canonical solution for \(T\), then for every \(CTQ^U\) query \(Q(x)\) and every tuple \(s\) from \(\text{Const}\), \(s \in \text{certain}(Q,T)\) iff \(T^* \models Q(s)\) (if \(Q\) is Boolean, then \(\text{certain}(Q,T) = \text{true}\) iff \(T^* \models Q\)).

Furthermore, for \(C_U\)-DTDs canonical solutions can be computed efficiently by repeatedly applying \(\text{ChangeAtt}\) and \(\text{ChangeReg}\).

**Lemma 6.6.** If \(D_T\) is a \(C_U\)-DTD, then it can be checked in polynomial time whether there exists a canonical solution for a given source tree \(T\). Furthermore, if such a solution exists, then it can be computed in polynomial time.

Begin by putting together these two lemmas we obtain:

**Proposition 6.7.** \( C_U \) is tractable for \( C T Q \) queries.

Now we define the class \( C_U \), explain how \texttt{ChangeReg} works and then prove Lemmas 6.5 and 6.6. First, we need some terminology. Let \textit{alph}(w) (or \textit{alph}(r)) stands for the set of alphabet symbols mentioned in a string \( w \) (or a regular expression \( r \)). For every \( a \in \textit{alph}(w) \), recall that \( \#_a(w) \) is the number of occurrences of \( a \) in \( w \).

By the way, we only consider strings \( w \) for \( \textit{alph}(w) \) and canonical solution for \( D_B \), canonical pre-solution for \( T \) and canonical solution for \( T \).

For example, \( \textit{alph}(\mathit{aa}) = \{a\} \). Sometimes \texttt{ChangeReg} may need to extend not \( w \) itself but a substring of \( w \). For example, \( \textit{min\_ext}(bb, bc^+) = \emptyset \) and, thus, the only way to repair \( bb \) is to merge two \( b \)'s into a single \( b \) and then expand to a string in \( \pi(r) \). The resulting strings from the process of expanding substrings of \( w \) are the strings from which \texttt{ChangeReg} will be chosen a candidate to replace \( w \). Formally, the set of possible repairs of \( w \), denoted by \( \textit{rep}(w, r) \), is defined as:

\[
\text{rep}(w, r) = \bigcup_{w' \subseteq w, \text{alph}(w') = \text{alph}(w)} \text{min\_ext}(w', r).
\]

In this definition, we only consider strings \( w' \) such that \( \text{alph}(w) = \text{alph}(w') \), since \( \Sigma_{ST} \) forces \( v \) to have at least one child of type \( b \), for every \( b \in \text{alph}(w) \).

Once \texttt{ChangeReg} has constructed \( \text{rep}(w, r) \), it replaces \( w \) by a string \( w' \) from \( \text{rep}(w, r) \). In general, \( \text{rep}(w, r) \) will have more than one element, so we need a criterion to decide which string is the “best” candidate. For example, \( ccdl \) and \( cd \) belong to \( \text{rep}(cc, (cd)^*(cde)^*) \). Which one is better? If we decide to merge two
nodes into a single one, we have to put their attributes together. But this is not possible if these nodes have different constants values on the same attribute. Thus, we prefer candidates that merge as less elements as possible to avoid attribute clashes. For example, we prefer ccdd to cd, since ccdd does not merge any element type. Furthermore, we do not want to add element types if we are not forced to do it and, hence, we prefer ccdd to ccde. We formalize our preference relation as a preorder \( \preceq_w \). Formally, \( w_1 \preceq_w w_2 \) iff (1) \( \#_b(w_2) \geq \min\{\#_b(w_1), \#_b(w)\} \) for all \( b \in \text{alph}(w), \) and (2) \( \text{alph}(w_2) \setminus \text{alph}(w) \subseteq \text{alph}(w_1) \setminus \text{alph}(w) \). Thus, \text{ChangeReg} replaces \( w \) by \( w' \in \max_{\preceq_w} \text{rep}(w, r) \).

The canonical solution for a source tree must be unique, no matter which string \text{ChangeReg} picks from \( \max_{\preceq_w} \text{rep}(w, r) \) and no matter how \text{ChangeReg} merges the elements of \( w \). The problem is that for an arbitrary regular expression this does not necessarily hold. Thus, we have to restrict our attention to regular expressions such that (1) \( \max_{\preceq_w} \text{rep}(w, r) \) has a “best” candidate \( w' \) and (2) if \( \#_b(w) > \#_b(w') \), then \( \#_b(w') \) is equal to 1, so that there is only one way to merge the children of \( w \) of type \( b \). We now define these conditions formally. For a regular expression \( r \) and \( a \in \text{alph}(r) \), let \text{fixed}_{a}(r) \) be the set of \( w \) such that \( w' \in \pi(r) \) and \( w \preceq_w w' \) imply \( \#_a(w) = \#_a(w') \). For example, if \( r = a \mid aab^* \), then \( a \in \text{fixed}_{a}(r) \) since every string \( w \in \pi(r) \) such that \( a a \preceq w \) is a permutation of a string of the form \( aab^n \) \((n \geq 0)\) and, hence, \( \#_a(aa) = \#_a(a) = 2 \). On the other hand, \( a \notin \text{fixed}_{a}(r) \) since \( a \preceq_w aa \in \pi(r) \) and \( \#_a(a) < \#_a(aa) \). If \( \text{fixed}_{a}(r) \neq \emptyset \), then define \( c_a(r) = \max\{\#_a(w) \mid w \in \text{fixed}_{a}(r)\} \). If \( \text{fixed}_{a}(r) = \emptyset \), then \( c_a(r) = 0 \).

Finally, \( c(r) = \max\{c_a(r) \mid a \in \text{alph}(r)\} \).

For example, \( c_a(a \mid aab^*) = 2 \) and \( c_b(a \mid aab^*) = 0 \), and, thus, \( c(a \mid aab^*) = 2 \).

**Lemma 6.8.** \( c(r) \) is finite for every \( r \).

**Proof.** Let \( r \) be a regular expression and \( a \in \text{alph}(r) \). It is enough to prove that there exists a natural number \( k \) such that \( c_a(r) \leq k \). By Lemma 5.4, there exist regular expressions \( s_1, \ldots, s_n \) such that \( \pi(r) = \pi(s_1) \cdots \pi(s_n) \) and each \( s_i \) \((i \in [1, n])\) is of the form \( w_0(w_1^*) \cdots (w_m^*) \), where each \( w_j \) is a string \((j \in [0, m])\). Assume that \( s_i = w_i(w_{i,1})^* \cdots (w_{i,m_i})^* \) \((i \in [1, n])\), where \( w_i, w_{i,1}, \ldots, w_{i,m_i} \) are strings over \( \text{alph}(r) \). We will show that \( c_a(r) \leq \max_{i \in [1, n]} \#_a(w_i) \).

By contradiction, assume that either \( \{f \mid \text{there exists } w \in \text{fixed}_{a}(r) \text{ such that } \#_a(w) = f \} \) is unbounded or \( c_a(r) > \#_a(w_i) \) for every \( i \in [1, n] \). In either case, there exists a string \( w \in \text{fixed}_{a}(r) \) such that \( \#_a(w) > \#_a(w_i) \) for every \( i \in [1, n] \). Since \( w \in \pi(r) \) and \( \pi(r) = \pi(s_1) \cdots \pi(s_n) \), there exists \( j \in [1, n] \) such that \( w \in \pi(s_j) \). Thus, \( w \) is a permutation of a string \( w_j w', \) where \( w' \) is in the regular language defined by \( (w_{j,1})^* \cdots (w_{j,m_j})^* \). Given that \( \#_a(w) > \#_a(w_i) \), we have that \( a \in \text{alph}(w') \) and, therefore, \( a \in \text{alph}((w_{j,1})^* \cdots (w_{j,m_j})^*) \). Hence, string \( w w_{j,1} w_{j,2} \cdots w_{j,m_j} \) is in \( \pi(s_j) \subseteq \pi(r) \) and \( \#_a(w) < \#_a(w w_{j,1} w_{j,2} \cdots w_{j,m_j}) \), which contradicts the fact that \( w \in \text{fixed}_{a}(r) \). This concludes the proof of the lemma. □

**Definition 6.9.** We say that a regular expression \( r \) is univocal if \( c(r) \leq 1 \) and for every string \( w \) such that \( \text{rep}(w, r) \neq \emptyset \), the set \( \text{rep}(w, r) \) has a maximum element with respect to \( \preceq_w \): that is, an element \( w' \in \text{rep}(w, r) \) such that \( w' \preceq_w w'' \) for all \( w'' \in \text{rep}(w, r) \). We write \( U \) for the class of univocal regular expressions.
For example, all of the following are univocal regular expressions: $bc^d e^?$, $(b^+ | c^*)$ and $(bc)^* (de)^*$. It is easy to see that all simple regular expressions are univocal, and hence $C_U$ is an admissible class.

**Proposition 6.10.** It is decidable whether a regular expression $r$ is univocal. In fact, for each $r$ one can compute a sentence $\Phi_r$ of Presburger Arithmetic which is true iff $r$ is univocal.

**Proof.** Assume that $\text{alph}(r) = \{\sigma_1, \ldots, \sigma_n\}$. By Lemma 5.4 we know that $\pi(r) = \pi(s_1) \ldots |s_m|$, where each $s_i (i \in [1, m])$ is of the form $u_0(w_1)^* \cdots (w_\ell)^*$, where each $w_j$ is a string ($j \in [0, \ell]$). Let $i \in [1, m]$ and assume that $s_i = w_0 w_1^* \cdots w_\ell^*$. In the proof of Proposition 5.3, we showed that for each $s_i$, there exists an $n \times \ell$ matrix $A_i$ of non-negative integers such that for every string $w$, we have that $w \in \pi(s_i)$ iff there is an $\ell$-vector $\bar{x}$ of nonnegative integers such that $A_i \bar{x} + \bar{b} = \bar{c}$, where $\bar{b}$ and $\bar{c}$ are $n$-vectors with $b_j = \#_{\sigma_j}(w_0)$ and $c_j = \#_{\sigma_j}(w)$ ($j \in [1, n]$). Since $A_i$ depends only on $s_i$, there exists a formula $\varphi_i(x_1, \ldots, x_n)$ of Presburger Arithmetic such that for every string $w$, we have

$$w \in \pi(s_i) \text{ iff } \varphi_i(\#_{\sigma_1}(w), \ldots, \#_{\sigma_n}(w)) \text{ holds.}$$

We conclude that formula $\varphi(r)(x_1, \ldots, x_n) = \bigwedge_{i=1}^m \varphi_i(x_1, \ldots, x_n)$ is such that a string $w$ is in $\pi(r)$ iff $\varphi_r(\#_{\sigma_1}(w), \ldots, \#_{\sigma_n}(w))$ holds.

Now simply by examining the definition of univocality we notice that we only refer to number of occurrences of symbols in strings, and the definition itself can be stated in first-order logic using $\varphi_r$; hence the result follows.

Summing up, if $D_T$ is a $C_U$-DTD, then $\text{ChangeReg}(T', v)$ is defined as shown in Figure 7 (for the sake of completeness, we also include function $\text{ChangeAtt}$ in Figure 7). Recall that $\ell = \lambda_T(v)$, $w = \lambda_T(\text{children}(v))$ and $r = P_T(\ell)$. Initially, $\text{ChangeReg}$ checks whether $\text{rep}(w, r)$ is empty. If this is the case, then it fails. Otherwise, $\text{ChangeReg}$ picks an arbitrary string $w'$ from $\text{max}_{w''} \text{rep}(w, r)$, and then it replaces $w$ by $w'$. More precisely, let $b \in \text{alph}(r)$, $p = \#_b(w)$ and $q = \#_b(w')$. If $p < q$, then $\text{ChangeReg}$ adds $(q - p)$ new children to $v$ of type $b$, each of them having no attributes and no children. If $q < p$, then $q = 1$ (since $r$ is univocal) and, thus, $\text{ChangeReg}$ replaces the sequence $v_1, \ldots, v_p$ of children of $v$ of type $b$ by a single fresh node $v'$ of type $b$, and then for every subtree $T_i$ of $T'$ rooted at $v_i (i \in [1, p])$, it replaces the root of $T_i$ by $v'$. At this point $\text{ChangeReg}$ fails if there is an attribute clash, that is, if there is a pair of subtrees of $T'$ rooted at $v_i, v_j (i, j \in [1, p])$ and an attribute $\delta a$ such that $\rho_{\delta a}(v_i) \in \text{Const}, \rho_{\delta a}(v_j) \in \text{Const}$ and $\rho_{\delta a}(v_i) \neq \rho_{\delta a}(v_j)$.

In the rest of this section, we prove Lemmas 6.5 and 6.6 that are used to show that the algorithm presented in this section is correct and it can be implemented in polynomial time, for every fixed target DTD $D_T$ containing only univocal regular expressions. But before doing this, we note that all regular expressions used in nested-relational DTDs are univocal. Hence, the following extension of relational data exchange handled by Clio [Popa et al. 2002] falls in the following large tractable case:

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5Violations generated by adding $b$-nodes without attributes or children are repaired later by repeatedly applying $\text{ChangeAtt}$ and $\text{ChangeReg}$. 

A (possible infinite) sequence of trees $T_0, \ldots, T_i, \ldots$ over $(E_T, A_T)$ is a chase sequence if for every $T_j, T_{j+1}$ in the sequence, either $\text{ChangeAtt}$ or $\text{ChangeReg}$ can be applied to $T_j$ to generate $T_{j+1}$, that is, $T_j \neq T_{j+1}$ and there exists a node $v$ in $T_j$ such that either $T_{j+1} = \text{ChangeAtt}(T_j, v)$ or $T_{j+1} = \text{ChangeReg}(T_j, v)$.
Moreover, a chase sequence $T_0, \ldots, T_i, \ldots$ is said to be terminal if it is finite and its last tree $T_n$ is such that neither ChangeAtt nor ChangeReg can be applied to it.

**Lemma 6.12.** Every chase sequence $T_0, \ldots, T_i, \ldots$ is finite.

**Proof.** Let $T_0, \ldots, T_i, \ldots$ be a chase sequence. We prove this lemma by induction on the depth of $T_0$. If the depth of $T_0$ is 1, then $T_0$ has only one node. Given that $D_T$ is a consistent DTD, we have that $T_0, \ldots, T_i, \ldots$ is contained in a terminal chase sequence having as last element a tree $T_n$ conforming to $D_T$.

Assume that the depth of $T_0$ is $m > 1$ and that the property holds for every chase sequence having as first element a tree with depth at most $m - 1$. Furthermore, for every pair $T_j, T_{j+1}$ of trees in $T_0, \ldots, T_i, \ldots$, assume that either $T_{j+1} = \text{ChangeAtt}(T_j, v_j)$ or $T_{j+1} = \text{ChangeReg}(T_j, v_j)$. Let $u_0$ be the root node of $T_0$. Since $u_0$ can be used at most twice to construct the chase sequence $T_0, \ldots, T_i, \ldots$, once as input of ChangeAtt and the other one as input of ChangeReg, we can assume that there exists $j \geq 0$ such that $u_0 \neq v_k$, for every $k \geq j$. Let $u_1, \ldots, u_p$ be the sequence of children of $u_0$ in $T_j$, and for every $k \in [1, p]$, let $T_k^j, \ldots, T_k^j$ be a chase sequence defined as follows. $T_k^j$ is the subtree of $T_j$ rooted at $u_k$. Let $T', T''$ be a consecutive pair of trees in $T_0, \ldots, T_i, \ldots$ such that $T', T''$ is the $\ell$-th ($\ell \geq 1$) pair of consecutive trees in the chase sequence $T_j, \ldots, T_i, \ldots$ such that either $T'' = \text{ChangeAtt}(T', v')$ or $T'' = \text{ChangeReg}(T', v')$ and $v'$ is a descendant of $u_k$. Then $T_k^j = \text{ChangeAtt}(T_k^{j-1}, v')$, if $T'' = \text{ChangeAtt}(T', v')$, and $T_k^j = \text{ChangeReg}(T_k^{j-1}, v')$ otherwise. Given that $u_0$ is not used to construct the chase sequence $T_j, \ldots, T_i, \ldots$, the children of the root $u_0$ are the same in every tree of this sequence and, hence, every node used to construct $T_j, \ldots, T_i, \ldots$ is a descendant of some node $u_k$ ($k \in [1, p]$). Thus, if every chase sequence $T_0^j, \ldots, T_i^j, \ldots$ is finite, then $T_j, \ldots, T_i, \ldots$ is finite and, hence, $T_0, \ldots, T_i, \ldots$ is finite. But the depth of $T_0^j (k \in [1, p])$ is at most $m - 1$ and, hence, by induction hypothesis we have that $T_0^j, \ldots, T_i^j, \ldots$ is finite. This proves that our original chase sequence $T_0, \ldots, T_i, \ldots$ is also finite. □

As a corollary of the previous lemma we obtain that every chase sequence $T_0, \ldots, T_i, \ldots$ is contained in a terminal sequence.

We say that a chase sequence $T_0, \ldots, T_n$ is successful if $T_n = D_T$, and we say that $T_0, \ldots, T_n$ is a failing chase sequence if $T_0, \ldots, T_n$ is terminal and $T_n \neq D_T$. Moreover, given a source tree $T$ conforming to $D_S$, we say that $T_0, \ldots, T_n$ is a chase sequence for $T$ if $T_0 = \text{cps}(T)$, and we say that a target tree $T'$ is a canonical solution for $T$ if there exists a successful chase sequence $T_0, \ldots, T_n$ for $T$ such that $T' = T_n$.

**Example 6.13.** Let $D_R$ and $D_T$ be the DTDs shown in Figures 6 (a) and (b), and $\Sigma_{ST}$ be the set \{\$[B(\ell=m = x)] : A(\ell = x)\} of fully-specified STDs. Notice that $D_T$ is a $(BC)^\ast$-DTD since $(BC)^\ast$ is a univocal regular expression.

