Pure bigraphs: Structure and dynamics

Citation for published version:

Digital Object Identifier (DOI):
10.1016/j.ic.2005.07.003

Link:
Link to publication record in Edinburgh Research Explorer

Published In:
Information and Computation
ALGEBRA OF COMMUNICATING PROCESSES WITH ABSTRACTION

J.A. BERGSTRA and J.W. KLOP

Centre for Mathematics and Computer Science, P.O. Box 4079, 1009 AB Amsterdam, The Netherlands

Communicated by E. Engeler
Received February 1984
Revised October 1984

Abstract. We present an axiom system ACP_r, for communicating processes with silent actions ('τ-steps'). The system is an extension of ACP, Algebra of Communicating Processes, with Milner's τ-laws and an explicit abstraction operator. By means of a model of finite acyclic process graphs for ACP_r, syntactic properties such as consistency and conservativity over ACP are proved. Furthermore, the Expansion Theorem for ACP is shown to carry over to ACP_r. Finally, termination of rewriting terms according to the ACP_r axioms is proved using the method of recursive path orderings.

Keywords. Concurrency, communicating processes, internal actions, process algebra, bisimulation, process graph, handshaking, terminating rewrite rules, recursive path ordering.

1980 Mathematics Subject Classification. 68B10, 68C01, 68D25, 68F20.


Contents

Introduction ................................... 77
ACP, Algebra of Communicating Processes .................... 77
ACP_r, Algebra of Communicating Processes with abstraction ............ 78
Summary of results ..... ........ .......... 79
Related literature ................................ 81
1. The axiom system ACP_r ..................................... 81
2. The model of finite acyclic process graphs for ACP_r ................ 82
3. The Expansion Theorem for ACP_r . ............................. 100
Appendix A. Termination of ACP_r, reductions proved by recursive path orderings ... 105
Appendix B. An inductive proof of associativity of merge in ACP_r .......... 115
References ................................... 121

Introduction

ACP, Algebra of Communicating Processes

In [2] we have introduced ACP (Algebra of Communicating Processes). ACP is an equational specification of process cooperation, aiming at an algebraic theory.
of processes; more specifically, ACP gives an equational framework for asynchronous process cooperation via synchronous communication. As an axiom system, it consists of the left column of Table 2 below. For a more extensive motivation of ACP as well as a discussion of related approaches, we refer to [2]. Here we will only mention that ACP is derived from Milner's Calculus of Communicating Systems (CCS); a discussion of the differences, both in the technical sense, as regards the signature, and in the methodological sense, is again contained in [2]. We will discuss two of these differences here: CCS has prefix multiplication (atomic process "a" and process q yield a · q) whereas ACP admits general multiplication (processes p, q yield p · q, the sequential composition). This is important for the expressive power: it is not hard to prove that several recursively defined processes have finite recursive definitions in terms of general multiplication, but not in terms of prefix multiplication. Now this adoption of general multiplication brings with it the introduction of a constant δ for deadlock: namely consider the process p · q where $p = δ_{(a,b)}(a \parallel b)$, that is: the communication of steps a, b (encapsulated by $δ_{(a,b)}$). Now if a, b cannot communicate, execution of p · q will not reach q. So p is a process which 'blocks' q. Indeed, in the ACP formalism the consequence of $a \parallel b = δ$ ($a, b$ do not communicate) is that $p = δ$ and now $p · q = δ · q = δ$. In prefix multiplication, $δ_{(a,b)}(a \parallel b) · q$ would not be a well-formed expression.

One of the aims of ACP is to keep track of the various models ('process algebras') which this axiomatisation has, rather than fixing a model right away as is done in CCS or related work in Hoare's CSP. Models of ACP can be given as projective limits of process algebras consisting of finite processes (see [4]), or as metrical completions of such process algebras (see [1]), or via process graphs. The latter method starts with a suitable domain of process graphs, i.e., rooted multidigraphs with edges labeled by atomic actions. Already here, there is a great variety of possibilities, as to the choice of an upper bound for the branching degrees, the cardinality of the node sets, etc. For instance, one may restrict the attention to regular process graphs, or, as is done below, to finite process graphs without cyclic paths. Having such a domain of process algebras, a suitable equivalence relation is divided out, e.g., bisimulation (⇔). This notion derives from Milner's notion of strong equivalence on synchronisation trees (see [12]). For a proof-theoretical analysis of ACP, yielding results such as consistency of the axioms and an elimination property, we refer to [2].