Assume that $T$ is the source tree, conforming to $D_R$, shown in Figure 6 (c). Then the canonical pre-solution for $T$ is the tree shown in Figure 6 (d), and the canonical solution for $T$ shown in Figure 6 (e) is constructed as follows. Let $T_0 = \text{cps}(T)$, $v_0$ be the root node of $T_0$, $v_1, v_2$ the sequence of children of $v_0$ and $w = \lambda T_0(v_1)\lambda T_0(v_2) = BB$. Since $BB$ is $\not\in \pi(P_T(\Sigma)) = \pi((BC)^\ast)$, we invoke ChangeReg($T_0, v_0$).
A finite set of element types, do this, first we introduce the notion of homomorphism for trees. Let $E \subseteq El$ be a finite set of element types, $A \subseteq Att$ be a finite set of attributes and $T, T'$ be XML trees over $(E, A)$. Assume that $T = (N, <_{\text{child}}, \text{root})$ and $\text{Str}(T) = \{s \in \text{Str} \mid \text{there exists } v \in N \text{ and } @a \in A \text{ such that } \rho_{a}(v) = s\}$. Furthermore, assume that $T' = (N', <_{\text{child}}, \text{root}')$ and $\text{Str}(T')$ is defined as above. Then a function

**Fig. 8.** Chase sequence.

Since $\text{rep}(BB, (BC)^* ) = \text{min}_{\text{ext}} (B, (BC)^* ) \cup \text{min}_{\text{ext}} (BB, (BC)^* ) = \{BC, CB\} \cup \{BBC, BCBC, BCCB, CBBC, CBB, CBBC, CBCB, CBBB\}$, ChangeReg does not fail and it chooses a string from $\text{max}_{\text{ext}} \text{rep}(BB, (BC)^* )$. Given that $BC \equiv_{BB} \{CB \leq_{BB} CB \text{ and } CB \leq_{BB} BC\}$, $BC \prec_{BB} BBCC \text{ (} BC \leq_{BB} BBCC \text{ and } BBCC \not\leq_{BB} BC\text{)}$ and $BBCC$ is equivalent to all the strings in $\text{min}_{\text{ext}} (BB, (BC)^*)$, the algorithm chooses $w' = BBCC$. Since $\#_{B}(BB) = \#_{B}(BBCC)$ and $\#_{C}(BB) < \#_{C}(BBCC)$, the algorithm adds to $v_0$ two new children of type $C$, generating tree $T_1$ shown in Figure 8 (a). Let $v_3$ and $v_4$ be the node identifiers of these new nodes.

Given that $\lambda_{T_1}(v_3) = C$, $P_{T}(C) = D$ and $v_3$ has no children, we invoke ChangeReg($T_1, v_3$). Since $\text{rep}(\epsilon, D)$ is not empty ($\text{rep}(\epsilon, D) = \{D\}$), ChangeReg does not fail and it chooses a string $w'$ from $\text{max}_{\text{ext}} \text{rep}(\epsilon, D)$, in this case $w' = D$. Then it adds to $v_3$ a new child of type $D$ since $\#_{D}(\epsilon) < \#_{D}(D)$, generating tree $T_2$ shown in Figure 8 (b). Let $v_5$ be the node identifier of this new node. Since $\lambda_{T_2}(v_5) = D$, $R_{T}(D) = \{\oplus n\}$ and $v_5$ has no attributes, we invoke ChangeAtt($T_2, v_5$). This function adds to $v_5$ an attribute $\oplus n$ with value $\bot_1$, where $\bot_1$ is a fresh null value. The resulting tree $T_3$ is shown in Figure 8 (c).

Recall that $v_4$ is the last children of root node $v_0$. Given that $\lambda_{T_2}(v_4) = C$, $P_{T}(C) = D$ and $v_4$ has no children, we invoke ChangeReg($T_3, v_4$). Since $\text{rep}(\epsilon, D)$ is not empty, ChangeReg does not fail and it chooses a string $w'$ from $\text{max}_{\text{ext}} \text{rep}(\epsilon, D)$, in this case $w' = D$. Then it adds to $v_4$ a new child of type $D$ since $\#_{D}(\epsilon) < \#_{D}(D)$, generating tree $T_4$ shown in Figure 8 (d). Finally, let $v_6$ be the node identifier of this new node. Since $\lambda_{T_4}(v_6) = D$, $R_{T}(D) = \{\oplus n\}$ and $v_6$ has no attributes, we invoke ChangeAtt($T_4, v_6$). This function adds to $v_6$ an attribute $\oplus n$ with value $\bot_2$, where $\bot_2$ is a fresh null value. The resulting tree is the canonical solution for $T$, shown in Figure 6 (e).

Next we show that canonical solutions can be used to compute certain answers. To do this, first we introduce the notion of homomorphism for trees. Let $E \subseteq El$ be a finite set of element types, $A \subseteq Att$ be a finite set of attributes and $T, T'$ be XML trees over $(E, A)$.
for every $v \in N$, $h(v) \in N'$;
(b) if $s \in \text{Const} \cap \text{Str}(T)$, $h(s) = s$, and for every $s \in \text{Var} \cap \text{Str}(T)$, $h(s) \in \text{Str}(T')$;
—$h(\text{root}) = \text{root'}$;
—for every $v_1, v_2 \in N$, if $v_1 <_{\text{child}} v_2$, then $h(v_1) <_{\text{child}} h(v_2)$;
—for every $v \in N$, $\lambda_T(v) = \lambda_{T'}(h(v))$;
—for every $v \in N$ and $\bar{a} \in A$ such that $\rho_{\bar{a}}(v)$ is defined, $h(\rho_{\bar{a}}(v)) = \rho_{\bar{a}}(h(v))$.

It is easy to see that the following lemma holds.

\textbf{Lemma 6.14.} Let $E$ be a finite set of element types, $A$ a finite set of attributes, $T, T'$ XML trees over $(E, A)$, $Q(\bar{x})$ a $\mathcal{A}_{\mathcal{O}, \mathcal{I}, \mathcal{R}}$-query over $(E, A)$ and $\bar{s}$ a tuple of constants such that $T \models Q(\bar{s})$. If there exists a homomorphism $h : T \to T'$, then $T' \models Q(\bar{s})$.

\textbf{Lemma 6.15.} Let $T_0, \ldots, T_n$ be a terminal chase sequence for a tree $T$ conforming to $D$s.

(a) For every solution $T'$ for $T$ and every $i \in [0, n]$, there exists a homomorphism $h_i : T_i \to T'$.
(b) If $T_0, \ldots, T_n$ is a failing sequence, then there is no solution for $T$.

\textbf{Proof.} (a) By induction on $i \in [0, n]$. Since $T_0 = \text{cps}(T)$ and $T'$ is a solution for $T$, it is easy to see that there exists a homomorphism $h_0 : T_0 \to T'$. Assume that the property holds for $i < n$, that is, there exists a homomorphism $h_i : T_i \to T'$. To show that there exists a homomorphism $h_{i+1} : T_{i+1} \to T'$, we consider two cases. In both cases we assume that $N_i, N_{i+1}, N_{i+1}$ are the sets of node identifiers of $T_i, T_i$ and $T_{i+1}$, respectively.

First, assume that $T_{i+1} = \text{ChangeAtt}(T_i, v)$, and define function $h_{i+1} : N_{i+1} \cup \text{Str}(T_{i+1}) \to N' \cup \text{Str}(T')$ as follows. For every $u \in N_{i+1}$, define $h_{i+1}(u)$ as $h_i(u)$. We note that this is well defined since $T_{i+1} = \text{ChangeAtt}(T_i, v)$ and, hence, $N_i = N_{i+1}$. For every string $s \in \text{Str}(T_{i+1}) \cap \text{Const}$, define $h_{i+1}(s)$ as $s$. We note that this is well defined since $\text{Str}(T_i) \cap \text{Const} = \text{Str}(T_{i+1}) \cap \text{Const}$. Finally, for every $s \in \text{Str}(T_{i+1}) \cap \text{Var}$, we consider two cases. If $s \in \text{Str}(T_i)$, then define $h_{i+1}(s)$ as $h_i(s)$. Otherwise, $s$ is a null value that is added to $T_i$ by $\text{ChangeAtt}(T_i, v)$ and, therefore, there exists $\bar{a} \in R_T(\lambda_{T_{i+1}}(v))$ such that $s = \rho_{\bar{a}}(v)$. Define $h_{i+1}(s)$ as $\rho_{\bar{a}}(h_i(v))$. We observe that this is well defined since $T' \models D$, and, hence, $\rho_{\bar{a}}(h_i(v))$ is defined in $T'$ since $\bar{a} \in R_T(\lambda_{T'}(v)) = R_T(\lambda_{T'}(h_i(v)))$. Since $h_i$ is a homomorphism, it is easy to see that $h_{i+1}$ is a homomorphism from $T_{i+1}$ to $T'$.

Second, assume that $T_{i+1} = \text{ChangeReg}(T_i, v)$. To define homomorphism $h_{i+1} : T_{i+1} \to T'$ we need to prove an intermediate result. Let $w_i = \lambda_T(\text{children}(v))$, $w_{i+1} = \lambda_{T_{i+1}}(\text{children}(v))$ and $w' = \lambda_{T'}(\text{children}(h_i(v)))$.

\textbf{Claim 6.16.}

(a) $\text{alph}(w_{i+1}) \subseteq \text{alph}(w')$.
(b) If $a \in \text{alph}(w_i)$ is such that $\#_a(w_{i+1}) = 1$ and $\#_a(w_i) > 1$, then $\#_a(w') = 1$. 

The proof of Claim 6.16 can be found in the appendix. We use Claim 6.16 to define function \( h_{i+1} : N+1 \cup \text{Str}(T_{i+1}) \rightarrow N' \cup \text{Str}(T') \). For every \( u \in N+1 \) that is not a child of \( v \), define \( h_{i+1}(u) = h_i(u) \). We observe that this is well defined since \( \text{ChangeReg}(T_i, v) \) modifies only the sequence of children of \( v \). For every \( s \in \text{Str}(T_{i+1}) \cap \text{Const} \), define \( h_{i+1}(s) \) as \( s \). We note that this is well defined since \( \text{Str}(T_i) \cap \text{Const} = \text{Str}(T_{i+1}) \cap \text{Const} \). Finally, for every children \( u \) of \( v \) and every \( \forall a \in R_T(\lambda_{T_{i+1}}(u)) \), we define \( h_{i+1}(u) \) and \( h_{i+1}(\rho_{T_{i+1}}(a)) \) as follows. Assume that \( \lambda_{T_{i+1}}(u) = \ell \). If \( \#_\ell(w_{i+1}) \geq \#_\ell(w_i) \) and \( u \in N_i \), then \( h_{i+1}(u) = h_i(u) \) and \( h_{i+1}(\rho_{T_{i+1}}(a)) = h_i(\rho_{T_{i+1}}(a)) \). If \( \#_\ell(w_{i+1}) \geq \#_\ell(w_i) \) and \( u \notin N_i \), then define \( h_{i+1}(u) \) as \( u' \), where \( u' \) is an arbitrary child of \( h_i(v) \) in \( T' \) of type \( \ell \). We note that such a node exists since, by Claim 6.16, \( \alpha \; T \; \alpha \) defined function \( \lambda_{T_{i+1}} \) and \( \lambda_{T_{i+1}} \) needs the following claim.

Let \( w = \text{children}(v) \), \( h \) a homomorphism from \( T_n \) to \( T' \) such a homomorphism exists by (a)) and \( u' = \text{children}(h(v)) \). We consider three cases.

First, assume that there exists a node \( v \) in \( T_n \) such that \( \{ \forall a \in A_T | \rho_{T_{i+1}}(v) \text{ is defined in } T_n \} \neq R_T(\lambda_{T_{i+1}}(v)) \) and \( \text{ChangeAtt}(T_n, v) \) fails or \( \lambda_{T_{i+1}}(\text{children}(v)) \notin \pi(\overline{T}(\lambda_{T_{i+1}}(v))) \) and \( \text{ChangeReg}(T_{i+1}, v) \) fails. Let \( w = \text{children}(v) \), \( h \) a homomorphism from \( T_n \) to \( T' \) such a homomorphism exists by (a)) and \( u' = \text{children}(h(v)) \). We consider three cases.

Second, assume that there exists a node \( v \) in \( T_n \) such that \( \lambda_{T_{i+1}}(\text{children}(v)) \notin \pi(\overline{T}(\lambda_{T_{i+1}}(v))) \) and \( \text{ChangeReg}(T_{i+1}, v) \) fails because \( \text{rep}(w, \overline{T}(\lambda_{T_{i+1}}(v))) \) is \( \emptyset \). Since \( h : T_n \rightarrow T' \), we have that \( \text{alph}(w) \subseteq \text{alph}(w') \). Define string \( w_1 \) as follows: \( \text{alph}(w_1) = \text{alph}(w) \) and \( \#_\alpha(w_1) = 1 \), for every \( a \in \text{alph}(w_1) \). Then \( w_1 \preceq w' \) since \( \text{alph}(w) \subseteq \text{alph}(w') \). Thus, there exists \( w_2 \in \text{min}_\text{ext}(w_1, \overline{T}(\lambda_{T_{i+1}}(v))) \) such that \( w_1 \preceq w_2 \preceq w' \) since \( \text{rep}(w', \overline{T}(\lambda_{T_{i+1}}(v))) \) is not empty, which contradicts our original assumption.

Third, assume that there exists a node \( v \) in \( T_n \) such that \( \lambda_{T_{i+1}}(\text{children}(v)) \notin \pi(\overline{T}(\lambda_{T_{i+1}}(v))) \) and \( \text{ChangeReg}(T_{i+1}, v) \) fails because the algorithm chooses \( w_1 = \max_{w \in \text{rep}(w, \overline{T}(\lambda_{T_{i+1}}(v)))} w \) such that \( \rho_{T_{i+1}}(a) \in \text{Const} \) and \( \rho_{T_{i+1}}(u_2) \in \text{Const} \) and \( \rho_{T_{i+1}}(u_1) \neq \rho_{T_{i+1}}(u_2) \). To establish a contradiction we need the following claim.

**Claim 6.17.** Let \( r \) be a univocal regular expression. For every string \( w_1 \) such
that \( \text{rep}(w_1, r) \neq \emptyset \), every \( w_2 \in \max_{\leq_w} \text{rep}(w_1, r) \) and every \( a \in \text{alph}(w_1) \), if \( \#_a(w_2) < \#_a(w_1) \), then \( \#_a(w_2) = 1 \).

The proof of Claim 6.17 can be found in the appendix. We use this claim to show that \( \#_b(w') = 1 \). On the contrary, assume that \( \#_b(w') > 1 \). Since \( h \) is a homomorphism from \( T_n \) to \( T' \), we have that \( \text{alph}(w) \subseteq \text{alph}(w') \). Define string \( w_2 \) as follows: \( \text{alph}(w_2) = \text{alph}(w) \), \( \#_b(w_2) = 2 \) and \( \#_c(w_2) = 1 \), for every \( c \in \text{alph}(w_2) \setminus \{ b \} \). Then \( w_2 \leq w' \) since \( \text{alph}(w) \subseteq \text{alph}(w') \) and \( \#_b(w') > 1 \). Thus, there exists \( w_3 \in \text{min}_{\leq w}(w_2, P_T(\lambda_T(v))) \) such that \( w_2 \leq w_3 \leq w' \) since \( w' \in \pi(P_T(\lambda_T(h(v)))) = \pi(P_T(\lambda_T(v))) \). By definition of \( \text{rep}(w, P_T(\lambda_T(v))) \) we have that \( w_3 \in \text{rep}(w, P_T(\lambda_T(v))) \). Since \( \#_b(w_2) = 2 \), we have that \( \#_b(w_3) > 1 \). Furthermore, given that \( \#_b(w_1) < \#_b(w) \) and \( w_1 \in \max_{\leq_w} \text{rep}(w, P_T(\lambda_T(v))) \), by Claim 6.17 we have that \( \#_b(w_1) = 1 \). Hence, given that \( \#_b(w_3) > 1 \), \( \#_b(w_1) = 1 \) and \( \#_b(w) > \#_b(w_1) \), we conclude that \( w_3 \not\leq_w w_1 \), which contradicts the fact that \( (\text{rep}(w, P_T(\lambda_T(v))), \leq_w) \) has a maximum element (recall that \( P_T(\lambda_T(v)) \) is a univocal regular expression) and \( w_1 \in \max_{\leq_w} \text{rep}(w, P_T(\lambda_T(v))) \).

Since \( \#_b(w') = 1 \), there is only one child of \( h(v) \) of type \( b \), say \( u' \). Since \( h : T_n \rightarrow T' \) is a homomorphism and both \( u_1 \) and \( u_2 \) are child of \( v \) of type \( b \), we have that \( h(u_1) = h(u_2) = u' \). Thus, \( h(\rho_{ab}(u_1)) = h(\rho_{ab}(u_2)) \). Thus, given that both \( \rho_{ab}(u_1) \in \text{Const} \) and \( \rho_{ab}(u_2) \in \text{Const} \), we conclude that \( \rho_{ab}(u_1) = h(\rho_{ab}(u_2)) = h(\rho_{ab}(u_2)) = \rho_{ab}(u_2) \), which contradicts our original assumption. This concludes the proof of the second part of the lemma.

We are finally ready to prove Lemma 6.5.

**Proof of Lemma 6.5.** (a) We only need to prove one direction. Assume that there is no canonical solution for \( T \). By Lemma 6.12, there exists a failing chase sequence for \( T \) and, therefore, there is no solution for \( T \) by Lemma 6.15.

(b) First, assume that \( T^* \neq Q(s) \). Then \( s \notin \text{certain}(Q, T) \) since \( T^* \) is a solution for \( T \). Second, assume that \( T^* \models Q(s) \) and let \( T' \) be a solution for \( T \). Then, by Lemma 6.15 we know that there exists a homomorphism \( h \) from \( T^* \) to \( T' \). Thus, by Lemma 6.14 we have that \( T^* \models Q(s) \) since \( Q \) is a \( \text{CTQ}^{\|\cdot\|} \)-query. We conclude that for every solution \( T' \) for \( T \), it is the case that \( T^* \models Q(s) \) and, hence, \( s \in \text{certain}(Q, T) \).

To show that the canonical solution can be computed in polynomial time, we just need to prove one additional lemma.

**Lemma 6.18.** Let \( r \) be a fixed regular expression. Then the following problems are solvable in \( \text{PTIME} \):

1. Given an input string \( w \), determine whether \( \text{rep}(w, r) \neq \emptyset \).
2. Given an input string \( w \) such that \( \text{rep}(w, r) \neq \emptyset \), compute \( w' \in \max_{\leq_w} \text{rep}(w, r) \).

**Proof.** Since \( r \) is a fixed regular expression, by Proposition 5.3, the problem of checking whether a string \( w \in \pi(r) \) can be solved in time \( O(p(|w|)) \), where \( p \) is a fixed polynomial.

(1) In what follows, we assume that \( \text{alph}(r) = \{a_1, \ldots, a_k\} \) and \( f : \{a_1, \ldots, a_k\}^* \rightarrow \mathbb{N}^k \) is a mapping defined as \( f(w) = (\#_{a_1}(w), \ldots, \#_{a_k}(w)) \). We
note that if \( f(w_1) = f(w_2) \), then \( w_1 \in \pi(r) \) if and only if \( w_2 \in \pi(r) \). To determine whether \( \text{rep}(w, r) \neq \emptyset \), we have to check whether there exists string \( w' \) such that \( \text{alph}(w') = \text{alph}(w) \), \( w' \preceq w \) and \( \text{min}_{\text{ext}}(w', r) \neq \emptyset \). By Lemma 5.8, to verify whether \( \text{min}_{\text{ext}}(w', r) \neq \emptyset \), we only need to check whether there exists string \( w'' \) such that \( w'' \in \pi(r) \), \( w' \preceq w'' \) and \( |w''| \leq (|w'| + 1) \cdot |r| \). Thus, given that

\[
|\{f(w'') : \text{for every } a \in \text{alph}(r), \#_a(w'') \leq (|w'| + 1) \cdot |r|\}| \\
\leq (\prod_{a \in \text{alph}(w)} |w_a|) \leq (\prod_{a \in \text{alph}(w)} |w_a|) \leq (\prod_{a \in \text{alph}(r)} |w_a|) = |w|^{|\text{alph}(r)|},
\]

we have that the problem of verifying whether \( \text{min}_{\text{ext}}(w', r) \neq \emptyset \) can be solved in time \( O(p((|w'| + 1) \cdot |r|) \cdot (|w'| + 1) \cdot |r| + 1)^{|\text{alph}(r)|}) \). Therefore, given that

\[
|\{f(w') : \text{alph}(w') = \text{alph}(w) \text{ and } w' \preceq w\}| = \\
\prod_{a \in \text{alph}(w)} \#_a(w) \leq \prod_{a \in \text{alph}(w)} |w| \leq \prod_{a \in \text{alph}(r)} |w| = |w|^{|\text{alph}(r)|},
\]

we conclude that the problem of verifying whether \( \text{rep}(w, r) \neq \emptyset \) can be solved in time \( O(|w|^{|\text{alph}(r)|} \cdot p(|w| + 1) \cdot |r| \cdot (|w| + 1) \cdot |r| + 1)^{|\text{alph}(r)|}) \), which is polynomial on \( |w| \) since \( r \) is fixed.

(2) Given that \( r \) is a fixed regular expression, we know by (1) that for every string \( w' \) such that \( \text{alph}(w') = \text{alph}(w) \) and \( w' \preceq w \), set \( \{f(w'') : w'' \in \text{min}_{\text{ext}}(w', r)\} \) can be computed in polynomial time on \( |w'| \leq |w| \). Furthermore, we also know by (1) that the number of \( f(w') \) for strings \( w' \) satisfying the previous condition is polynomial on \( |w| \) and, therefore, it is possible to compute \( \{f(w'') : w'' \in \text{rep}(w, r)\} \) in polynomial time on \( |w| \). By Lemma 5.8 the length of a string in \( \text{rep}(w, r) \) is at most \((|w|+1)\cdot|r|\) and, thus, it is possible to compute \( \max_{\leq} \text{rep}(w, r) \) in polynomial time on \( |w| \). This concludes the proof of the lemma.

**Proof of Lemma 6.6.** Given a fixed data exchange setting, function \text{ChangeReg} can be implemented in polynomial time by Lemma 6.18. Thus, by applying \text{ChangeAtt} and \text{ChangeReg} to \( \text{cps}(T) \) in a depth-first search manner (as shown in Example 6.4), we can compute a terminal chase sequence \( T_0, \ldots, T_n \) for \( T \) in polynomial time. If \( T_n \not\models D_T \), then we know by Lemma 6.15 that there is no solution for \( T \) and, in particular, there is no canonical solution for this tree. If \( T_n \models D_T \), then \( T_n \) is a canonical solution for \( T \).

### 6.2 The intractable case

The following shows that \( C_U \) is the maximal tractable class, and thus completes the classification of finding certain answers and proves the dichotomy theorem.

**Proposition 6.19.** Let \( C \) be an admissible class of regular expressions such that \( C \not\subseteq C_U \). Then \( C \) is strongly \text{coNP}-complete for \( \text{CTQ}\)-queries.

This result is a consequence of the following lemmas, which are proved in the rest of this section.

**Lemma 6.20.** Let \( r \) be a regular expression such that \( c(r) \geq 2 \) and \( C \) an admissible class of regular expressions containing \( r \). Then \( C \) is strongly \text{coNP}-complete for \( \text{CTQ}\)-queries.

Lemma 6.21. Let \( r \) be a non-univocal regular expression such that \( c(r) \leq 1 \) and \( \mathcal{C} \) an admissible class of regular expressions containing \( r \). Then \( \mathcal{C} \) is strongly coNP-complete for CTQ-queries.

Proof of Lemma 6.20. Let \( r \) be a regular expression such that \( c(r) = k \geq 2 \) and \( \mathcal{C} \) be an admissible class of regular expressions containing \( r \). Since \( c(r) = k \), there exists \( a \in \text{alph}(r) \) and \( w \in \text{fixed}_a(r) \) such that \( w = a^k a_1 \cdots a_t \), where \( a_i \in \text{alph}(r) \) and \( a \neq a_i \) (\( i \in [1, t] \)).

To show that \( \mathcal{C} \) is strongly coNP-complete, we define a data exchange setting \((D_S, D_T, \Sigma_{ST})\) and a Boolean CTQ-query \( Q \) such that \( D_S \) is a simple DTD, \( D_T \) is a \( C \)-DTD, \( \Sigma_{ST} \) is a set of fully-specified STDs and 3SAT can be reduced to the complement of \( \text{CERTAIN-ANSWERS}(Q) \), that is, for every propositional formula \( \theta \) in 3-CNF, there exists a PTIME constructible XML tree \( T_\theta \) conforming to \( D_S \) such that \( \theta \) is satisfiable if and only if \( \text{CERTAIN}(Q, T_\theta) = \text{false} \).

Simple DTD \( D_S \) is defined as follows. Let \( E_S = \{ B, C, H, L, I_1, \ldots, I_k, J_1, \ldots, J_t \} \) be a set of element types and \( A_S = \{ \@f, \@s, \@t, \@p, \@n, \@id \} \) a set of attributes. Then \( D_S = (P_S, R_S, B) \) is a DTD over \((E_S, A_S)\), where \( P_S \) is defined as:

\[
P_S(B) = C^n H^* L^* I_1^* \cdots I_k^* J_1^* \cdots J_t^*,
\]

and \( R_S \) is defined as:

\[
R_S(B) = \emptyset, \quad R_S(C) = \{ \@f, \@s, \@t \}, \quad R_S(H) = \{ \@t, \@f \}, \quad R_S(L) = \{ \@p, \@n \},
\]

\[
R_S(I_i) = \{ \@id \}, \text{ for every } i \in [1, k], \quad R_S(J_i) = \{ \@id \}, \text{ for every } i \in [1, t].
\]

In the following example we explain how XML trees conforming to \( D_S \) are used to represent propositional formulae. Let \( \theta \) be 3-CNF formula \((x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4)\). To construct tree \( T_\theta \), first we assign a distinct natural number to each literal, say

\[
x_1 \mapsto 1, \quad x_2 \mapsto 3, \quad x_3 \mapsto 5, \quad x_4 \mapsto 7, \quad \neg x_1 \mapsto 2, \quad \neg x_2 \mapsto 4, \quad \neg x_3 \mapsto 6, \quad \neg x_4 \mapsto 8.
\]

Then we represent each clause of \( \theta \) as a node of type \( C \), being the values of attributes \( \@f, \@s, \@t \) the first, second and third literal of that clause, respectively. For each propositional variable \( x \) in \( \theta \), we use the attributes \( \@p, \@n \) of a node of type \( L \) to store the values assigned to \( x \) and \( \neg x \), respectively. Furthermore, we create a node of type \( H \) and store in its attribute \( \@t \) value 1 (representing true value) and in its attribute \( \@f \) value 0 (representing false value). Finally, for every \( i \in [1, k] \) we create a node of type \( I_i \) with value \( i \) in its attribute \( \@id \), and for every \( j \in [1, t] \) we create a node of type \( J_j \) with value \( j \) in its attribute \( \@id \) (it will become clear why we need these nodes when we define \( D_T \) and \( \Sigma_{ST} \)). Tree \( T_\theta \) for \( \theta = (x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4) \) is shown in Figure 9.

\( C \)-DTD \( D_T \) is defined as follows. Let \( E_T = \{ B, C, H, G \} \cup \text{alph}(r) \) be a set of element types such that \( \{ B, C, H, G \} \cap \text{alph}(r) = \emptyset \), and let \( A_T = \{ \@f, \@s, \@t, \@id, \@e, \@f, \@t \} \) be a set of attributes. Then \( D_T = (P_T, R_T, B) \) is a DTD over \((E_T, A_T)\), where \( P_T \) is defined as:

Finally, the third rule of Σ

The second rule of Σ

Finally, set Σ

In this rule we use symbol \( \land \) to denote a sequence of formulae separated by commas. Indeed, conjunction is not allowed in tree-pattern formulae. Thus, for example, \( \land_{i=2}^{k} a(\@id = u_i, \@e = x') \) is a shorthand for:

To explain the meaning of the previous rule, we considered again tree \( T_\theta \) shown in Figure 9. Let \( i, j \) be a pair of complementary literals in \( T_\theta \), say \( i = 3 \) and \( j = 4 \). The previous rule says that for each of such pair and for each solution \( T' \) for \( T_\theta \),
there should exist a node $v$ of type $G$ in $T'$ having as children the following sequence of nodes:

![Diagram of a tree with nodes labeled by attributes and values]

Thus, $v$ has $k + 2$ children of type $a$. The first of these $a$-nodes has 1 as value of attribute $@id$ and 1 as value of attribute $@e$ since the third rule of $\Sigma_{ST}$ says that for this node $@id = u_1$ and $@e = x$, being $u_1$ and $x$ the values of the attribute $@id$ of the node of type $I_1$ in $T_0$ and the attribute $@t$ of the node of type $H$ in $T_0$, respectively. For the $i$-th ($i \in [2, k]$) $a$-node in the tree shown above, values of attributes $@id$ and $@e$ are $i$ and 0, respectively. For the last two $a$-nodes in this tree, attribute $@t$ takes values 3 and 4, respectively, since STD mentioned above says that there exist children of $v$ having $y = 3$ and $y' = 4$ as values of their attributes $@t$ (formula $a(\exists \ell = y), a(\exists \ell = y')$ above). Furthermore, $v$ also has as children a sequence of nodes of types $a_1, \ldots, a_\ell$, being $i$ the value of attribute $@id$ of the $i$-th node of this sequence.

Let $w'$ be the string of types of the node of $v$ in the tree shown above ($w' = a^k a_1 \cdots a_\ell w^\ell$). Since $w \in \text{fixed}_a(r)$, $w \leq w'$ and $\#_a(w) < \#_a(w')$, we have that $w' \not\in \pi(r)$. Thus, to construct a solution for $T_0$ we need to replace $w'$ by a string $w'' \in \pi(r)$ such that the generated tree continue satisfying $\Sigma_{ST}$ and either $w \leq w''$ and $\#_a(w) = \#_a(w'')$ or $w \not\leq w''$. The latter case is not possible since the first $k$ children of $v$ of type $a$ have pairwise distinct values in attribute $@id$ and the sequence of children of $v$ of types $a_1, \ldots, a_\ell$ have also pairwise distinct values in attribute $@id$ (recall that $a_i \neq a$, for every $i \in [1, \ell]$). Thus, we have to construct a string $w''$ from $w'$ such that $w \leq w''$ and $\#_a(w) = \#_a(w'')$. Given that the first $k$ children of $v$ of type $a$ have pairwise distinct values in attribute $@id$, the only way to do this is to remove the last two children of $v$ of type $a$ and choose among the first $k$ $a$-nodes where to place 3 and 4 as values of attribute $@t$. For example, Figure 10 shows a possible way of constructing string $w''$, where 3 and 4 are the values of attribute $@e$ of the last and the first node of type $a$, respectively. In this figure, dots next to the node of type $a_\ell$ represent the fact that $v$ can have some extra children not of type $a$.

We observe that when choosing where to place values 3 and 4, we are actually choosing the truth values for $x_2$ and $\neg x_2$. For example, in the solution for $T_0$ shown in Figure 10, we have chosen value 1 for $\neg x_2$ since 4 is the value of attribute $@t$ of a node with value distinct from 0 in attribute $@e$, and we have chosen value 0 for $x_2$ since 3 is the value of attribute $@t$ of a node with value 0 in attribute $@e$. We will use this property to prove that $\theta$ is satisfiable if and only if $\text{certain}(Q, T_0) = \text{false}$. It is worth mentioning that if $k > 2$, then it is possible to choose value 0 for both $x_2$ and $\neg x_2$. After defining query $Q$, we will show that this alternative does not cause any problems.
Boolean $CTQ$-query $Q$ is defined as:

$$\exists x \exists y \exists z \exists u \ B(C(\overline{a} f = x, \overline{a} s = y, \overline{a} t = z), H(\overline{a} f = u),$$

$$G[a(\overline{a} e = u, \overline{a} t = x)], G[a(\overline{a} e = u, \overline{a} t = y)], G[a(\overline{a} e = u, \overline{a} t = z)].$$

Intuitively, query $Q$ says that there exists a node $v$ of type $C$ such that each “literal” of $v$ is assigned value 0, that is, the values $i_1, i_2, i_3$ of the attributes $a f, a s, a t$ of $v$, respectively, are such that for every $i \in \{i_1, i_2, i_3\}$, there exists a node $v'$ of type $a$ such that $0, i$ are the values of attributes $a e, a t$ of $v'$, respectively.

Now we prove that for every 3-CNF propositional formula $\theta$, we have that $\theta$ is satisfiable if and only if $\text{certain}(Q, T_{θ}) = false$, where $T_{θ}$ is constructed from $\theta$ in $\text{PTIME}$ as shown above.

($\Rightarrow$) Assume that $\theta$ is satisfiable and let $\sigma$ be a truth assignment satisfying $\theta$. Define a solution $T'$ for $T_{θ}$ as follows. The structure of the $C$- and $H$-nodes of $T'$ is copied from $T_{θ}$. For every propositional variables $x$ in $\theta$, we define a $G$-node $v$ of $T'$ as follows. The string of types of the children of $v$ is $w$. The values of attributes $a id$ and $a e$ of the children of $v$ are assigned as shown above. If $\sigma(x) = 1$, then the value assigned to $x$ in $T_{θ}$ is the value of the attribute $a t$ of the first child of $v$ of type $a$, which has value 1 in attribute $a e$, and the value assigned to $\overline{x}$ in $T_{θ}$ is the value of the attribute $a t$ of the second child of $v$ of type $a$, which has value 0 in attribute $a e$. Otherwise, $\sigma(x) = 0$ and the value assigned to $\overline{x}$ in $T_{θ}$ is the value of the attribute $a t$ of the first child of $v$ of type $a$, and the value assigned to $x$ in $T_{θ}$ is the value of the attribute $a t$ of the second child of $v$ of type $a$.

It is straightforward to prove that $T'$ conforms to $D_T$ and satisfies $\Sigma_{ST}$. Furthermore, $T' \not\models Q$ since $\sigma$ satisfies $\theta$ and, therefore, at least one literal per clause $C$ is not assigned value 0. We conclude that $\text{certain}(Q, T_{θ}) = false$ since $T'$ is a solution for $T_{θ}$.

($\Leftarrow$) Assume that $\text{certain}(Q, T_{θ}) = false$ and let $T'$ be a solution for $T_{θ}$ such that $T' \not\models Q$. We define a truth assignment for the propositional variables of $\theta$ as follows. For every clause in $\theta$, find a $C$-node $v$ of $T'$ such that the values $i_1, i_2, i_3$ of attributes $a f, a s, a t$ of $v$ are the values assigned in $T_{θ}$ to the literals of that clause. Since $T' \not\models Q$, there exists $i \in \{i_1, i_2, i_3\}$ such that for every node $v'$ of type $a$ with value 0 in its attribute $a e$, we have that $i$ is not the value of attribute $a t$ of $v'$. If $i$ corresponds to a positive literal $x$, then define $\sigma(x)$ as 1. If $i$ corresponds to a negative literal $\overline{x}$, then define $\sigma(x)$ as 0 ($\sigma(\overline{x}) = 1$)

Fig. 10. A solution $T'$ for source tree $T_{θ}$. Jump to page 47.
We show that $\sigma$ is well defined. On the contrary, assume that there exists a propositional variable $x$ such that 1 was assigned to both $\sigma(x)$ and $\neg x$. Let $i$, $j$ be the values assigned in $T_0$ to $x$ and $\neg x$. Then for every node $v'$ of type $a$ with value 0 in its attribute $@e$, we have that $i$ is not the value of attribute $@\ell$ of $v'$. Let $v''$ be a $G$-node of $T'$ that satisfies the left hand side of the third rule of $\Sigma_{ST}$ instantiated on the following values from $T_0$:

$$B[H(@t = 1, @f = 0), L(@p = i, @n = j), \bigwedge_{i=1}^{k} I_i(\@id = i), \bigwedge_{j=1}^{l} J_j(\@id = j)].$$

This node has as children two distinct $a$-nodes $v_1, v_2$ with values $i, j$ in attribute $@\ell$, respectively. Since $i$ must be the value of attribute $@\ell$ of a child of $v''$ of type $a$ with value distinct from 0 in attribute $@e$, and there is exactly one child of $v''$ satisfying this condition (with value 1 in attribute $@e$), we have that the value of attribute $@e$ of $v_2$ is 0. Thus, there exists a node $v'$ of type $a$ such that 0, $j$ are the values of attributes $@e$, $@\ell$ of $v'$, respectively, and, therefore, 1 is not assigned to $\neg x$, which contradicts our original assumption.

Since $\sigma$ is well defined and $\sigma$ satisfies $\theta$ (by definition of $\sigma$), we conclude that $\theta$ is satisfiable. This concludes the proof Lemma 6.20.

**Proof of Lemma 6.21.** Assume that $C$ is an admissible class of regular expressions containing a non-univocal regular expression $r$ such that $c(r) \leq 1$, and assume that $\text{alph}(r) = \Sigma$.

Since $r$ is not a univocal regular expression, there exists $w \in \Sigma^*$ such that $w \not\in \pi(r)$, $\text{rep}(w, r) \neq \emptyset$ and $\text{rep}(w, r)$ does not have a maximum element with respect to $\preceq_w$, that is, there exist $w_1, \ldots, w_n$ in $\text{rep}(w, r)$ ($n \geq 2$) such that (1) for every $w' \in \text{rep}(w, r)$, there exists $i \in [1, n]$ such that $w' \preceq_w w_i$, and (2) for every $i, j \in [1, n], i \neq j$, we have that $w_i \not\preceq_w w_j$. Furthermore,

**Claim 6.22.** If $w' \in \pi(r)$ is such that $\text{alph}(w) \subseteq \text{alph}(w')$, then there exists $i \in [1, n]$ such that $w' \preceq_w w_i$.

The proof of Claim 6.22 can be found in the appendix. To prove the lemma, we consider three cases.