ACP⊥, Algebra of Communicating Processes with abstraction

ACP as briefly discussed above does not address the problem of abstraction ('hiding'), i.e., it does not deal with the so-called τ-steps (invisible or silent steps) of Milner. Now, ACP⊥ is an extension of ACP which does take the presence of τ-steps into account. As an axiom system, ACP⊥ is displayed in Table 2 below; it consists of ACP, in the left column, together with Milner's well-known 'τ-laws' T1-3. What is new in ACP⊥ as compared with CCS is that ACP⊥ also specifies the
behaviour of \( \tau \)-steps in relation with the communication merge operator \( \parallel \), an operator which is not present in CCS but which is vital for giving a finite axiomatisation of merge \( \parallel \) as ACP does. (This is rather sensitive: e.g., \( \tau a \parallel b \) must yield the same process as \( (\tau a + a) \parallel b \), obtained by application of the \( \tau \)-law \( \tau a = \tau a + a \). Indeed it does: \( (\tau a + a) \parallel b = \tau a \parallel b + a \parallel b = a \parallel b + a \parallel b = a \parallel b = \tau a \parallel b \). Also, care had to be taken that the \( \tau \)-laws are 'compatible' with the other auxiliary operator \( \parallel \); see similar Examples 2.22.)

Another new feature in the treatment of \( \tau \)-steps in ACP\(_{r}\) is that in CCS communication between two atomic steps \( a, b \) yields a \( \tau \)-step at once (if \( a, b \) are communication 'partners'). In ACP\(_{r}\), the abstraction act is separated from the communication: abstraction is executed by a special operator \( \tau_1 \). So \( a \parallel b \) is not \( \tau \) right away, but first yields an internal (but still 'visible') step, say \( i \), which later can be abstracted, i.e., renamed into \( \tau : \tau(i)(a \parallel b) = \tau(i)(i) = \tau \). This separation of communication and abstraction turns out to be vital since recursion and abstraction do not commute. E.g., if processes \( X, Y \) are defined by recursion equations \( X = aX, Y = bY \), then with \( a \parallel b = \tau \) we would get, for the parallel process \( Z = \delta_{(a,b)}(X \parallel Y) \), the recursion equation \( Z = \tau Z \). The problem is that in the presence of the \( \tau \)-laws T1-3, such '\( \tau \)-guarded' recursion equations have no unique solution, i.e., \( Z \) is underspecified; indeed, every \( Z = \tau p \) is a solution of \( Z = \tau Z \) for arbitrary \( p \). Using the \( \tau_1 \)-operator, the intended \( Z \) (i.e., the process "\( \tau \)°") is easily defined, namely by putting \( a \parallel b = i \) and

\[
Z = \tau(i)(\delta_{(a,b)}(X \parallel Y)).
\]

This matter is not pursued in the present paper, but these remarks may serve as a motivation for \( \tau_1 \). In the present paper we are not concerned with explorations of the expressive power of ACP\(_{r}\) but simply with introducing this system and proving some fundamental theorems about it so that it can serve as a firm basis for further explorations.

**Summary of results**

In Section 1, the signature of ACP\(_{r}\) and the axioms of ACP\(_{r}\) are given. This signature extends that of ACP by the presence of \( \tau_1 \) and \( \tau \); all axioms involving them are in the right column of Table 2.