(I) First, assume that there exists distinct $i, j \in [1, n]$ such that $w \preceq w_i$ and $w \preceq w_j$. Without loss of generality, assume that $i = 1$ and $j = 2$. Define $I = \{i \in [2, n] \mid w \preceq w_i\}$ and for every $i \in I \cup \{1\}$, define $X(w_i)$ as $\text{alph}(w_i) \setminus \text{alph}(w)$. Furthermore, define $Y$ as

$$Y = \left( \bigcup_{i \in I} X(w_i) \right) \setminus X(w_1).$$

Since $w_2 \not\preceq_w w_1$, there exists $a_0 \in X(w_1)$ such that $a_0 \not\in X(w_2)$. Given that $w_1 \not\preceq_w w_i$ ($i \in I$), there exists $b \in X(w_i)$ such that $b \not\in X(w_1)$. Thus, by definition of $Y$, we conclude that $Y \cap X(w_1) = \emptyset$ and $X(w_i) \cap Y \neq \emptyset$, for every $i \in I$.

To show that $C$ is strongly coNP-complete, we define a data exchange setting $(D_S, D_T, \Sigma_{ST})$ and a Boolean CTQ-query $Q$ such that $D_S$ is a simple DTD, $D_T$ is a $C$-DTD, $\Sigma_{ST}$ is a set of fully-specified STDs and $3SAT$ can be reduced to the

complement of \textsc{Certain-Answers}(Q), that is, for every propositional formula $\theta$ in 3-CNF, there exists a PTIME constructible XML tree $T_\theta$ conforming to $D_S$ such that $\theta$ is satisfiable if and only if $\text{certain}(Q, T_\theta) = \text{false}$. Simple DTD $D_S$ is defined as follows. Let $k = \max\{\#_b(w) | b \in \text{alph}(w)\}$, $E_S = \{B, C, L, I_1, \ldots, I_k\}$ be a set of element types and $A_S = \{@f, @s, @t, @p, @n, @id\}$ be a set of attributes. Then $D_S = (P_S, R_S, B)$ is a DTD over $(E_S, A_S)$, where $P_S$ is defined as:

$$P_S(B) = C^*L^*I_1^*\ldots I_k^*,$$

and $R_S$ is defined as:

$$R_S(B) = \emptyset, \quad R_S(C) = \{@f, @s, @t\}, \quad R_S(I_i) = \{@id\}, \quad \text{for every } i \in [1, k].$$

XML trees conforming to $D_S$ are used to represent propositional formulas. Let $\theta$ be 3-CNF formula $(x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4)$. To construct tree $T_\theta$, first we assign a distinct natural number to each literal, say

$$x_1 \mapsto 1, \quad x_2 \mapsto 3, \quad x_3 \mapsto 5, \quad x_4 \mapsto 7, \quad \text{(4)}$$

Then we represent each clause of $\theta$ as a node of type $C$, being the values of attributes $@f, @s, @t$ the first, second and third literal of that clause, respectively. For each propositional variable $x$ in $\theta$, we use the attributes $@p, @n$ of a node of type $L$ to store the values assigned to $x$ and $\neg x$, respectively. Finally, for every $i \in [1, k]$ we create a node of type $I_i$ with value $i$ in its attribute @id (it will become clear why we need these nodes when we define $D_T$ and $\Sigma_{ST}$). Tree $T_\theta$ for the formula defined above is shown in Figure 11.

C-DTD $D_T$ is defined as follows. Let $E_T = \{B, C\} \cup \{G_i | i \in [1, 8]\} \cup \text{alph}(r)$ be a set of element types such that $(\{B, C\} \cup \{G_i | i \in [1, 8]\}) \cap \text{alph}(r) = \emptyset$, and let $A_T = \{@f, @s, @t, @id, @c, @e, @id\}$ be a set of attributes. Then $D_T = (P_T, R_T, B)$ is a DTD over $(E_T, A_T)$, where $P_T$ is defined as:

$$P_T(B) = G_1^*C^*, \quad P_T(G_1) = G_2^2G_3^*, \quad P_T(G_2) = G_4^4G_5^5,$$

$$P_T(G_4) = G_7^7, \quad P_T(G_7) = G_8^8, \quad P_T(G_8) = \varepsilon,$$

$$P_T(G_5) = r, \quad P_T(\ell) = \varepsilon, \quad \text{for every } \ell \in \text{alph}(r), \quad P_T(G_3) = G_6^6,$$

$$P_T(G_6) = \varepsilon, \quad P_T(C) = \varepsilon.$$

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and \( R_T \) is defined as:

\[
\begin{align*}
R_T(B) &= \emptyset, \quad R_T(G_1) = \{ @e \}, \\
R_T(G_2) &= \{ @e \}, \quad R_T(G_4) = \emptyset, \\
R_T(G_7) &= \emptyset, \quad R_T(G_8) = \{ @c \}, \\
R_T(G_3) &= \emptyset, \quad R_T(\ell) = \emptyset, \quad \text{for every } \ell \in \text{alph}(r) \setminus \{ a_0 \} \cup Y \cup \text{alph}(w), \\\nR_T(G_8) &= \emptyset, \quad R_T(\ell) = \{ @id \}, \quad \text{for every } \ell \in \text{alph}(w), \\\nR_T(G_5) &= \emptyset, \quad R_T(\ell) = \{ @d \}, \quad \text{for every } \ell \in Y, \\\nR_T(G_6) &= \{ @d \}, \quad R_T(C) = \{ @f, @s, @t \}.
\end{align*}
\]

Finally, the set \( \Sigma_{ST} \) of fully-specified STDs is defined as follows. The first rule of \( \Sigma_{ST} \) is defined as:

\[
B[C(@f = x, @s = y, @t = z)] :– B[C(@f = x, @s = y, @t = z)].
\]

This rule says that every node of type \( C \) in a source tree \( T \) must appear in every solution for \( T \). The second rule of \( \Sigma_{ST} \) is defined as follows:

\[
B[G_1(@e = x)]G_2(@e = y)]G_4[G_7[G_8]], \ G_5[ \bigwedge_{b \in \text{alph}(w)} b(@id = u_i)], \ G_3[G_6] :– B[L(@p = x, @n = y), \bigwedge_{i=1}^k I_i(@id = u_i)].
\]

As in the proof of Lemma 6.20, we use symbol \( \bigwedge \) to denote a sequence of formulae separated by commas. Indeed, conjunction is not allowed in tree-pattern formulae. Thus, for example, \( \bigwedge_{i=1}^{\#(w)} b(@id = u_i) \) denotes formula \( b(@id = u_1), \ldots, b(@id = u_{\#(w)}) \). To explain the meaning of this rule, we considered again tree \( T_\theta \) shown in Figure 11. Assuming that \( w = a_1 \cdots a_p \) \((p \geq 0)\), the previous rule says that for each pair of complementary literals, say \((3, 4)\), and for each solution \( T' \) for \( T_\theta \), there should exist a node \( v_1 \) of type \( G_1 \) in \( T' \) having the following descendants:

In this figure, assume that \( v_i \) \((i \in [1, 8])\) is the identifier of the node of type \( G_i \). Node \( v_1 \) has an attribute \( @e \) with value 3 and it has two children, node \( v_2 \) of type \( G_2 \) and node \( v_3 \) of type \( G_3 \). Node \( v_2 \) has an attribute \( @e \) with value 4 and it has...
two children, node \( v_4 \) of type \( G_4 \) and node \( v_5 \) of type \( G_5 \). Let \( b \in \text{alph}(w) \). Node \( v_5 \) has \( \#_b(w) \) children of this type. Furthermore, these \( b \)-nodes are assigned pairwise distinct values in attribute \( @\text{id} \), taken from attribute \( @\text{id} \) of the nodes of type \( I_1, \ldots, I_k \) in \( T_\theta \). We observe that if \( w = \varepsilon \), then \( v_5 \) has no children.

Since \( w \notin \pi(r) \), to construct a solution \( T' \) for \( T_\theta \) we need to replace \( w \) by a string \( w' \in \pi(r) \) such that the generated tree continue satisfying \( \Sigma_{ST} \). By Claim 6.22, we know that there exists \( i \in [1, n] \) such that \( w' \preceq_w w_i \). First assume that \( i = 1 \). Then, by definition of \( \preceq_w \), we have that \( a_0 \in \text{alph}(w') \) and, therefore, the generated solution is of the form shown in Figure 12 (a). Second, assume that \( i \neq 1 \). Since the children of \( v \) of type \( b \) (\( b \in \text{alph}(w) \)) have pairwise distinct values in attribute \( @\text{id} \), we cannot remove any of these nodes in order to construct a solution for \( T' \). Thus, \( w \preceq w' \) and, therefore, \( w \preceq w_i \). We conclude that \( i \in I \). Given that \( w' \preceq_w w_i \), there exists \( b \in Y \) such that \( b \in \text{alph}(w') \) and, hence, the generated solution is of the form shown in Figure 12 (b).

We note that when choosing whether to replace \( w \) by either a string contained in \( w_1 \) or a string contained in \( w_i \) (\( i \in I \)), we are actually choosing the truth values for \( x_2 \) and \( \neg x_2 \). We say that a literal \( j \) has been assigned value 0 if \( j \) is the value of attribute \( @\text{c} \) of a node \( v \) having the following descendants:
That is, \( v \) has a “great-grandchild” \( u_5 \) with an attribute \( @c \) and it has a “grandchild” \( u_4 \) with an attribute \( @d \). For example, in the solution for \( T_0 \) shown in Figure 13 (a), we have chosen value 0 for \( x_3 \) since 3 is the value of attribute \( @e \) of a node (of type \( G_1 \)) having a “great-grandchild” (of type \( a_0 \)) with an attribute \( @c \) and having a “grandchild” (of type \( G_6 \)) with an attribute \( @d \). On the other hand, in the solution for \( T_0 \) shown in Figure 13 (b), we have chosen value 0 for \( \neg x_3 \) since 4 is the value of attribute \( @e \) of a node (of type \( G_2 \)) having a “great-grandchild” (of type \( G_8 \)) with an attribute \( @c \) and having a “grandchild” (of type \( b \)) with an attribute \( @d \). It is worth mentioning that it is possible to choose value 0 for both \( x_3 \) and \( \neg x_3 \). After defining query \( Q \), we will show that this alternative does not cause any problems. From now on, we say that a node \( v \) is a \((@c, @d)\)-node if \( v \) has a “great-grandchild” with an attribute \( @c \) and it has a “grandchild” with an attribute \( @d \). Thus, we say that we have chosen value 0 for a propositional variable \( x \) if there exists a \((@c, @d)\)-node \( v \) having in attribute \( @c \) the value assigned to \( x \) in \( T_0 \).

Boolean \( CT \)-query \( Q \) is defined as:

\[
\exists x \exists y \exists z \exists u_1 \exists u_2 \exists u_3 \exists v_1 \exists v_2 \exists v_3 \ \{ C(\neg f = x, @s = y, @t = z) \land \neg(@c = x) \land \neg([\neg(@c = u_1)] \land ([\neg(@d = v_1)] \land \neg(@c = y) \land ([\neg(@c = u_2)] \land ([\neg(@d = v_2)] \land \neg(@c = z) \land ([\neg(@c = u_3)] \land ([\neg(@d = v_3)]).
\]

Intuitively, query \( Q \) says that there exists a node \( v \) of type \( C \) such that each “literal” of \( v \) is assigned value 0, that is, the values \( i_1, i_2, i_3 \) of the attributes \( @f, @s, @t \) of \( v \), respectively, are such that for every \( i \in \{i_1, i_2, i_3\} \), there exists a \((@c, @d)\)-node \( v' \) having \( i \) as value of attribute \( @c \).

Now we prove that for every 3-CNF propositional formula \( \theta \), we have that \( \theta \) is satisfiable if and only if \( \text{certain}(Q,T_0) = false \), where \( T_0 \) is constructed from \( \theta \) in \( \text{PTIME} \) as shown above.

(\( \Rightarrow \)) Assume that \( \theta \) is satisfiable and let \( \sigma \) be a truth assignment satisfying \( \theta \). Define a solution \( T' \) for \( T_0 \) as follows. The structure of the \( C \)-nodes of \( T' \) is copied from \( T_0 \). For every propositional variables \( x \) in \( \theta \), we define a \( G_1 \)-node \( v_1 \) of \( T' \) as follows. Node \( v_1 \) has the value assigned to \( x \) in \( T_0 \) in attribute \( @c \) and it has two children, node \( v_2 \) of type \( G_2 \) and node \( v_3 \) of type \( G_3 \). Node \( v_3 \) has only one child (of type \( G_5 \)). Node \( v_2 \) has the value assigned to \( \neg x \) in \( T_0 \) in attribute \( @c \) and it has two children, node \( v_4 \) of type \( G_4 \) and node \( v_5 \) of type \( G_5 \). Node \( v_4 \) has only one child (of type \( G_7 \), which in turn has only one child (of type \( G_8 \). The sequence of children of \( v_5 \) is defined as follows. If \( \sigma(x) = 0 \), then the string of types of the children of \( v_5 \) is \( w_1 \). For every \( b \in \text{alph}(w) \), exactly \#_b(w) children of \( v_5 \) of type \( b \) are assigned pairwise distinct values in attribute \( @id \), taken from attribute \( @id \) of the nodes of type \( I_1, \ldots, I_k \) in \( T_0 \). Furthermore, attributes with fresh null values are added to the descendants of \( v_1 \) according to \( R_T \). We note that in this case we have assigned value 0 to \( \sigma(x) \) since the value assigned to \( x \) in \( T_0 \) is the value of attribute \( @e \) of a \((@c, @d)\)-node (of type \( G_1 \)). We also note that in this case we have not assigned value 0 to \( \sigma(\neg x) \). If \( \sigma(x) = 1 \), then the string of types of the children of \( v_5 \) is \( w_2 \). For every \( b \in \text{alph}(w) \), exactly \#_b(w) children of \( v_5 \) of type \( b \) are assigned pairwise distinct values in attribute \( @id \), taken from attribute \( @id \) of
the nodes of type $I_1, \ldots, I_k$ in $T_\theta$. Furthermore, attributes with fresh null values are added to the descendants of $v$ according to $R_T$. We note that in this case we have assigned value 0 to $\sigma(\neg x)$ since the value assigned to $\neg x$ in $T_\theta$ is the value of attribute $@c$ of a $(@c, @d)$-node (of type $G_2$). We also note that in this case we have not assigned value 0 to $\sigma(x)$. It is straightforward to prove that $T'$ conforms to $D_T$ and satisfies $\Sigma_{ST}$. Furthermore, $T' \not\models Q$ since $\sigma$ satisfies $\theta$ and, therefore, at least one literal per clause $C$ is not assigned value 0. We conclude that certain($Q, T_\theta$) = false since $T'$ is a solution for $T_\theta$.

(⇐) Assume that certain($Q, T_\theta$) = false and let $T'$ be a solution for $T_\theta$ such that $T' \not\models Q$. We define a truth assignment for the propositional variables of $\theta$ as follows. For every clause in $\theta$, find a $C$-node $v$ of $T'$ such that the values $i_1, i_2, i_3$ of attributes $@f, @s, @t$ of $v$ are the values assigned in $T_\theta$ to the literals of that clause. Since $T' \not\models Q$, there exists $i \in \{i_1, i_2, i_3\}$ such that no $(@c, @d)$-node $v'$ has $i$ as value of attribute $@c$. If $i$ corresponds to a positive literal $x$, then define $\sigma(x)$ as 1. If $i$ corresponds to a negative literal $\neg x$, then define $\sigma(x)$ as 0. We will show that $\sigma$ is well defined. On the contrary, assume that there exists a propositional variable $x$ such that 1 was assigned to $\sigma(x)$ and $\sigma(\neg x)$. Let $i, j$ be the values assigned in $T_\theta$ to $x$ and $\neg x$. Then no $(@c, @d)$-node $v'$ has $j$ as value of attribute $@c$. Let $v_1$ be a $G$-node of $T'$ that satisfies the left hand side of the second rule of $\Sigma_{ST}$ instantiated on the following values from $T_\theta$:

$$B[L(\@p = i, \@n = j), \bigwedge_{i=1}^k I_i(\@id = i)].$$

Then $v_1$ has a child of type $G_2$, which in turn has a child of type $G_3$. Let $v_5$ be the identifier of this node and $w' = \lambda_{T'}(\text{children}(v_5))$. Since no $(@c, @d)$-node $v'$ has $j$ as value of attribute $@c$, we have that alph($w'$) $\cap$ $Y = \emptyset$. Thus, by Claim 6.22, we conclude that $w' \preceq_w w_1$ and, therefore, $a_0 \in$ alph($w'$). But $@c \in R_T(a_0)$ and, hence, $v_1$ is a $(@c, @d)$-node having $i$ as value of attribute $@c$. We conclude that there exists a $(@c, @d)$-node having $i$ as value of attribute $@c$, which contradicts the fact that 1 was assigned to $\sigma(x)$.

Since $\sigma$ is well defined and $\sigma$ satisfies $\theta$ (by definition of $\sigma$), we conclude that $\theta$ is satisfiable. This concludes the proof of case (I).

(II) Second, assume that there exists distinct $i, j \in [1, n]$ and $a \in$ alph($w$) such that (1) $\#_a(w_1) < \#_a(w)$ and (2) for every $b \in$ alph($w$), we have that $\#_b(w_1) \leq \#_b(w_j)$ or $\#_b(w_j) \geq \#_b(w)$. Without loss of generality, assume that $i = 1$ and $j = 2$. Here, we consider two sub-cases.

(II.1) Assume that for every $b \in$ alph($w$) such that $\#_b(w_1) < \#_b(w)$, we have that $\#_b(w_1) = \#_b(w_2)$. Given that $w_1 \not\preceq_w w_2$, there exist $b \in$ alph($w_2$) \ alph($w$) such that $b \in$ alph($w_1$), and given that $w_2 \not\preceq_w w_1$, there exist $c \in$ alph($w_1$) \ alph($w$) such that $c \in$ alph($w_2$).

Let $w'$ be a string such that: alph($w'$) = alph($w$) and $\#_b(w') = \min\{\#_b(w_1), \#_b(w)\}$, for every $b \in$ alph($w'$). We note that $w' \not\in \pi(r)$ since $w_1 \preceq_w w'$ and $w' \not\preceq_w w_1$ ($c \in$ alph($w_1$) and $c \not\in$ alph($w$)). Since $w_1 \in \text{rep}(w, r)$,
there exists string $s \preceq w$ such that $w_1 \in \text{min} \_ \text{ext}(s, r)$. Then $s \preceq w'$. On the contrary, assume that $s \not\preceq w'$. Hence, given that $s \preceq w$, there exists $d \in \text{alph}(w)$ such that $\#_d(w') < \#_d(s)$, which contradicts the fact that $s \preceq w_1$. Given that $s \preceq w'$, we have that $\#_d(w_1) = \#_d(w') < \#_d(s)$, which contradicts the fact that $s \preceq w_1$. Thus, $w_1 \in \text{min} \_ \text{ext}(w', r)$. We conclude that $w_1 \in \text{rep}(w', r)$. Similarly, we conclude that $w_2 \in \text{rep}(w', r)$.

Now we show that $w_1 \in \max \_ \preceq \text{rep}(w', r)$. On the contrary, assume that there exists $s' \in \text{rep}(w', r)$ such that $w_1 \preceq_w s'$. Given that $w_1 \preceq_w s'$, we have that $\#_d(s') = \#_d(s') \leq \#_d(s')$. Furthermore, given that $w_1 \preceq_w s'$, we have that $\text{alph}(s') \subseteq \text{alph}(w') \subseteq \text{alph}(w_1) \setminus \text{alph}(w')$. Thus, given that $\text{alph}(w') = \text{alph}(w)$, we conclude that $w_1 \preceq_w s'$. Since $\text{alph}(w) \subseteq \text{alph}(s')$, by Claim 6.22 we have that $s' \preceq_w w_1$ (for all $i \in [1, n]$). If we assume that $i = 1$, then $\text{alph}(w_1) \setminus \text{alph}(w) \subseteq \text{alph}(s') \setminus \text{alph}(w)$ and, therefore, $\text{alph}(w_1) \setminus \text{alph}(w') \subseteq \text{alph}(s') \setminus \text{alph}(w')$. Thus, given that $w' \preceq_w w_1$, we conclude that $s' \preceq_w w_1$, which contradicts our assumption that $w_1 \preceq_w s'$. Thus, $s' \preceq_w w_1$, where $i \neq 1$. Given that $w_1 \preceq_w s'$, we conclude that $w_1 \preceq_w w_1$, which contradicts our original assumption. Thus, $w_1 \in \max \_ \preceq \text{rep}(w', r)$ and, similarly, $w_2 \in \max \_ \preceq \text{rep}(w', r)$.

Given that there exist $b \in \text{alph}(w_2) \setminus \text{alph}(w)$ such that $b \not\in \text{alph}(w_1)$ and there exist $c \in \text{alph}(w_1) \setminus \text{alph}(w)$ such that $c \not\in \text{alph}(w_2)$, we have that $w_1 \preceq_w w_2$ and $w_2 \preceq_w w_1$. Thus, given that $w' \not\in \pi(r)$, $w_1 \in \max \_ \preceq \text{rep}(w', r)$, $w_2 \in \max \_ \preceq \text{rep}(w', r)$, $w' \preceq w_1$ and $w' \preceq w_2$, we have that $w'$ is a string satisfying case (I) of this proof. Hence, we use case (I) to prove that $\mathcal{C}$ is strongly coNP-complete.

(II.2) Assume that there exists $a_0 \in \text{alph}(w)$ such that $\#_{a_0}(w_1) < \#_{a_0}(w)$ and $\#_{a_0}(w_1) < \#_{a_0}(w_2)$. Since $w_1 \preceq_w w_2$, we have that there exists $b \in \text{alph}(w_2) \setminus \text{alph}(w)$ such that $b \not\in \text{alph}(w_1)$. Let $X$ be set of all such elements, that is, $X = \{b \in \text{alph}(r) \mid \text{there exists } i \in [2, n] \text{ such that } b \in \text{alph}(w_i) \setminus \text{alph}(w) \text{ and } b \not\in \text{alph}(w_1)\}$. Then $X \neq \emptyset$.

To show that $\mathcal{C}$ is strongly coNP-complete, we define a data exchange setting $(D_\mathcal{S}, D_T, \Sigma_{ST})$ and a Boolean CTQ-query $Q$ such that $D_\mathcal{S}$ is a simple DTD, $D_T$ is a C/DTD, $\Sigma_{ST}$ is a set of fully-specified STDs and 3SAT can be reduced to the complement of Certain-Answers($Q$), that is, for every propositional formula $\theta$ in 3-CNF, there exists a PTIME constructible XML tree $T_\theta$ conforming to $D_\mathcal{S}$ such that $\theta$ is satisfiable if and only if Certain($Q, T_\theta$) = false. Simple DTD $D_T$ is defined as follows. Let $k = \max\{\#_b(w_1) \mid b \in \text{alph}(w)\}$, $E_\mathcal{S} = \{B, C, L, I_1, \ldots, I_k\}$ be a set of element types and $A_\mathcal{S} = \{\#f, \#s, \#t, \#p, \#n, \#id\}$ be a set of attributes. Then $D_\mathcal{S} = (P_\mathcal{S}, R_\mathcal{S}, B)$ is a DTD over $(E_\mathcal{S}, A_\mathcal{S})$, where $P_\mathcal{S}$ is defined as:

\[ P_\mathcal{S}(B) = C^* L_1^* \cdots L_k^*, \]

\[ P_\mathcal{S}(\ell) = \varepsilon, \text{ for every } \ell \in E_\mathcal{S} \setminus \{B\}. \]

and $R_\mathcal{S}$ is defined as:

\[ R_\mathcal{S}(B) = \emptyset, \]

\[ R_\mathcal{S}(L) = \{\#p, \#n\}, \]

\[ R_\mathcal{S}(C) = \{\#s, \#t\}, \]

\[ R_\mathcal{S}(I_i) = \{\#id\}, \text{ for every } i \in [1, k]. \]
XML trees conforming to $D_S$ are used to represent propositional formulae exactly as in case (I). Assume that $\theta$ and $T_\theta$ are as shown in Figure 11, where variables $x_1$, $x_2$, $x_3$, $x_4$ and their negations have been assigned the same values as in case (I) (see equation (4)).

C-DTD $D_T$ is defined as follows. Let $E_T = \{B, G, C, N, F\} \cup \text{alph}(r)$ be a set of element types such that $\{B, G, C, N, F\} \cap \text{alph}(r) = \emptyset$, and let $A_T = \{\@f, \@s, \@t, \@id, \@c\}$ be a set of attributes. Then $D_T = (P_T, R_T, B)$ is a DTD over $(E_T, A_T)$, where $P_T$ is defined as:

$$P_T(B) = G^*C^*, \quad P_T(G) = r, \quad P_T(\ell) = \varepsilon, \quad \text{for every } \ell \in \text{alph}(r) \setminus \{a_0\},$$

$$P_T(a_0) = N^*F^*, \quad P_T(N) = \varepsilon, \quad P_T(F) = \varepsilon,$$

and $R_T$ is defined as:

$$R_T(B) = \emptyset, \quad R_T(C) = \{\@f, \@s, \@t\},$$

$$R_T(G) = \emptyset, \quad R_T(\ell) = \{\@id\}, \quad \text{for every } \ell \in \text{alph}(w) \setminus \{a_0\}$$

$$R_T(a_0) = \{\@id, \@c\}, \quad R_T(\ell) = \{\@f\}, \quad \text{for every } \ell \in X,$$

$$R_T(N) = \{\@c\}, \quad R_T(\ell) = \emptyset, \quad \text{for every } \ell \in \text{alph}(r) \setminus (X \cup \text{alph}(w)),$$

$$R_T(F) = \{\@f\}.$$

Finally, set $\Sigma_{ST}$ of fully-specified STDs is defined as follows. The first rule of $\Sigma_{ST}$ is defined as follows:

$$B[C(\@f = x, \@s = y, \@t = z)] :– B[C(\@f = x, \@s = y, \@t = z)].$$

This rule says that every node of type $C$ in a source tree $T$ must appear in every solution for $T$. The second rule of $\Sigma_{ST}$ is defined as (we use $\bigwedge$ to denote a sequence of formulae separated by commas, as in case (I)):

$$B[G \bigwedge_{b \in \text{alph}(w) \setminus \{a_0\}} \bigwedge_{i=1}^{n_b} b(\@id = u_i), \bigwedge_{i=n_b+1}^{\#b(w)} b, \bigwedge_{i=1}^{\#a_0(w)} a_0(\@id = u_i, \@c = x)[F], \bigwedge_{i=n_{a_0}+1}^{\#a_0(\@c = y)} a_0[N(\@c = y)]]] :– B[L(\@p = x, \@n = y), \bigwedge_{i=1}^{k} I_i(\@id = u_i)],$$

where $n_b = \min\{\#b(w), \#b(w_1)\}$, for every $b \in \text{alph}(w)$. In particular, $n_{a_0} = \min\{\#a_0(w), \#a_0(w_1)\} = \#a_0(w_1)$.

To explain the meaning of the previous rule, we considered again tree $T_\theta$ shown in Figure 11. Assuming that $w = a_0^{\#a_0(w)} a_1 \cdots a_p$, where $a_i \neq a_0$ ($i \in [1, p]$), the previous rule says that for each pair of complementary literals, say $(3, 4)$, and for each solution $T'$ for $T_\theta$, there should exist a node $v$ of type $G$ in $T'$ having the following descendants.
In this tree, \( v \) has \#_{a_0}(w) \) children of type \( a_0 \). The first \( n_{a_0} \) of these children are defined as follows. Let \( i \in [1, n_{a_0}] \). Then the \( i\)-th child of \( v \), from left to right, of type \( a_0 \) has a child of type \( F \) and it has \( i \) as value of attribute \( @id \) and 3 as value of attribute \( @e \) since the second rule of \( \Sigma_{\text{ST}} \) says that for this node \( @id = u_i \) and \( @e = x \), being \( u_i \) and \( x \) the values of attribute \( @id \) of the node of type \( I_i \) in \( T_0 \) and attribute \( @p \) of a node of type \( L \) in \( T_0 \), respectively. The remaining \((\#_{a_0}(w) - n_{a_0})\) children of \( v \) of type \( a_0 \) are defined as follows. Let \( i \in [n_{a_0} + 1, \#_{a_0}(w)] \). Then the \( i\)-th child of \( v \) of type \( a_0 \) has as child a node of type \( N \) having 4 as value of attribute \( @e \). Moreover, for every \( b \in \text{alph}(w) \setminus \{a_0\} \), the first \( n_b \) children of \( v \) of type \( b \) have pairwise distinct values in attribute \( @id \). Since \( w \not\in \pi(r) \), to construct a solution \( T' \) for \( T_0 \) we need to replace \( w \) by a string \( w' \in \pi(r) \) such that the generated tree continue satisfying \( \Sigma_{\text{ST}} \). By Claim 6.22, we know that there exists \( i \in [1, n] \) such that \( w' \preceq_w w_i \). First assume that \( i = 1 \). Then, by definition of \( \preceq_w \), we have that \#_{a_0}(w') \leq \#_{a_0}(w_i) = n_{a_0}. \) Thus, given that the first \( n_{a_0} \) children of \( v \) of type \( a_0 \) have pairwise distinct values in attribute \( @id \), to construct \( w' \) from \( w \) we have to remove the last \((\#_{a_0}(w) - n_{a_0})\) children of \( v \) of type \( a_0 \) and choose among the first \( n_{a_0} \) nodes of this type where to place the descendants of the removed \( a_0 \)-nodes. For example, we can make them children of the first \( a_0 \)-node of \( w \), generating the subtree shown in Figure 13 (a). Second, assume that \( i \neq 1 \) and let \( s \) be a string such that \( \text{alph}(s) = \text{alph}(w) \) and \#_{b}(s) = n_b \), for every \( b \in \text{alph}(s) \). Since the first \( n_b \) children of \( v \) of type \( b \) have pairwise distinct values in attribute \( @id \), for every \( b \in \text{alph}(w) \), we conclude that \( s \preceq w \). Given that \( s \preceq w', w' \preceq_w w_i \), and \#_{b}(s) = \min\{\#_{b}(w), \#_{b}(w_i)\} \) for every \( b \in \text{alph}(w) \), we have that for every \( c \in \text{alph}(w) \) such that \#_{c}(w_i) < \#_{c}(w), \) it is the case that \#_{c}(w_i) \geq \#_{c}(w') \geq \#_{c}(w) = \#_{c}(w_i). \) Thus, given that \( w_i \not\preceq_w w_i \), there exists \( b \in \text{alph}(w_i) \setminus \text{alph}(w_i) \) such that \( b \not\in \text{alph}(w_i) \). But \( \text{alph}(w_i) \setminus \text{alph}(w) \subseteq \text{alph}(w') \setminus \text{alph}(w) \) and, thus, \( b \in \text{alph}(w') \). Therefore, there exists a node in \( w' \) of type \( b \in X \) and, hence, the generated subtree is of the form shown in Figure 13 (b). We observe that \( w' \) must contain at least \( n_{a_0} \) nodes of type \( a_0 \), each of them having value 3 in attribute \( @e \), since the first \( n_{a_0} \) children of \( v \) of type \( a_0 \) have pairwise distinct values in attribute \( @id \).

We note that when choosing whether to replace \( w \) by either a string contained in \( w_i \) or a string contained in \( w_i \) (\( i \neq 1, i \in [1, n] \)), we are actually choosing the truth values for \( x_2 \) and \( \neg x_2 \). We say that a literal \( j \) has been assigned value 0 if \( j \) is the value of attribute \( @e \) of a node having a sibling with an attribute \( @f \). For example, in the solution for \( T_0 \) shown in Figure 13 (a), we have chosen value 0 for \( \neg x_2 \) since 4 is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). On the other hand, in the solution for \( T_0 \) shown in
Figure 13 (b), we have chosen value 0 for \( x_2 \) since 3 is the value of attribute \( @e \) of a node (of type \( a_0 \)) having a sibling (of type \( b \)) with an attribute \( @f \). We will use this property to prove that \( \theta \) is satisfiable if and only if \( \text{certain}(Q, T_\theta) = \text{false} \). It is worth mentioning that it is possible to choose value 0 for both \( x_2 \) and \( \neg x_2 \). After defining query \( Q \), we will show that this alternative does not cause any problems.

Boolean \( C\text{TQ} \)-query \( Q \) is defined as:

\[
\exists x \exists y \exists z \exists u_1 \exists u_2 \exists u_3 \ (C(\@f = x, \@s = y, \@t = z) \land \neg[(\@f = u_1), (\@e = x)] \land \neg[(\@f = u_2), (\@e = y)] \land \neg[(\@f = u_3), (\@e = z)]).
\]

Intuitively, query \( Q \) says that there exists a node \( v \) of type \( C \) such that each “literal” of \( v \) is assigned value 0, that is, the values \( i_1, i_2, i_3 \) of the attributes \( @f, @s, @t \) of \( v \), respectively, are such that for every \( i \in \{i_1, i_2, i_3\} \), there exists a node \( v' \) having \( i \) as value of attribute \( @e \) and having a sibling with an attribute \( @f \).

Now we prove that for every 3-CNF propositional formula \( \theta \), we have that \( \theta \) is satisfiable if and only if \( \text{certain}(Q, T_\theta) = \text{false} \), where \( T_\theta \) is constructed from \( \theta \) in \( \text{PTIME} \) as shown above.

\((\Rightarrow)\) Assume that \( \theta \) is satisfiable and let \( \sigma \) be a truth assignment satisfying \( \theta \). Define a solution \( T' \) for \( T_\theta \) as follows. The structure of the \( C \)-nodes of \( T' \) is copied from \( T_\theta \). For every propositional variables \( x \) in \( \theta \), we define a \( G \)-node \( v \) of \( T' \) as follows. If \( \sigma(x) = 1 \), then the string of types of the children of \( v \) is \( w_1 \). For every \( b \in \text{alph}(w) \), exactly \( n_b \) children of \( v \) of type \( b \) are assigned pairwise distinct values in attribute \( \@id \), taken from attribute \( \@id \) of the nodes of type \( I_1, \ldots, I_k \) in \( T_\theta \). The value assigned to \( x \) in \( T_\theta \) is the value of attribute \( @e \) of the \( n_{a_0} \) children of \( v \) of type \( a_0 \). Furthermore, the first child of \( v \) of type \( a_0 \) has a child of type \( F \) and \((\#_{a_0}(w) - n_{a_0})\) children of type \( N \), each of them having the value assigned to \( \neg x \) in \( T_\theta \) as value of attribute \( @e \). The remaining \( n_{a_0} - 1 \) children of \( v \) of type \( a_0 \) have exactly one child of type \( F \). Finally, each node of type \( F \) has an attribute \( @f \) with value a fresh null. We note that in this case we have assigned value 0 to \( \sigma(\neg x) \), since the value assigned to \( \neg x \) in \( T_\theta \) is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). We also note that in this case we have not assigned value 0 to \( \sigma(x) \). Now, let us consider \( \sigma(x) = 0 \). In this
case, the string of types of the children of \( v \) is \( w_2 \). For every \( b \in \text{alph}(w) \), exactly \( n_b \) children of \( v \) of type \( b \) are assigned pairwise distinct values in attribute \( @id \), taken from attribute \( @id \) of the nodes of type \( I_1, \ldots, I_k \) in \( T_b \). The value assigned to \( x \) in \( T_b \) is the value of attribute \( @e \) of the first \( n_{a_0} \) children of \( v \) of type \( a_0 \). Each of these nodes also has a child of type \( F \), and these are the only descendant of \( v \) having children of type \( F \). Since \( \#_{a_0}(w_1) < \#_{a_0}(w_2) \), there exists at least one child of \( v \) of type \( a_0 \) not having a child of type \( F \). Let \( v' \) one of these nodes. Then \( v' \) has as children \( \#_{a_0}(w_1) - n_{a_0} \) nodes of type \( N \), each of them having the value assigned to \( \neg x \) in \( T_b \) as value of attribute \( @e \). Finally, every node of type either \( F \) or \( b \in \text{alph}(w_2) \setminus \text{alph}(w_1) \) has an attribute \( @f \) with value a fresh null. We note that in this case we have assigned value 0 to \( \sigma(x) \), since the value assigned to \( x \) in \( T_b \) is the value of attribute \( @e \) of a node (of type \( a_0 \)) having a sibling (of type \( b \in \text{alph}(w_2) \setminus \text{alph}(w_1) \)) with an attribute \( @f \). We also note that in this case we have not assigned value 0 to \( \sigma(\neg x) \) (no node of type \( a_0 \) has both a child of type \( F \) and a child of type \( N \)).

It is straightforward to prove that \( T' \) conforms to \( D_T \) and satisfies \( \Sigma_{ST} \). Furthermore, \( T' \not\cong Q \) since \( \sigma \) satisfies \( \theta \) and, therefore, at least one literal per clause \( C \) is not assigned value 0. We conclude that \( \text{certain}(Q, T_b) = \text{false} \) since \( T' \) is a solution for \( T_b \).