In Section 2 we give a simple model for ACP\(_{r}\), consisting of finite process graphs without cycles, modulo an equivalence relation \( \equiv\tau_r \) called rooted \( \tau \)-bisimulation. Here, '\( \tau \)-bisimulation' \( (\equiv\tau \) in our notation) coincides with Milner's well-known notion of observational equivalence, at least for finite processes. A problem with observational equivalence, or \( \tau \)-bisimulation, is that it is not a congruence w.r.t. the operations \( + \) and \( \parallel \) (the typical example is that while \( \tau a \equiv a, a \equiv b, \) one has \( \tau a + b \not\equiv a + b \)). Therefore, we consider a mild variant of it, \( \equiv\tau \), which is a congruence w.r.t. all operators. For an algebraic approach it seems essential to work with congruences; thus we can take the quotient algebra of the domain of finite acyclic processes modulo \( \equiv\tau \), and this algebra is proved in Theorem 2.23 to be
isomorphic to the initial algebra of ACP. Otherwise said, ACP is a complete axiomatisation for this process algebra. (The completeness of the \( \tau \)-laws for finite processes was first proved by Milner, as stated in [12], for the smaller signature as favoured by CCS.) This proof, which also entails the conservativity of ACP over ACP (i.e., no unwanted identifications are caused by the extension from ACP to ACP), makes a typical use of the underlying graph domain. An important ingredient in the proof is the use of some very simple transformations of process graphs. These transformations tend to normalize a process graph; a key fact (Theorem 2.12) states that each \( \tau \)-bisimulation equivalence class contains a unique normal graph. Another important fact, of independent interest, used in the proof is the Elimination Theorem 2.20 stating that the 'defined' operators \( \|, \|, \|, \|, \tau \) can all be eliminated (in a finite process) in favour of the 'basic constructors' + and \( \cdot \). Since the proof of the Elimination Theorem requires quite some work, it is contained in Appendix A. The method used to prove the termination of the rewrite rules, which tend to eliminate the defined operators, is that of the 'recursive path ordering' as described by Dershowitz, based on Kruskal's Tree Theorem. In proofs like this termination proof, it is important to have an axiomatisation as ACP gives, which lends itself to simple rewrite rules. Appendix A gives next to the actual application of the recursive path ordering method to the ACP-termination problem, a (mostly notational) restatement of the r.p.o. method which we find helpful when we actually use it for a rather complicated rewrite system as the one under consideration.

Section 3 proves the Expansion Theorem for ACP (Theorem 3.9). This theorem, first proved by Milner [12] for CCS, was proved in [5] for ACP. The extension to ACP turns out to be nontrivial, but the theorem, which is indispensable for breaking down merge expressions \( x_1 \| \ldots \| x_k \), fortunately holds in exactly the same form as for ACP:

\[
x_1 \| \ldots \| x_k = \sum_{1 \leq i \leq k} x_i \| X_i^k + \sum_{1 \leq i < j \leq k} (x_i \| x_j) \| X_{ij}^k,
\]

where \( X_i^k \) stands for the merge of \( x_1, \ldots, x_k \) except \( x_i \), and \( X_{ij}^k \) is the merge of \( x_1, \ldots, x_k \) except \( x_i, x_j \). (Note that the auxiliary operators \( \|, \| \) make a succinct formulation possible.)

Finally, in Appendix B we prove by a straightforward induction on term formation the associativity of merge \( \| \); by a different, indirect, method this is also done in Section 3 (Corollary 3.8) but we have preferred also to include the proof in Appendix B because it is entirely algebraical, using the axioms of ACP, thus demonstrating their ease in computations (the second half of the proof in Appendix B uses a complicated simultaneous induction, though), and because it proves more, viz. several identities which are of independent interest.

We conclude this introduction with some remarks about related literature (for a more comprehensive comparison, see [2]).
Related literature

ACP, was defined in [4]; the subsystem ACP was defined in [2]. Abstraction was studied in [3]. The formulation of the Expansion Theorem is taken from [5].

Both ACP and ACP, have been derived from Milner's CCS [12]. In particular, CCS contains the operators +, $\parallel$, $a \cdot$ for each atom $a$ and derives as laws: A1, A2, A3 and T1, T2, T3. The axioms C1, C2 are from Hennessy [10]; Winskel [13] surveys communication formats of atomic actions. The operator $\cdot$ is present in Hoare's CSP [11] as "\;" and in [1] as "$\circ$". We refer to Graf and Sifakis [9] for a proof-theoretic discussion of the $\tau$-laws. Brookes and Rounds [6] give an explicit description of bisimulation modulo $\tau$ on finite graphs.

1. The axiom system ACP,

Let $A$ be a finite set of atomic actions, containing a constant $\delta$, and let $\cdot |: A \times A \to A$ be a communication function which is commutative and associative and for which $\delta | a = \delta$. A communication $a | b = c$ is said to be proper if $c \neq \delta$. Further, we consider the constant $\tau$, for the silent action; we write $A_\tau = A \cup \{\tau\}$. Silent actions are obtained from applications of the abstraction operator $\tau_I$ which renames atoms $e I \subseteq A$ into $\tau$.

The signature of the equational theory ACP, is given in Table 1. Here the first five operators are binary, $\delta_H$ and $\tau_I$ are unary. The operation $\delta_H$ renames the atoms in $H$ into $\delta$, and $\tau_I$ renames the atoms in $I$ into $\tau$.

The initial algebra of the equational theory ACP, in Table 2 is called $A_{\tau}$.

| \(+\) | alternative composition (sum) |
| \(\cdot\) | sequential composition (product) |
| \(\parallel\) | parallel composition (merge) |
| \(\mid\) | left-merge |
| $\delta_H$ | communication merge |
| $\tau_I$ | encapsulation |
| $\tau$ | abstraction |
| $\delta$ | deadlock/failure |
| $\tau$ | silent action |

The communication function $\parallel$ is extended to the communication merge, having the same notation, between processes (i.e., elements of a model of ACP,).

The left column in Table 2 is the axiom system ACP (without $\tau$). In Table 2, "$a$" varies over $A$.

The axioms T1, T2, T3 are the \textquoteleft\textquoteleft $\tau$-laws\right\textquoteright\ from Milner [12].

Notation: Often we will write $xy$ instead of $x \cdot y$.

The initial algebra of the equational theory ACP, in Table 2 is called $A_{\tau}$. 
Table 2. ACP_τ

<table>
<thead>
<tr>
<th>Expression</th>
<th>Rule</th>
</tr>
</thead>
<tbody>
<tr>
<td>( x + y = y + x )</td>
<td>A1</td>
</tr>
<tr>
<td>( x + (y + z) = (x + y) + z )</td>
<td>A2</td>
</tr>
<tr>
<td>( x + x = x )</td>
<td>A3</td>
</tr>
<tr>
<td>( (x + y)z = xz + yz )</td>
<td>A4</td>
</tr>
<tr>
<td>( (xy)z = x(yz) )</td>
<td>A5</td>
</tr>
<tr>
<td>( x + \delta = x )</td>
<td>A6</td>
</tr>
<tr>
<td>( \delta x = \delta )</td>
<td>A7</td>
</tr>
<tr>
<td>( a \mid b = b \mid a )</td>
<td>C1</td>
</tr>
<tr>
<td>( (a \mid b) \mid c = a \mid (b \mid c) )</td>
<td>C2</td>
</tr>
<tr>
<td>( \delta \mid a = \delta )</td>
<td>C3</td>
</tr>
<tr>
<td>( x</td>
<td></td>
</tr>
<tr>
<td>( a \mid x = ax )</td>
<td>CM2</td>
</tr>
<tr>
<td>( (ax) \mid y = a(x \mid y) )</td>
<td>CM3</td>
</tr>
<tr>
<td>( (x + y) \mid z = x \mid z + y \mid z )</td>
<td>CM4</td>
</tr>
<tr>
<td>( (ax) \mid b = (a \mid b)x )</td>
<td>CM5</td>
</tr>
<tr>
<td>( a \mid (bx) = (a \mid b)x )</td>
<td>CM6</td>
</tr>
<tr>
<td>( (ax)(by) = (a \mid b)(x \mid y) )</td>
<td>CM7</td>
</tr>
<tr>
<td>( (x + y) \mid z = x \mid z + y \mid z )</td>
<td>CM8</td>
</tr>
<tr>
<td>( x \mid (y + z) = x \mid y + x \mid z )</td>
<td>CM9</td>
</tr>
<tr>
<td>( \delta_H(\tau) = \tau )</td>
<td>DT</td>
</tr>
<tr>
<td>( \tau_1(\tau) = \tau )</td>
<td>T1</td>
</tr>
<tr>
<td>( \delta_H(a) = a ) if ( a \in H )</td>
<td>D1</td>
</tr>
<tr>
<td>( \delta_H(a) = \delta ) if ( a \notin H )</td>
<td>D2</td>
</tr>
<tr>
<td>( \delta_H(x + y) = \delta_H(x) + \delta_H(y) )</td>
<td>D3</td>
</tr>
<tr>
<td>( \delta_H(xy) = \delta_H(x) \cdot \delta_H(y) )</td>
<td>D4</td>
</tr>
<tr>
<td>( \delta \mid a \mid b = b \mid a \mid \delta )</td>
<td>A8</td>
</tr>
</tbody>
</table>