\( \langle \Rightarrow \rangle \) Assume that \( \text{certain}(Q, T_b) = \text{false} \) and let \( T' \) be a solution for \( T_b \) such that \( T' \not\cong Q \). We define a truth assignment for the propositional variables of \( \theta \) as follows. For every clause in \( \theta \), find a \( C \)-node \( v \) of \( T' \) such that the values \( i_1, i_2, i_3 \) of attributes \( @f, @s, @t \) of \( v \) are the values assigned in \( T_b \) to the literals of that clause. Since \( T' \not\cong Q \), there exists \( i \in \{i_1, i_2, i_3\} \) such that every node \( v' \) having \( i \) as value of attribute \( @e \) does not have a sibling with an attribute \( @f \). If \( i \) corresponds to a positive literal \( x \), then define \( \sigma(x) \) as 1. If \( i \) corresponds to a negative literal \( \neg x \), then define \( \sigma(x) \) as 0. We will show that \( \sigma \) is well defined. On the contrary, assume that there exists a propositional variable \( x \) such that 1 was assigned to \( \sigma(x) \) and \( \sigma(\neg x) \). Let \( i, j \) be the values assigned in \( T_b \) to \( x \) and \( \neg x \). Then every node \( v' \) having \( i \) as value of attribute \( @e \) does not have a sibling with an attribute \( @f \). Let \( v'' \) be a \( C \)-node of \( T' \) that satisfies the left hand side of the second rule of \( \Sigma_{ST} \) instantiated on the following values from \( T_b \):

\[
B[L(@p = i, @n = j), \bigwedge_{i=1}^k I_i(@id = i)],
\]

and let \( w'' \leq_i w_i \), where \( i \neq 1 \). Since the first \( n_b \) children of \( v'' \) of type \( b \) have pairwise distinct values in attribute \( @id \), for every \( b \in \text{alph}(w) \), we conclude that \( \#_b(w'') \geq n_b = \min\{\#_b(w), \#_b(w_1)\} \) for every \( b \in \text{alph}(w) \). Thus, given that \( w'' \leq_i w_i \), we have that for every \( c \in \text{alph}(w) \) such that \( \#_c(w_1) = \#_c(w) \), it is the case that \( \#_c(w) \geq \#_c(w'') \). Hence, given that \( w_1 \nleq_i w_i \), there exists \( b \in \text{alph}(w_1) \setminus \text{alph}(w) \) such that \( b \not\in \text{alph}(w_1) \). But \( \text{alph}(w_1) \setminus \text{alph}(w) \subseteq \text{alph}(w_1) \setminus \text{alph}(w) \).
for every $i \in [1, n]$, there exists $a \in \text{alph}(w)$ such that $\#_a(w_i) < \#_a(w)$.

(b) For every $i \in [1, n]$ and every $a \in \text{alph}(w)$ such that $\#_a(w_i) < \#_a(w)$, we have that $\#_a(w_i) = 1$.

(c) For every $i, j \in [1, n], i \neq j$, there exists $a \in \text{alph}(w)$ such that $\#_a(w_i) = 1 < \#_a(w)$ and $\#_a(w_i) < \#_a(w_j)$.

Proof. (a) On the contrary, assume that there exists $i \in [1, n]$ such that $w \preceq w_i$. Then, given that (I) does not hold, for every $j \in [1, n], j \neq i$, there exists $a \in \text{alph}(w)$ such that $\#_a(w_j) < \#_a(w)$. But $n \geq 2$ and, thus, there exist distinct $i, j \in [1, n]$ and $a \in \text{alph}(w)$ such that (1) $\#_a(w_j) < \#_a(w)$ and (2) for every $b \in \text{alph}(w)$, we have that $\#_b(w_j) \leq \#_b(w_i)$ or $\#_b(w_j) \geq \#_b(w)$, which contradicts the fact that (II) does not hold.

(b) On the contrary, assume that there exists $i \in [1, n]$ and $a \in \text{alph}(w)$ such that $1 < \#_a(w_i) < \#_a(w)$. Since $c(r) \leq 1$, we have that $w_i \notin \text{fixed}_a(r)$ and, therefore, there exists $w' \in \pi(r)$ such that $w_i \preceq w'$ and $\#_a(w_i) < \#_a(w')$. Let $s$ be a string such that $\text{alph}(s) = \text{alph}(w), \#_a(s) = \#_a(w_i) + 1$ and $\#_b(s) = \min\{\#_b(w), \#_b(w_i)\}$, for every $b \in \text{alph}(w) \setminus \{a\}$. Then $s \preceq w$ and $s \preceq w'$ and, therefore, there exists $s' \in \min_{\text{ext}}(s, r)$ such that $s \preceq s' \preceq w'$ and $s' \in \text{rep}(w, r)$. By Claim 6.22, there exists $j \in [1, n]$ such that $s \preceq_w w_j$. Notice that $j \neq i$ since $\#_a(w_i) < \#_a(w)$ and $\#_a(w_j) = \#_a(s)$. It is easy to see that for every $b \in \text{alph}(w)$, we have that $\#_b(w_i) \leq \#_b(w_j)$ and $\#_b(w_i) \geq \#_b(w)$. Thus, there exist distinct $i, j \in [1, n]$ and $a \in \text{alph}(w)$ such that (1) $\#_a(w_i) < \#_a(w_i)$ and (2) for every $b \in \text{alph}(w)$, we have that $\#_b(w_i) \leq \#_b(w_j)$ or $\#_b(w_i) \geq \#_b(w)$, which contradicts the fact that (II) does not hold.

(c) On the contrary, assume that there exist $i, j \in [1, n], i \neq j$, such that for every $b \in \text{alph}(w)$ such that $\#_b(w_i) = 1 < \#_b(w_j), w_i$, we have that $\#_b(w_i) \geq \#_b(w_j)$. Then, by (b), we conclude that for every $b \in \text{alph}(w)$ such that $\#_b(w_i) < \#_b(w_j), w_i$, we have that $\#_b(w_i) \geq \#_b(w_j)$. But by (a) we know that there exists $a \in \text{alph}(w)$ such that $\#_a(w_i) < \#_a(w)$ and, therefore, there exist distinct $i, j \in [1, n]$ and $a \in \text{alph}(w)$ such that (1) $\#_a(w_j) < \#_a(w)$ and (2) for every $b \in \text{alph}(w)$, we have that $\#_b(w_j) \leq \#_b(w_i)$ or $\#_b(w_j) \geq \#_b(w)$, which contradicts the fact that (II) does not hold.

For every $i \in [1, n]$, let $X(w_i)$ be the set of element types \{\begin{itemize} \item $b \in \text{alph}(w) \mid 1 = \#_b(w_i) < \#_b(w_i)$ \end{itemize} \}. By Claim 6.23 we know that $X(w_i) \neq \emptyset$, for every $i \in [1, n]$, and that $X(w_i) \not\subseteq X(w_j)$, for every $i, j \in [1, n], i \neq j$. Let $a_0 \in X(w_i)$ such that $\theta_a(\sigma(w_i)) \neq 1$. Since $\sigma$ is well defined and $\sigma$ satisfies $\theta$ (by definition of $\sigma$), we conclude that $\theta$ is satisfiable. This concludes the proof of case (II).
of element types such that

\[
\{ T \} \text{ Fig. 14. XML tree}
\]

a data exchange setting (\( \theta \) propositional formula is a simple DTD, \( D \))

\[ \text{XML trees conforming to } \theta \]

and \( C \) can be reduced to the complement of \( \text{Certain Answers}(Q) \), that is, for every propositional formula \( \theta \) in 3-CNF, there exists a PTIME constructible XML tree \( T_\theta \) conforming to \( D \) such that \( \theta \) is satisfiable if and only if \( \text{certain}(Q, T_\theta) = \text{false} \).

Simple DTD \( D \) is defined as follows. Let \( E_S = \{ B, C, L \} \) be a set of element types and \( A_S = \{ \check{a}f, \check{a}s, \check{a}t, \check{a}p, \check{a}n \} \) be a set of attributes. Then \( D_S = (P_S, R_S, B) \) is a DTD over \( (E_S, A_S) \), where \( P_S \) is defined as:

\[
P_S(B) = C^*L^*, \quad P_S(\ell) = \varepsilon, \quad \text{for every } \ell \in E_S \setminus \{ B \}.
\]

\( R_S \) is defined as:

\[
R_S(B) = \emptyset, \quad R_S(C) = \{ \check{a}f, \check{a}s, \check{a}t \}, \quad R_S(L) = \{ \check{a}p, \check{a}n \}.
\]

XML trees conforming to \( D_S \) are used to represent propositional formulae. Let \( \theta \) be 3-CNF formula \((x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4)\). To construct tree \( T_\theta \), first we assign a distinct natural number to each literal, say

\[
x_1 \mapsto 1, \quad x_2 \mapsto 3, \quad x_3 \mapsto 5, \quad x_4 \mapsto 7,
\]

\[
\neg x_1 \mapsto 2, \quad \neg x_2 \mapsto 4, \quad \neg x_3 \mapsto 6, \quad \neg x_4 \mapsto 8.
\]

Then we represent each clause of \( \theta \) as a node of type \( C \), being the values of attributes \( \check{a}f, \check{a}s, \check{a}t \) the first, second and third literal of that clause, respectively. For each propositional variable \( x \) in \( \theta \), we use the attributes \( \check{a}p, \check{a}n \) of a node of type \( L \) to store the values assigned to \( x \) and \( \neg x \), respectively. Tree \( T_\theta \) for \( \theta = (x_1 \lor x_2 \lor \neg x_3) \land (\neg x_2 \lor x_3 \lor \neg x_4) \) is shown in Figure 14.

C-DTD \( D_T \) is defined as follows. Let \( E_T = \{ B, G, C, N, F \} \) be a set of element types such that \( \{ B, G, C, N, F \} \cap \text{alph}(r) = \emptyset \), and let \( A_T = \{ \check{a}f, \check{a}s, \check{a}t, \check{a}c \} \) be a set of attributes. Then \( D_T = (P_T, R_T, B) \) is a DTD over \( (E_T, A_T) \), where \( P_T \) is defined as:

\[
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\]
\[ P_T(B) = G \ast C^*, \quad P_T(G) = r, \quad P_T(\ell) = \epsilon, \quad \text{for every } \ell \in \text{alph}(r) \setminus (Y \cup \{a_0\}), \]
\[ P_T(C) = \epsilon, \quad P_T(F) = \epsilon, \quad P_T(\ell) = N \ast F^*, \quad \text{for every } \ell \in Y \cup \{a_0\}, \]
\[ P_T(N) = \epsilon. \]

and \( R_T \) is defined as:
\[ R_T(B) = \emptyset, \quad R_T(G) = \emptyset, \quad R_T(\ell) = \emptyset, \quad \text{for every } \ell \in \text{alph}(r) \]
\[ R_T(C) = \{@f, @s, @t\}, \quad R_T(N) = \{@e\}, \quad R_T(F) = \{@f\}. \]

Finally, set \( \SigmaST \) of fully-specified STDs is defined as follows. The first rule of \( \SigmaST \) is defined as:
\[ B[C(@f = x, @s = y, @t = z)] \quad \vdash \quad B[C(@f = x, @s = y, @t = z)]. \]

This rule says that every node of type \( C \) in a source tree \( T \) must appear in every solution for \( T \). The second rule of \( \SigmaST \) is defined as (we use \( \bigwedge \) to denote a sequence of formulae separated by commas, as in cases (I) and (II)):
\[ B[G[a_0[F], \bigwedge_{i=2}^{\#a_0(w)} a_0[N(@e = x)]], \bigwedge_{i=2}^{\#b(w)} b[F], \bigwedge_{i=2}^{\#e(w)} b[N(@e = y)]], \bigwedge_{c \in \text{alph}(w) \setminus (Y \cup \{a_0\})}^{\#c(w)} c] \quad \vdash \quad B[L(@p = x, @n = y)]. \]

To explain the meaning of this rule, we considered again tree \( T_0 \) shown in Figure 14. Assuming that \( b \in Y \), the previous rule says that for each pair of complementary literals, say \((3, 4)\), and for each solution \( T' \) for \( T_0 \), there should exist a node \( v \) of type \( G \) in \( T' \) having the following descendants:

In this figure, \( v \) has \( \#a_0(w) \) children of type \( a_0 \). The first of these children has only one child (of type \( F \)). Let \( i \in [2, \#a_0(w)] \). Then the \( i \)-th child of \( v \), from left to right, of type \( a_0 \) has only one child (of type \( N \)) having 3 as value of attribute \( @e \). Moreover, \( v \) has \( \#b(w) \) children of type \( b \), for every \( b \in Y \). The first of these children has only one child (of type \( F \)). Let \( i \in [2, \#b(w)] \). Then the \( i \)-th child of \( v \), from left to right, of type \( b \) has only one child (of type \( N \)) having 4 as value of attribute \( @e \). Finally, for every \( c \in \text{alph}(w) \setminus (Y \cup \{a_0\}) \), we have that \( v \) has exactly \( \#c(w) \) children of type \( c \).

Since \( w \not\in \pi(r) \), to construct a solution \( T' \) for \( T_0 \) we need to replace \( w \) by a string \( w' \in \pi(r) \) such that \( \text{alph}(w) \subseteq \text{alph}(w') \). By Claim 6.22, we know that there
exists \( i \in [1, n] \) such that \( w' \preceq_w w_i \). First assume that \( i = 1 \). Then, given that
\( \#_{a_0}(w_1) = 1 < \#_{a_0}(w) \), we have that \( \#_{a_0}(w') = 1 \) and, hence, to construct \( w' \) from \( w \) we have to group all \( a_0 \)-nodes together into a single node, generating the subtree shown in Figure 15 (a). Second, assume that \( i \neq 1 \). Then, there exists \( b \in Y \) such that \( \#_{b}(w_i) = 1 < \#_{b}(w) \) and, thus, \( \#_{b}(w') = 1 \). In this case, to construct \( w' \) from \( w \) we have to group all \( b \)-nodes together into a single node, generating the subtree shown in Figure 15 (b).

We note that when choosing whether to replace \( w \) by either a string contained in \( w_1 \) or a string contained in \( w_i \) (\( i \neq 1 \), \( i \in [1, n] \)), we are actually choosing the truth values for \( x_2 \) and \( \neg x_2 \). As in case (II.2), we say that a literal \( j \) has been assigned value 0 if \( j \) is the value of attribute \( @e \) of a node having a sibling with an attribute \( @f \). For example, in the solution for \( T_o \) shown in Figure 15 (a), we have chosen value 0 for \( x_2 \) since 3 is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). On the other hand, in the solution for \( T_o \) shown in Figure 15 (b), we have chosen value 0 for \( \neg x_2 \) since 4 is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). We will use this property to prove that \( \theta \) is satisfiable if and only if \( certain(Q,T_o) = false \). It is worth mentioning that it is possible to choose value 0 for both \( x_2 \) and \( \neg x_2 \). After defining query \( Q \), we will show that this alternative does not cause any problems.

Boolean CTQ-query \( Q \) is defined exactly as in case (II.2):

\[
\exists x \exists y \exists z \exists u_1 \exists u_2 \exists u_3 (C(@f = x, @s = y, @t = z) \land
\not\phi(\not\phi(@f = u_1), \phi(@e = x)) \land \not\phi(\not\phi(@f = u_2), \phi(@e = y)) \land
\not\phi(\not\phi(@f = u_3), \phi(@e = z))).
\]

Intuitively, query \( Q \) says that there exists a node \( v \) of type \( C \) such that each “literal” of \( v \) is assigned value 0, that is, the values \( i_1, i_2, i_3 \) of the attributes \( @f, @s, @t \) of \( v \), respectively, are such that for every \( i \in \{i_1, i_2, i_3\} \), there exists a node \( v' \) having \( i \) as value of attribute \( @e \) and having a sibling with an attribute \( @f \).

Now we prove that for every 3-CNF propositional formula \( \theta \), we have that \( \theta \) is satisfiable if and only if \( certain(Q,T_o) = false \), where \( T_o \) is constructed from \( \theta \) in PTIME as shown above.
Define a solution \( T' \) for \( T_\theta \) as follows. The structure of the \( C \)-nodes of \( T' \) is copied from \( T_\theta \). For every propositional variables \( x \) in \( \theta \), we define a \( G \)-node \( v \) of \( T' \) as follows. If \( \sigma(x) = 0 \), then the string of types of the children of \( v \) is \( w_1 \). In particular, \( v \) has only one child of type \( a_0 \), which has as children one node of type \( F \) and \((\#_{a_0}(w_1) - 1)\) nodes of type \( N \), each of them having in attribute \( @e \) the value assigned to \( x \) in \( T_\theta \). For every \( b \in Y \), we have that \( v \) has \#_{b}(w_1)\) children of type \( b \) \((\#_{b}(w_1) > 1\) by definition of \( Y \)). The first child of \( v \) of type \( b \) has as children a node of type \( F \). Each of the remaining \((\#_{b}(w_1) - 1)\) \( b \)-nodes has as children only one node (of type \( N \)) having in attribute \( @e \) the value assigned to \( \neg x \) in \( T_\theta \). Finally, each node of type \( F \) has an attribute \( @f \) with value a fresh null. We note that in this case we have assigned value 0 to \( \sigma(x) \), since the value assigned to \( x \) in \( T_\theta \) is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). Observe that these nodes are descendants of a node of type \( a_0 \). We also note that in this case we have not assigned value 0 to \( \sigma(\neg x) \). Now, let us consider \( \sigma(x) = 1 \). In this case, the string of types of the children of \( v \) is \( w_2 \). In particular, \( v \) has only one child of type \( b \), for some \( b \in Y \), which has as children one node of type \( F \) and \((\#_{a_0}(w_2) - 1)\) nodes of type \( N \), each of them having in attribute \( @e \) the value assigned to \( \neg x \) in \( T_\theta \). Furthermore, \( v \) has \#_{a_0}(w_2)\) children of type \( a_0 \) \((\#_{a_0}(w_2) > 1\) since \( a_0 \not\in X(w_2)\)). The first child of \( v \) of type \( a_0 \) has as children a node of type \( F \). Each of the remaining \((\#_{a_0}(w_2) - 1)\) \( a_0 \)-nodes has as children only one node (of type \( N \)) having in attribute \( @e \) the value assigned to \( x \) in \( T_\theta \). Finally, each node of type \( F \) has an attribute \( @f \) with value a fresh null. We note that in this case we have assigned value 0 to \( \sigma(\neg x) \), since the value assigned to \( \neg x \) in \( T_\theta \) is the value of attribute \( @e \) of a node (of type \( N \)) having a sibling (of type \( F \)) with an attribute \( @f \). Observe that these nodes are descendants of a node of type \( b \in Y \). We also note that in this case we have not assigned value 0 to \( \sigma(x) \).

It is straightforward to prove that \( T' \) conforms to \( D_T \) and satisfies \( \Sigma_{ST} \). Furthermore, \( T' \not\models Q \) since \( \sigma \) satisfies \( \theta \) and, therefore, at least one literal per clause \( C \) is not assigned value 0. We conclude that \( \text{certain}(Q, T_\theta) = false \) since \( T' \) is a solution for \( T_\theta \).