2. The model of finite acyclic process graphs for ACP_τ

A process graph over \( A_\tau \) is a rooted, directed multigraph such that every node is accessible from the root and whose edges are labeled by elements from \( A_\tau \). A process graph is finite if it has finitely many edges and nodes; it is acyclic when it contains no cyclic path, i.e., there are no edges \( h_i = s_i \rightarrow s_{i+1} \) \( (i < k, l_i \in A_\tau) \) and nodes \( s_j (j \leq k) \) such that

\[
\begin{align*}
S_0 & \xrightarrow{l_0} s_1 \xrightarrow{l_1} \cdots \xrightarrow{l_{k-1}} s_k = S_0 \quad (k \geq 1).
\end{align*}
\]

Let \( G \) be the collection of finite acyclic process graphs over \( A_\tau \). In order to define the notion of bisimulation on \( G \), we will first introduce the notion of \( \delta \)-normal process graph. A process graph \( g \in G \) is \( \delta \)-normal if whenever an edge

\[
S \xrightarrow{\delta} T
\]

occurs in \( g \), then the node \( s \) as outdegree 1 and the node \( t \) has outdegree 0. In
anthropomorphic terminology, let us say that an edge
\[ \delta \rightarrow \tau \] is an ancestor of \[ \delta' \rightarrow \tau' \]
if it is possible to move along edges from \( t \) to \( s' \); likewise, the latter edge will be
called a descendant of the former. Edges having the same begin node are brothers.
So, a process graph \( g \) is \( \delta \)-normal if all its \( \delta \)-edges have no brothers and no
descendants.

Note that for \( g \in G \) the ancestor relation is a partial order on the set of edges of \( g \).

We will now associate to a process graph \( g \in G \) a unique \( g' \) in \( \delta \)-normal form,
by the following procedure:

1. nondeterministic \( \delta \)-removal is the elimination of a \( \delta \)-edge having at least one
   brother,
2. \( \delta \)-shift of a \( \delta \)-edge

\[ \delta \rightarrow \tau \]
in \( g \) consists of deleting this edge, creating a fresh node \( t' \) and adding the edge
\[ \delta \rightarrow \tau' \].

Now it is not hard to see that the procedure of repeatedly applying (in arbitrary
order) (1), (2) in \( g \) will lead to a unique graph \( g' \) which is \( \delta \)-normal; this \( g' \) is the
\( \delta \)-normal form of \( g \). It is understood that pieces of the graph which have become
disconnected from the root, are discarded.

**Example**

![Fig. 1.](image)

We can now define bisimulation between process graphs \( g_1, g_2 \in G \). First some
preliminary notions: a trace \( \sigma \) is a possibly empty finite string over \( A_\tau \); thus, \( \sigma \in A_\tau^\ast \). With \( e(\sigma) \) we denote the trace \( \sigma \) where all \( \tau \)-steps are erased, e.g., \( e(\alpha \tau \tau \beta \tau \tau \tau) = abc \).