\((\Rightarrow)\) Assume that \( \theta \) is satisfiable and let \( \sigma \) be a truth assignment satisfying \( \theta \). For every propositional variables \( x \) in \( \theta \), we define a \( G \)-node \( v \) of \( T' \) as follows. For every clause in \( \theta \), find a \( C \)-node \( v \) of \( T' \) such that the values \( i_1, i_2, i_3 \) of attributes \( @f, @s, @t \) of \( v \) are the values assigned in \( T_\theta \) to the literals of that clause. Since \( T' \not\models Q \), there exists \( i \in \{i_1, i_2, i_3\} \) such that every node \( v' \) having \( i \) as value of attribute \( @e \) does not have a sibling with an attribute \( @f \). If \( i \) corresponds to a positive literal \( x \), then define \( \sigma(x) \) as 1. If \( i \) corresponds to a negative literal \( \neg x \), then define \( \sigma(x) \) as 0. We will show that \( \sigma \) is well defined. On the contrary, assume that there exists a propositional variable \( x \) such that 1 was assigned to \( \sigma(x) \) and \( \sigma(\neg x) \). Let \( i, j \) be the values assigned in \( T_\theta \) to \( x \) and \( \neg x \). Then every node \( v' \) having \( i \) as value of attribute \( @e \) does not have a sibling with an attribute \( @f \). Let \( v'' \) be a \( G \)-node of \( T' \) that satisfies the left hand side of the second rule of \( \Sigma_{ST} \) instantiated on the following values from \( T_\theta \):

\[ B[L(@p = i, @n = j)] \]

and let $w'' = \lambda T^*(\text{children}(v''))$. Since every node $v'$ having $j$ as value of attribute @e does not have a sibling with an attribute @f, for every $b \in Y$ we have that either $\#_b(w'') = 0$ or $\#_b(w'') \geq 2$. Thus, by Claims 6.22 and definition of $Y$, we have that $w'' \preceq_w w_1$ and, hence, $\#_{a_0}(w'') = 1$. We conclude that the only child of $v''$ of type $a_0$ must have a child of type $F$ and a child of type $N$ having $i$ as value of attribute @e and, hence, there exists a node having $i$ as value of attribute @e and having a sibling with an attribute @f, which contradicts the fact that 1 was assigned to $\sigma(x)$.

Since $\sigma$ is well defined and $\sigma$ satisfies $\theta$ (by definition of $\sigma$), we conclude that $\theta$ is satisfiable. This concludes the proof of case (III) and the proof of Lemma 6.21.

7. CONCLUSIONS

We have defined the basic notions of XML data exchange: source-to-target constraints, data exchange settings, consistency and query answering problems. We have seen that transferring relational data exchange results to the XML setting requires considerable effort, even in the fairly simple setting that shows how to translate source patterns into target patterns. We have shown that, while checking consistency is hard in general, it is tractable for a practically relevant class handled by the Clio system at IBM [Popa et al. 2002]. For query answering, we showed a dichotomy, that separates query answering instances into tractable and coNP-complete ones, depending on properties of DTDs and constraints.

As far as the theoretical foundations of XML data exchange are concerned, this paper uncovered at most the tip of the iceberg. We now briefly list other problems that seem to be worthy a theoretical investigation. We would like to remove the distinct-variable restriction on source patterns used in our investigation of the consistency problem, and analyze the resulting settings for decidability/complexity issues. The standard notions of local-as-view and global-as-view from data integration [Lenzerini 2002] have been adapted in relational data exchange [Fagin et al. 2005; Fagin et al. 2005] and sometimes they lead to better algorithms or easier analysis of the behavior of data exchange settings and queries. So far we have not made these notions precise in the XML case. We have concentrated on tree patterns that use the child and descendant axes of XPath; in the future we plan to consider more expressive source-to-target constraints that use other axes such as next sibling. We also would like to consider more expressive schema constraints (for example, ID and IDREF attributes). Finally, to define the notion of certain answers, we used queries that produce tuples of values. Most XML queries produce trees, but it is not at all clear how to define the certain answers semantics for them. We plan to work on this in the future. One very specific issue one needs to address is the complexity of checking univocality of regular expressions (which guarantees tractable query answering). We showed that the notion is decidable by reduction to Presburger arithmetic, but this does not give us good complexity bounds.

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REFERENCES


In this section, we recall some basic facts about ranked and unranked tree automata.

A nondeterministic (ranked) finite tree automaton (NFTA) on binary node-labeled trees over alphabet $\Gamma$ is defined as $A = (Q, q_0, \delta, F)$ where $Q$ is the set of states, $q_0 \in Q$, $F \subseteq Q$ and $\delta : \Gamma \times Q \times Q \rightarrow 2^Q$ is the transition function. Given a binary tree $T$, a run of $A$ on $T$ is a function $\text{run}_A : T \rightarrow Q$ that assigns states to nodes. For a leaf $s$ labeled $a$, we require that $\text{run}_A(s) \in \delta(a, q_0, q_0)$, and for a node $s$ labeled $a$ with two children $s_1$ and $s_2$ we require that $\text{run}_A(s) \in \delta(a, \text{run}_A(s_1), \text{run}_A(s_2))$. A tree $T$ is accepted if there is a run $\text{run}_A$ such that $\text{run}_A(root) \in F$. Given an NFTA $A$, testing whether $L(A) = \emptyset$ can be done in time linear in the size of $T$.

### A. STRING AND TREE AUTOMATA

In this section, we recall some basic facts about ranked and unranked tree automata. We write NFA and DFA for non-deterministic and deterministic finite automata. If $A$ is an automaton, then $L(A)$ is the language accepted by it. Recall that given a regular expression $r$, constructing an NFA $A_r$ with $L(A_r) = L(r)$ can be done in polynomial time.
the set of states, \( F \subseteq Q \) and \( \delta : Q \times \Gamma \rightarrow 2^Q \) is the transition function such that \( \delta(q, a) \) is a regular language for every \( s \in Q \) and \( a \in \Gamma \). Given an ordered unranked tree \( T \), a run of \( A \) on \( T \) is again a function \( \text{run}_A : T \rightarrow Q \) that assigns states to nodes. If \( s \) is a node whose children are \( s_1, \ldots, s_n \) ordered by the sibling relation as \( s_1 <_{\text{sib}} \ldots <_{\text{sib}} s_n \), then the word \( \text{run}_A(s_1) \ldots \text{run}_A(s_n) \) over \( Q \) must be in \( \delta(\text{run}_A(s), a) \). In particular, if \( s \) is a leaf, then a run can assign a state \( q \) to it iff \( q \in L(\delta(q, a)) \). A tree \( T \) is accepted if there is a run \( \text{run}_A \) such that \( \text{run}_A(\text{root}) \in F \).

An automaton is deterministic if every tree admits only one run. The standard representation of UNFTAs uses NFAs for transitions, that is, \( \delta \) maps pairs state-letter to NFAs over \( Q \). It is known that testing nonemptiness is again polynomial-time [Neven 2002]. If an automaton is deterministic and furthermore all transitions are represented by DFAs, then we refer to UFTA(DFA).

DTDs can naturally be represented by tree automata. We shall consider DTDs without attributes. Such a DTD \( D \) over a set \( E \) of element types is represented by an automaton \( A_D \) in which the set of states is \( E \), and \( \delta(\ell, \ell') \) is defined to be an automaton for \( P(\ell) \), and \( \delta(\ell, \ell') = \emptyset \) otherwise, and \( F = \{ \text{root} \} \).

B. PROOFS

B.1 Proof of Proposition 4.4

As before, we can assume that all formulae in STDs have no free variables. Membership in NP is easy by guessing an instance; for membership in PSPACE we transform a DTD such that all regular expressions become either conjunctions or disjunctions, and then use an alternating polynomial-time algorithm. For hardness, we use reductions from QSAT for PSPACE and 3SAT for NP.

We start with a). By Claim 4.2, it suffices to consider STDs in which all attribute formulae are of the form \( \ell \in \mathcal{E} \). Furthermore, every nonrecursive DTD \( D \) that does not use the Kleene star can be in polynomial time transformed into a DTD \( D' \) in which all productions are of the form \( \ell \rightarrow \ell \ell' \), or \( \ell \rightarrow \ell' \), or \( \ell \rightarrow \varepsilon \). This is done by repeatedly changing each rule \( \ell \rightarrow r_1 r_2 \) into \( \ell \rightarrow \ell_1 \ell_2, \ell_1 \rightarrow r_1, \ell_2 \rightarrow r_2 \), and each rule \( \ell \rightarrow r_1 | r_2 \) into \( \ell \rightarrow \ell_1 | \ell_2, \ell_1 \rightarrow r_1, \ell_2 \rightarrow r_2 \), where \( \ell_1 \) and \( \ell_2 \) are fresh symbols from \( \mathcal{E} \). This also establishes an embedding \( h : \text{SAT}(D) \rightarrow \text{SAT}(D') \) such that for every tree-pattern formula given by the grammar

\[ \varphi := \ell, \ell \in E \mid \ell[\varphi] \mid \ell[\varphi], \]

one can find a formula \( \varphi' \) from the same class such that \( T \models \varphi \) iff \( h(T) \models \varphi' \), for every \( T \in \text{SAT}(D) \). (This formula simply leaves \( \ell[\varphi] \) in place, and replaces \( \ell[\varphi] \) by an explicit chain of new element types introduced in the translation). In view of this, we can assume, without loss of generality, that in all DTDs all the productions are of the form \( \ell \rightarrow \ell \ell' \), or \( \ell \rightarrow \ell' \ell'' \), or \( \ell \rightarrow \varepsilon \).

Now we show membership in PSPACE. Since by the assumption the target DTD \( D_T \) is fixed and is not recursive and does not use the Kleene star, there are only finitely many trees that conform to it (if we disregard attribute values), that can
be explicitly listed. Let $T_1, \ldots, T_m$ be the listing of those trees. Then for each STD $\psi : \varphi$ and each $T_i$ we can verify if $T_i \models \psi$. Furthermore, since each tree-pattern formula can be translated into an FO formula in the vocabulary that contains both child $<_{\text{child}}$ and descendant $<_{\text{child}}$ relation, checking whether $T_i \models \psi$ can be done in PSPACE (since the combined complexity of FO is PSPACE).

Let $\Phi_i$ be the set of all $\varphi$'s such that $T_i \not\models \psi$ where $\psi : \varphi$ is an STD in $\Sigma_{ST}$. Then the setting $(D_S, D_T, \Sigma_{ST})$ is consistent if there is a tree $T \models D_S$ and $i \leq n$ such that $T \not\models \varphi$ for every $\varphi \in \Phi_i$ (in this case $T_i$ is a solution for $T$). Thus, to show PSPACE-membership, it suffices to show that for a given set $\Phi$ of right-hand sides of STDs from $\Sigma_{ST}$, one can check, in PSPACE, whether there exists a tree $T$ that conforms to $D_S$ and falsifies every formula in $\Phi$. This is proved by providing an alternating PTIME algorithm; since alternating PTIME equals PSPACE, the result follows. Given the restriction on STDs, each $\varphi$ simply checks the existence of a path with a fixed set of labels $\ell_1, \ldots, \ell_k$, indicating for each consecutive ones whether they are in the child or descendant relation. Hence the alternating algorithm makes an existential step for each $\ell \rightarrow \ell' \ell''$ rule in the DTD, and a universal step for each $\ell \rightarrow \ell'$ rule. It takes polynomial time to keep each path in memory and verify whether it falsifies every $\varphi \in \Phi$. Since $D_S$ is non-recursive, this alternating algorithm runs in polynomial time, thus proving PSPACE-membership.

For PSPACE-hardness, we show reduction from QBF. Suppose we are given a quantified Boolean formula

$$\alpha = Q_1 x_1 \ldots Q_m x_m \ (C_1 \land \ldots \land C_n),$$

where each $Q_i$ is either $\forall$ or $\exists$, and each clause $C_i$ is a disjunction $(x_j^{+} \lor x_j^{-})$. Here $x^+\lor$ indicates that variables could be negated: $x^+$ refers to $x$ and $x^-$ to $\neg x$. Since the restriction of QBF to 3-CNF quantifier-free formulae is known to be PSPACE-complete, we can assume this restriction on the shape of clauses.

To represent formula (5) we use the following data exchange setting. The source DTD $D_S$ has element types $\{\xi, x_1^+, x_1^-, \ldots, x_m^+, x_m^-, x_{m+1}^+, x_{m+1}^-, \ldots, x_k^+, x_k^-, \ldots\}$, assuming that formula (5) mentions propositional variables $x_1, \ldots, x_m$. The rules of $D_S$ are as follows:

- $\xi \rightarrow x_1^+ x_1^-$ if $Q_1 = \forall$
- $\xi \rightarrow x_1^+ \neg x_1$ if $Q_1 = \exists$
- $x_i \rightarrow x_i^+ x_{i+1}^-$ if $Q_{i+1} = \forall$, for $1 \leq i < m$
- $x_i \rightarrow x_i^+ \neg x_{i+1}$ if $Q_{i+1} = \exists$, for $1 \leq i < m$

Let $f$ be an element type that does not occur in the target DTD, whose root is denoted by $\gamma$. For each clause $C$, consider the assignment that invalidates it. For example, let $C = (x_i \lor \neg x_j \lor x_k)$ with $i < j < k$. Then the invalidating assignment is $x_i = 0, x_j = 1, x_k = 0$. In this case we put the following STD into $\Sigma_{ST}$:

$$\xi'[f] : = \xi[\overset{+}{x_i} \overset{-}{x_j} \overset{+}{x_k}]$$

assuming $i = 1, j = 0, k = j + 1$. In other words, if $C$ is invalid, we attempt to put a node in the target tree that is inconsistent with the target DTD. When some of the indices are consecutive, we have to omit the descendant $\overset{+}{x_i}$: for example, if $i = 1, j > 2$ and $k = j + 1$, we use

$$\xi'[f] : = \xi[\overset{+}{x_i} \overset{-}{x_j} \overset{+}{x_k}]$$

since in this case \( x^- \) has to be witnessed at a child of the root, and not a descendant of a child of a root.

We now let \( \Sigma_{ST} \) contain all such STDs for all the clauses used in the formula. Then a straightforward argument shows that \( \alpha \) is true if\( \exists \) there is a tree \( T \models D_S \) such that no right-hand side of an STD is satisfied, which in turn is equivalent to the consistency of the setting.

We continue with b). This proof is similar to the previous case. Again we assume that formulae in STDs do not have free variables. We shall need the following observation. If we have a path-pattern formula \( \varphi \), a tree \( T \), and a node \( v \) of \( T \), one can verify if \( v \) witnesses \( \varphi \) in \( T \) in time \( O(||T|| \cdot ||\varphi||) \). Indeed, we inductively find sets of nodes in which subformulae of \( \varphi \) are true. First, each formula \( \ell \) is true in nodes labeled \( \ell \). To find nodes in which \( \ell[\varphi'] \) holds we find \( \ell \)-nodes which have a child for which by induction we already know that \( \varphi' \) holds. To find nodes in which \( \langle \varphi' \rangle \) holds, we depth-first traverse the tree and for each node in which \( \varphi' \) holds, mark all its ancestors with \( \langle \varphi' \rangle \) as we go backwards. Thus, for each subformula of \( \varphi \) we need time linear in the size of \( T \), and hence the algorithm runs in time \( O(||T|| \cdot ||\varphi||) \).

We now show membership in NP. Since \( D_T \) is fixed and does not use the Kleene star, there may be only a fixed number of trees that conform to it. Let \( T_1, \ldots, T_n \) enumerate them. As before, let \( \Phi_1 = \{ \varphi \mid \psi : \varphi \in \Sigma_{ST} \text{ and } T_i \models \psi \} \). Then it suffices to check in NP if for some \( i \leq n \), there exists a tree \( T \) such that \( T \models D_S \) and \( T \models \| \varphi \| \) for all \( \varphi \in \Phi_i \). If that is the case, the pair \( (T, T_i) \) witnesses consistency; if there is no such tree for all \( i \), the setting is inconsistent. For the latter, we guess a tree \( T \) simply by making a choice for each of the rules \( \ell \rightarrow \ell_1 | \ldots | \ell_m \). Then, by the earlier observation, we can verify whether \( T \models \varphi \) in polynomial time in the sizes of \( T \) (which is linear in the size of \( D_S \)) and \( \varphi \). This proves membership in NP.

For hardness, we simply apply the proof for QBF in the case when all quantifiers are existential. Then every rule is of the form \( \ell \rightarrow \ell' | \ell'' \) or \( \ell \rightarrow \varepsilon \), and the QBF reduction becomes a 3SAT reduction. This proves NP-hardness, and the proposition.

### B.2 Proof of Theorem 5.11

We consider here classes \( STD(\varphi//) \) and \( STD(\varphi,) \). The proof for the class \( STD(\varphi//) \) was already given in Section 5.3.