If \( g \in G \), a path \( \pi: s_0 \rightarrow s_k \) in \( g \) is a sequence of edges of the form

\[ \delta_0 \overset{l_0}{\longrightarrow} \delta_1 \overset{l_1}{\longrightarrow} \cdots \overset{l_{k-1}}{\longrightarrow} \delta_k \quad (k \geq 0) \]

where the \( s_i \) are nodes of \( g \), the \( h_i \) are edges between \( s_i \) and \( s_{i+1} \), and each \( l_i \in A_\tau \).
is the label of edge \( h_i \). (The \( h_i \) are needed because we work with multigraphs.) The trace \( \text{trace}(\pi) \) associated to this path \( \pi \) is just \( l_0l_1 \ldots l_{k-1} \).

2.1. Definition. A \textit{bisimulation modulo} \( \tau \) (or \( \tau \)-\textit{bisimulation}) between finite acyclic process graphs \( g_1 \) and \( g_2 \) is a relation \( R \) on \( \text{NODES}(g_1) \times \text{NODES}(g_2) \) satisfying the following conditions:

(i) \((\text{ROOT}(g_1), \text{ROOT}(g_2)) \in R\).

(ii) For each pair \((s_1, s_2) \in R\) and for each path \( \pi_1 : s_1 \rightarrow t_1 \) in \( g_1 \) there is a path \( \pi_2 : s_2 \rightarrow t_2 \) in \( g_2 \) such that \((t_1, t_2) \in R\) and \( e(\text{trace}(\pi_1)) = e(\text{trace}(\pi_2)) \) (see Fig. 2(a)).

(iii) Likewise for each pair \((s_1, s_2) \in R\) and for each path \( \pi_2 : s_2 \rightarrow t_2 \) in \( g_2 \) there is a path \( \pi_1 : s_1 \rightarrow t_1 \) in \( g_1 \) such that \((t_1, t_2) \in R\) and \( e(\text{trace}(\pi_1)) = e(\text{trace}(\pi_2)) \) (see Fig. 2(b)).

Let \( g_1, g_2 \) be in \( \delta \)-normal form. Then \( g_1, g_2 \) are \textit{bisimilar modulo} \( \tau \) (or \( \tau \)-\textit{bisimilar}) if there is a \( \tau \)-bisimulation between \( g_1, g_2 \).

Notation: \( g_1 \leftrightarrow_{\tau} g_2 \).

Note that for a \( \tau \)-bisimulation \( R \) between \( g_1, g_2 \) we have: Domain\((R) = \text{NODES}(g_1)\) and Codomain\((R) = \text{NODES}(g_2)\). Also note that an equivalent definition is obtained by letting \( \pi_1 \) in Definition 2.1(ii) consist of one edge, likewise \( \pi_2 \) in (iii).

Strictly speaking we should say that \( R \) as in Definition 2.1 is a \( \tau \)-bisimulation from \( g_1 \) to \( g_2 \) rather than between \( g_1, g_2 \). Note that if \( R \) is a \( \tau \)-bisimulation from \( g_1 \) to \( g_2 \), the converse relation \( R^{-1} \) (defined by \((s, t) \in R^{-1} \Leftrightarrow (t, s) \in R\)) is a \( \tau \)-bisimulation from \( g_2 \) to \( g_1 \).

2.2. Definition. Let \( g_1, g_2 \in G \) be in \( \delta \)-normal form. A \textit{rooted bisimulation modulo} \( \tau \) between \( g_1, g_2 \) is a bisimulation modulo \( \tau \) between \( g_1, g_2 \) such that the root of \( g_1 \) is not related to a non-root node of \( g_2 \), and vice versa.

Notation: \( g_1 \leftrightarrow_{r \tau} g_2 \).

2.3. Definition. Let \( g_1, g_2 \in G \) with \( \delta \)-normal forms \( g_1', g_2' \) respectively. Then \( g_1 \leftrightarrow_{r \tau} g_2 \) if \( g_1' \leftrightarrow_{r \tau} g_2' \).
2.4. Examples

\[ a\tau b\delta \Leftrightarrow_{rr} ab\delta \]  
(Fig. 3(a)),

\[ ab \Leftrightarrow_{rr} a\tau (\tau b + \tau b) \]  
(Fig. 3(b)),

\[ a(\tau b + b) \Leftrightarrow_{rr} ab \]  
(Fig. 3(c)),

\[ c(a + b) \Leftrightarrow_{rr} c(\tau(a + b) + a) \]  
(Fig. 3(d)).

For a negative example, see Fig. 3(e). The heavy line denotes where it is not possible to continue a construction of the bisimulation.

Fig. 3.

Since we intend to construct from \( G \) a model for ACP, we will now define operations \( +, \cdot, \parallel, \parallel_{L}, \delta_{H}, \tau_{I} \) on \( G \). (Cf. [3] where \( +, \cdot, \parallel, \parallel_{L} \) were defined in the context of the axiom system PA.)

1. The sum \( g_{1} + g_{2} \) is the result of identifying the roots of \( g_{1}, g_{2} \).
2. The product \( g_{1} \cdot g_{2} \) is the result of appending \( g_{2} \) at all end nodes of \( g_{1} \).
3. The merge \( g_{1} \parallel g_{2} \) is the 'cartesian product graph' of \( g_{1}, g_{2} \), enriched by 'diagonal' edges for nontrivial communication steps, as follows: if

\[
\begin{array}{c}
a \\
\text{b} \\
\text{a} \\
\text{b} \\
a
\end{array}
\]
is a subgraph of the cartesian product graph, then the arrow $\circ \rightarrow \circ$ (where $c = a \mid b$) is inserted; result:

(Here $\tau$ has only trivial communications: $\tau \mid a = \tau \mid \tau = \delta$.)

**Example.** Let $A_\tau = \{a, b, c, \tau, \delta\}$, where the only nontrivial communication is: $a \mid b = c$. Then, writing $ab$ for the graph

we have: $ab \parallel bab\tau$ is the process graph as in Fig. 4(a).

![Fig. 4](image)

(4) The left merge $g_1 \parallel g_2$ is like $g_1 \parallel g_2$ but omitting all steps which are not a first step from $g_1$ or the descendant of such a first step.

**Example:** In the situation of the previous example we have $ab \parallel bab\tau$ as the graph in Fig. 4(b) and $bab\tau \parallel ab$ as in Fig. 4(c).

(Note that we have omitted the diagonal edges labeled with $\delta$, resulting from trivial communications. This is allowed in view of our preference of $\delta$-normal graphs. Indeed, a 'diagonal' $\delta$-edge can always be omitted by (1) of the $\delta$-normalization procedure.)

(5) The communication merge $g_1 \mid g_2$ is harder to define since it is in general not, as $g_1 \parallel g_2$ is, a subgraph of $g_1 \parallel g_2$. The reason behind the definition can be understood by considering, e.g., $\tau t a x \mid \tau t t b y$ and evaluating this term according to the axioms of ACP:

$\tau t a x \mid \tau t t b y = a x \mid b y = (a \mid b) \cdot (x \parallel y)$.

We define:

$g_1 \mid g_2 = \sum \{(t \rightarrow s) \cdot (g_1 \parallel g_2)_s \mid t \rightarrow s$ is a maximal communication in $g_1 \parallel g_2$ such that $t$ can be reached from the root via a sequence of $\tau$-steps\}.
Here, 'maximal' refers to the p.o. given by the ancestor relation. The sequence of \( \tau \)-steps may be empty. Further, \( (g) \), denotes the subgraph of \( g \) with root \( s \).

**Example.** (i) Let \( g_1 = \tau ard, g_2 = \tau rbd. \) Let \( a \mid b = c \) be the only nontrivial communication. Then \( g_1 \parallel g_2 \) is as in Fig. 5(a) and \( g_1 \mid g_2 \) as in Fig. 5(b):

![Diagram 5](image)

Here the heavily drawn edge \( \circ \rightarrow \circ \) is an edge \( t \rightarrow s \) as in the definition of \( g_1 \mid g_2 \).