Case of \( STD(\varphi//) \): We define a data exchange setting \( (D_S, D_T, \Sigma_{ST}) \) and a Boolean CQ-query \( Q \) such that both \( D_S \) and \( D_T \) are simple DTDs, \( \Sigma_{ST} \) is a set of source-to-target dependencies in \( STD(\varphi//) \) and 3SAT can be reduced to the complement of \( Certain-Answers(Q) \), that is, for every propositional formula \( \theta \) in 3-CNF, there exists a PTIME constructible XML tree \( T_\theta \) conforming to \( D_S \) such that \( \theta \) is satisfiable if and only if \( Certain(Q, T_\theta) = false \). Simple DTD \( D_S \) is defined exactly as in the proof for \( STD(\varphi//) \) (see Section 5.3). Simple DTD \( D_T \) is defined as follows. Let \( E_T = \{ K, L, B_1, B_2, G_1, G_2, J, H_1, H_2, C_1, C_2, C_3 \} \) be a set of element types and \( A_T = \{ \&\ell, \&p, \&n, \&m \} \) a set of attributes. Then \( D_T = (P_T, RT_T, K) \) is a DTD over \( (E_T, A_T) \), where \( P_T \) is defined as:
Figure 16 which one is going to be a subtree of $T$

That is, there exists a node and another one having $J$ and another one having $i$ in attribute $\bar{\ell}$. Thus, in Figure 16 (a), literal $i$ has been assigned value 1 since there is a node (of type $K$) having as great-grandchildren one of type $J$ and another one having $i$ in attribute $\bar{\ell}$. In Figure 16 (b), literal $i$ has been assigned value 1 since there is a node (of type $K$) having as great-grandchildren three different ways of satisfying the clause stored in the children of $v$. We say that a literal $i$ has been assigned value 1 if $i$ appears in a subtree of the form:

\[
\begin{align*}
P_T(K) &= B_1^*L^*, & P_T(B_1) &= B_2^*, & P_T(B_2) &= G_1^*J^*C_1^*, \\
P_T(G_1) &= G_2^*J^*, & P_T(G_2) &= J^*, & P_T(J) &= H_1^*, \\
P_T(H_1) &= H_2^*, & P_T(H_2) &= \varepsilon, & P_T(C_1) &= C_2^*, \\
P_T(C_2) &= C_3^*, & P_T(C_3) &= \varepsilon, & P_T(L) &= \varepsilon.
\end{align*}
\]

and $R_T$ is defined as:

\[
\begin{align*}
R_T(K) &= \emptyset, & R_T(B_1) &= \emptyset, & R_T(B_2) &= \emptyset, \\
R_T(G_1) &= \{\bar{m}\}, & R_T(G_2) &= \emptyset, & R_T(J) &= \{\bar{m}\}, \\
R_T(H_1) &= \emptyset, & R_T(H_2) &= \emptyset, & R_T(C_1) &= \{\bar{\ell}\}, \\
R_T(C_2) &= \{\bar{\ell}\}, & R_T(C_3) &= \{\bar{\ell}\}, & R_T(L) &= \{\bar{p}, \bar{n}\}.
\end{align*}
\]

Finally, $\Sigma_{ST}$ is defined as follows. The first rule of $\Sigma_{ST}$ is defined as:

\[
K[L(\bar{m} = x, \bar{n} = y)] \quad :- \quad K[L(\bar{p} = x, \bar{m} = y)].
\]

This rule says that every node of type $L$ in a source tree $T$ must appear in every solution for $T$. The second rule of $\Sigma_{ST}$ is defined as:

\[
K[B_1B_2J(\bar{m} = u)][C_1(\bar{e} = x)C_2(\bar{e} = y)C_3(\bar{e} = z)]] \quad :- \quad K[C(\bar{f} = x, \bar{s} = y, \bar{t} = z)].
\]

Notice that this rule is not fully-specified since it does not say whether the node having an attribute $\bar{m}$ is of type either $G_1$ or $J$. Also notice that in the left hand side of this rule we have a formula of the form $K[B_1B_2[\varphi_1, \varphi_2]]$ not using descendant $//$, where $K$ is the type of the root.

The previous rules say that for every $C$-node $v$ of a source tree $T$ having $i, j, k$ as values of attributes $\bar{f}, \bar{s}, \bar{t}$, and for every solution $T'$ for $T$, $T'$ must have as subtree at least one of the trees shown in Figure 16.

When constructing a solution for $T_\theta$, we are actually constructing a truth assignment for $\theta$. Let $v$ be a $C$-node of $T_\theta$ with values $i, j, k$ in attributes $\bar{f}, \bar{s}, \bar{t}$. To construct a solution $T'$ for $T$ we have to instantiate the second dependency of $\Sigma_{ST}$ on values $i, j$ and $k$, and then we have to choose among the trees shown in Figure 16 which one is going to be a subtree of $T'$. These alternatives represent three different ways of satisfying the clause stored in the children of $v$. We say that a literal $i$ has been assigned value 1 if $i$ appears in a subtree of the form:
a node of type $J$ and a node (of type $C_1$) having $i$ in attribute $@f$. On the other
hand, in Figure 16 (b), literal $j$ has been assigned value 1 since there is a node (of
type $B_1$) having as great-grandchildren a node of type $J$ and a node (of type $C_2$
having $j$ in attribute $@s$, and in Figure 16 (c), literal $k$ has been assigned value 1
since there is a node (of type $B_2$) having as great-grandchildren a node of type $J$
and a node (of type $C_3$) having $k$ in attribute $@t$. Notice that when constructing
a truth assignment for $\theta$, it is possible to choose value 1 for two complementary
literals (when considering complementary literals in two distinct clauses). To take
care of this problem we use the following Boolean $CTQ$-query $Q$:

$$\exists x \exists y (L(@p = x, @n = y) \land \llbracket J \rrbracket \land \llbracket (\ell = x) \rrbracket \land \llbracket (\ell = y) \rrbracket).$$

Intuitively, query $Q$ says that there exists two complementary literals $x$ and $y$ such
that both $x$ and $y$ have been assigned value 1, that is, there exists a node having at
least two great-grandchildren, one of type $J$ and the other one having $x$ in attribute
$@f$, and the same holds for $y$.

Now we prove that for every 3-CNF propositional formula $\theta$, we have that $\theta$ is
satisfiable if and only if $\text{certain}(Q, T_\theta) = \text{false}$, where $T_\theta$ is constructed from $\theta$
in $\text{PTIME}$ as in the proof for $\text{STD}(_/\_)$ (see Section 5.3).

$(\Rightarrow)$ Assume that $\theta$ is satisfiable and let $\sigma$ be a truth assignment satisfying $\theta$. 
Define a solution $T'$ for $T_\theta$ as follows. The structure of the $L$-nodes of $T'$ is copied 
from $T_\theta$. For every $C$-node $v$ in $T_\theta$ having $i, j, k$ in attributes $@f, @s, @t$, if $\sigma$ makes 
true the first literal of this clause, then $T'$ has as subtree the tree shown in Figure
16 (a). If $\sigma$ makes true the second literal of this clause, then $T'$ has as subtree 
the tree shown in Figure 16 (b). Finally, if $\sigma$ makes true the third literal of this 
clause, then $T'$ has as subtree the tree shown in Figure 16 (c). It is straightforward

Fig. 16. Different alternatives for satisfying the second rule of $\Sigma_{ST}$ in case $\text{STD}(_/\_)$ of the proof
of Theorem 5.11.

to prove that $T'$ conforms to $D_T$ and satisfies $\Sigma_{ST}$. Furthermore, $T' \not= Q$ since $\sigma$ is well defined and, therefore, for every propositional variables $x$, either $x$ or $\neg x$ is not assigned value 1. We conclude that $\text{certain}(Q, T_0) = \text{false}$ since $T'$ is a solution for $T_0$.

$(\Leftarrow)$ Assume that $\text{certain}(Q, T_0) = \text{false}$ and let $T'$ be a solution for $T_0$ such that $T' \not= Q$. We define a truth assignment for the propositional variables of $\theta$ as follows. For every clause in $\theta$, find the values $i$, $j$, $k$ assigned in $T_0$ (as values of attributes $@f$, $@s$ and $@t$) to the literals of that clause. Then $T'$ has as subtree at least one of the trees shown in Figure 16. If $T'$ has as subtree the tree shown in Figure 16 (a), then $\sigma$ assigns value 1 to the first literal of the clause. If $T'$ has as subtree the tree shown in Figure 16 (b), then $\sigma$ assigns value 1 to the second literal of the clause. Finally, if $T'$ has as subtree the tree shown in Figure 16 (c), then $\sigma$ assigns value 1 to the third literal of the clause. Since $T' \not= Q$, we have that $\sigma$ is well defined. Thus $\theta$ is satisfiable since $\sigma$ satisfies this formula by definition. This concludes the proof of case of $\text{STD}(r, //)$.

Case of $\text{STD}(\cdot, \cdot)$: We define a data exchange setting $(D_S, D_T, \Sigma_{ST})$ and a Boolean $C\overline{T}Q$-query $Q$ such that both $D_S$ and $D_T$ are simple DTDs. $\Sigma_{ST}$ is a set of source-to-target dependencies in $\text{STD}(\cdot, \cdot)$ and $3\text{SAT}$ can be reduced to the complement of $\text{CERTAIN-ANSWERS}(Q)$, that is, for every propositional formula $\theta$ in $3\text{-CNF}$, there exists a PTIME constructible XML tree $T_0$ conforming to $D_S$ such that $\theta$ is satisfiable if and only if $\text{certain}(Q, T_0) = \text{false}$.

Simple DTD $D_S$ is defined exactly as in the previous case. Simple DTD $D_T$ is defined as follows. Let $E_T = \{K, L, B_1, B_2, G_1, G_2, J, C_1, C_2, C_3\}$ be a set of element types and $A_T = \{@\ell, @p, @n\}$ a set of attributes. Then $D_T = (P_T, R_T, K)$ is a DTD over $(E_T, A_T)$, where $P_T$ is defined as:

\[
\begin{align*}
  P_T(K) &= B_1^*L^*, & P_T(B_1) &= B_2^*, & P_T(B_2) &= G_1^*J^*C_1^*, \\
  P_T(G_1) &= G_2^*J^*, & P_T(G_2) &= J^*, & P_T(J) &= \epsilon, \\
  P_T(C_1) &= C_2^*, & P_T(C_2) &= C_3^*, & P_T(C_3) &= \epsilon, \\
  P_T(L) &= \epsilon.
\end{align*}
\]

and $R_T$ is defined as:

\[
\begin{align*}
  R_T(K) &= \emptyset, & R_T(B_1) &= \emptyset, & R_T(B_2) &= \emptyset, \\
  R_T(G_1) &= \emptyset, & R_T(G_2) &= \emptyset, & R_T(J) &= \emptyset, \\
  R_T(C_1) &= \{@\ell\}, & R_T(C_2) &= \{@\ell\}, & R_T(C_3) &= \{@\ell\}, \\
  R_T(L) &= \{@p, @n\}.
\end{align*}
\]

Finally, $\Sigma_{ST}$ is defined as follows. The first rule of $\Sigma_{ST}$ is defined as:

\[
K[L(@p = x, @n = y)] \vdash K[L(@p = x, @n = y)].
\]

This rule says that every node of type $L$ in a source tree $T$ must appear in every solution for $T$. The second rule of $\Sigma_{ST}$ is defined as:

\[
K[B_1|B_2||J, C_1(@\ell = x)|C_2(@\ell = y)|C_3(@\ell = z)||] \vdash K[C(@f = x, @s = y, @t = z)].
\]

Fig. 17. Different alternatives for satisfying the second rule of $\Sigma_{ST}$ in case $STD(T, \varphi)$ of the proof of Theorem 5.11.

Notice that this rule is not fully-specified since it does not say whether the father of $J$ is a node of type either $B_2$ or $G_1$ or $G_2$. Also notice that in the left hand side of this rule we have a formula of the form $K[B_1[B_2[\varphi_1, \varphi_2]]]$ not using wildcard $\_$. The previous rule says that for every $C$-node $v$ of a source tree $T$ having $i$, $j$, $k$ as values of attributes $\_f$, $\_s$, $\_t$, and for every solution $T'$ for $T$, $T'$ must have as subtree at least one of the trees shown in Figure 17.

When constructing a solution for $T_\theta$, we are actually constructing a truth assignment for $\theta$. Let $v$ be a $C$-node of $T_\theta$ with values $i$, $j$, $k$ in attributes $\_f$, $\_s$, $\_t$. To construct a solution $T'$ for $T$ we have to instantiate the second dependency of $\Sigma_{ST}$ on values $i$, $j$ and $k$, and then we have to choose among the trees shown in Figure 17 which one is going to be a subtree of $T'$. These alternatives represent three different ways of satisfying the clause stored in the children of $v$. As in the previous case, we say that a literal $i$ has been assigned value 1 if there exists a node having at least two great-grandchildren, one of type $J$ and another one having $i$ in attribute $\_t$. Thus, in Figure 17 (a), literal $i$ has been assigned value 1 since there is a node (of type $K$) having as great-grandchildren a node of type $J$ and a node (of type $C_1$) having $i$ in attribute $\_t$. On the other hand, in Figure 17 (b), literal $j$ has been assigned value 1 since there is a node (of type $B_1$) having as great-grandchildren a node of type $J$ and a node (of type $C_2$) having $j$ in attribute $\_s$, and in Figure 17 (c), literal $k$ has been assigned value 1 since there is a node (of type $B_2$) having as great-grandchildren a node of type $J$ and a node (of type $C_3$) having $k$ in attribute $\_s$. Notice that when constructing a truth assignment for $\theta$, it is possible to choose value 1 for two complementary literals (when considering complementary literals in two distinct clauses). To take care of this problem we
use the same Boolean $CTQ$-query $Q$ as in the previous case:

$$\exists x \forall y (L(\overline{p} = x, \overline{n} = y) \land \overline{[\overline{[\overline{\ell} = x]}]} \land \overline{[\overline{[\overline{\ell} = y]}]}).$$

Exactly as in the previous case, we prove that for every 3-CNF propositional formula $\theta$, we have that $\theta$ is satisfiable if and only if $\text{certain}(Q, T_\theta) = false$, where $T_\theta$ is constructed from $\theta$ in PTIME as in the proof for STD($\varnothing$) (see Section 5.3). This concludes the proof of case STD($\varnothing$) and the proof of Theorem 5.11.

B.3 Proof of Claim 6.16

(a) On the contrary, assume that $\text{alp}(w_{i+1}) \not\subset \text{alp}(w')$. Since $h_i$ is a homomorphism from $T_i$ to $T'$, we have that $\text{alp}(w_i) \subset \text{alp}(w')$ and, therefore, $\text{alp}(w_{i+1}) \setminus \text{alp}(w_i) \not\subset \text{alp}(w') \setminus \text{alp}(w_i)$. Define string $w'_i$ as follows: $\text{alp}(w'_i) = \text{alp}(w_i)$ and $\#: (w'_i) = 1$, for every $a \in \text{alp}(w_i)$. Then $w'_i \preceq w'$ since $\text{alp}(w_i) \subset \text{alp}(w')$. Thus, there exists $w''_i \in \text{min}_\text{ext}(w'_i, P\text{Pr}(\lambda_T(v)))$ such that $w'_i \preceq w''_i \preceq w'$ since $w' \in \pi(P\text{Pr}(\lambda_T(h_i(v)))) = \pi(P\text{Pr}(\lambda_T(v)))$. By definition of $\text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$ we have that $w''_i \in \text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$. Since $\text{alp}(w''_i) \subset \text{alp}(w')$ and $\text{alp}(w_{i+1}) \setminus \text{alp}(w_i) \subset \text{alp}(w''_i) \setminus \text{alp}(w_i)$, we have that $\text{alp}(w_{i+1}) \setminus \text{alp}(w_i) \not\subset \text{alp}(w''_i) \setminus \text{alp}(w_i)$. We conclude that $w''_i \preceq_{w_i} w_{i+1}$, which contradicts the fact that $(\text{rep}(w_i, P\text{Pr}(\lambda_T(v))), \preceq_{w_i})$ has a maximum element (recall that $P\text{Pr}(\lambda_T(v))$ is a univocal regular expression) and $w_{i+1} \in \text{max}_\preceq_{w_i} \text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$.

(b) On the contrary, assume that $\#: (w') > 1$. Since $h_i$ is a homomorphism from $T_i$ to $T'$, we have that $\text{alp}(w_i) \subset \text{alp}(w')$. Define string $w'_i$ as follows: $\text{alp}(w'_i) = \text{alp}(w_i)$, $\#: (w'_i) = 2$ and $\#: (w') = 1$, for every $b \in \text{alp}(w'_i) \setminus \{a\}$. Then $w'_i \preceq w'$ since $\text{alp}(w_i) \subset \text{alp}(w')$ and $\#: (w') > 1$. Thus, there exists $w''_i \in \text{min}_\text{ext}(w'_i, P\text{Pr}(\lambda_T(v)))$ such that $w'_i \preceq w''_i \preceq w'$ since $w' \in \pi(P\text{Pr}(\lambda_T(h_i(v)))) = \pi(P\text{Pr}(\lambda_T(v)))$. By definition of $\text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$ we have that $w''_i \in \text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$. Given that $\#: (w''_i) \geq \#: (w'_i) > 1$, $\#: (w_{i+1}) = 1$ and $\#: (w_i) > 1$, we conclude that $w''_i \preceq_{w_i} w_{i+1}$, which contradicts the fact that $(\text{rep}(w_i, P\text{Pr}(\lambda_T(v))), \preceq_{w_i})$ has a maximum element (recall that $P\text{Pr}(\lambda_T(v))$ is a univocal regular expression) and $w_{i+1} \in \text{max}_\preceq_{w_i} \text{rep}(w_i, P\text{Pr}(\lambda_T(v)))$. This concludes the proof of the claim.

B.4 Proof of Claim 6.17

By contradiction, assume that there exist strings $w_1, w_2$ and $a \in \text{alp}(r)$ such that $\text{rep}(w_1, r) \neq \emptyset$, $w_2 \in \text{max}_\preceq_{w_1} \text{rep}(w_1, r)$ and $2 \leq \#: (w_2) < \#: (w_1)$. Since $\#: (r) \leq 1$, we have that $w_2 \notin \text{fixed}_a(r)$ and, hence, there exists a string $w_3 \in \pi(r)$ such that $w_2 \preceq w_3$ and $\#: (w_2) < \#: (w_3)$. Let $w_4$ be a string such that $\text{alp}(w_4) = \text{alp}(w_1)$, $\#: (w_4) = \#: (w_2) + 1$ and for every $b \in \text{alp}(w_1) \setminus \{a\}$, $\#: (w_4) = 1$. Since $w_3 \preceq w_3$ and $w_3 \in \pi(r)$, we conclude that $\text{min}_\text{ext}(w_4, r) \neq \emptyset$. Let $w_5 \in \text{min}_\text{ext}(w_4, r)$. By definition of $\text{min}_\text{ext}(w_a, r)$, we have that $\#: (w_5) \geq \#: (w_4) > \#: (w_2)$, and by definition of $w_4$ and $\text{rep}(w_1, r)$, we have that $w_5 \in \text{rep}(w_1, r)$. We conclude that there exists a string $w_5 \in \text{rep}(w_1, r)$ such that $\#: (w_2) < \#: (w_5)$. Thus, given that $\#: (w_2) < \#: (w_1)$, we have that $w_5 \preceq_{w_1} w_2$, which contradicts the fact that $w_2 \in \text{max}_\preceq_{w_1} \text{rep}(w_1, r)$ and $(\text{rep}(w_1, r), \preceq_{w_1})$ has a maximum element.
B.5 Proof of Claim 6.22

Let \( s \) be a string such that \( \text{alph}(s) = \text{alph}(w) \) and \( \#_a(s) = \min\{\#_a(w'), \#_a(w)\} \), for every \( a \in \text{alph}(s) \). We note that \( s \preceq w \) and \( s \preceq w' \). Since \( w' \in \pi(r) \), there exists \( s' \in \min_{\text{ext}}(s, r) \) such that \( s \preceq s' \preceq w' \). By definition of \( \text{rep}(w, r) \), we have that \( s' \in \text{rep}(w, r) \) and, hence, there exists \( i \in [1, n] \) such that \( s' \preceq_w w_i \). We conclude that \( w' \preceq_w w_i \) since (1) for every \( a \in \text{alph}(w) \) such that \( \#_a(w_i) < \#_a(w) \), we have that \( \#_a(w_i) \geq \#_a(s') \geq \#_a(s) = \#_a(w') \) and (2) \( \text{alph}(w_i) \setminus \text{alph}(w) \subseteq \text{alph}(s') \setminus \text{alph}(w) \subseteq \text{alph}(w') \setminus \text{alph}(w) \).

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