(ii) Let

\[
g_1: \quad \begin{array}{ccc}
& b & \\
\quad & a & \\
\tau & & \\
& & \\
& d & \end{array}
\quad \text{and} \quad g_2: \quad \begin{array}{ccc}
& & \\
& a & \\
\tau & & \\
& & \\
& b & \end{array}
\]

where the only nontrivial communications are \( a \mid a = a^0 \) and \( b \mid b = b^0 \). Then \( g_1 \parallel g_2 \) and \( g_1 \mid g_2 \) are as in Fig. 6(a), (b) respectively:

![Diagram 6](image)

Using \( \text{ACP}_\tau \) we calculate with terms corresponding to \( g_1, g_2 \):

\[
(ba + \tau a) \mid (ab + \tau b) = ba \mid ab + ba \mid \tau b + \tau a \mid ab + \tau a \mid \tau b
\]

\[
= (b \mid a) \cdot (a \parallel b) + ba \mid b + a \mid ab + a \mid b = b^0 a + a^0 b + b = b^0 a + a^0 b.
\]

(6) The definition of the operators \( \delta_H, \tau_1 \) on process graphs \( g \in G \) is easy: they merely rename some atoms (labels at the edges) into \( \delta, \tau \) respectively.

This ends the definition of the structure \( G = G(+) \cdot \mid \parallel \), \( \delta_H, \tau_1 \). The domain of process graphs \( G \) itself is not yet a model of \( \text{ACP}_\tau \) (e.g., \( G \models x + x = x \)). However, we have the following theorem.
2.5. Theorem

(i) Rooted \( \tau \)-bisimulation \( \equiv_{\tau r} \) is a congruence on \( G \).

(ii) \( G / \equiv_{\tau r} \) is a model of ACP\( _r \).

Proof. (i) Let \( g, g', h, h' \in G \). We want to show that

\[
g \equiv_{\tau r} g' \land h \equiv_{\tau r} h' \Rightarrow g \parallel h \equiv_{\tau r} g' \parallel h'
\]

and likewise for the other operators. Only the cases \( \parallel, \perp, \mid \) are interesting and we start with \( \parallel \).

Suppose, then, that \( S \) is an \( \tau \tau \)-bisimulation between \( g, g' \) and \( T \) is an \( \tau \tau \)-bisimulation between \( h, h' \). Let \( s \) be a typical node of \( g \), \( s' \) of \( g' \), \( t \) of \( h \), and \( t' \) of \( h' \). Then we define the following relation \( S \times T \) between the node sets of \( g \parallel h \) and \( g' \parallel h' \):

\[
((s, t), (s', t')) \in S \times T \iff (s, s') \in S \land (t, t') \in T.
\]

We claim that \( S \times T \) is an \( \tau \tau \)-bisimulation between \( g \parallel h \) and \( g' \parallel h' \).

Proof of the claim. (1) Let \( (s_1, t_1) \xrightarrow{\tau} (s_1, t_2) \) be a 'horizontal step' in \( g \parallel h \), where \( u \in A_{\tau} \). Let \( ((s_1, t_1), (s'_1, t'_1)) \in S \times T \). Then \( t_1 \xrightarrow{u} t_2 \) in \( h \) and \( (t_1, t'_1) \in T \). Hence, a path as in the definition of bisimulation can be found whose trace is externally equivalent to \( u \) and whose end point bisimulates with \( t_2 \). This path can be 'lifted' to \( g \parallel h \).

(2) Likewise for a 'vertical step' in \( g \parallel h \).

(3) \( (s_1, t_1) \xrightarrow{\tau} (s_2, t_2) \) is a 'diagonal step' (a communication step) in \( g \parallel h \), and \( ((s_1, t_1), (s'_1, t'_1)) \in S \times T \). Now a path as required can be found from the data \( (s_1, s'_1) \in S \) and \( (t_1, t'_1) \in T \) and an inspection of Fig. 7.

The case of \( \perp \) is easy since \( g \parallel h \) is a subgraph of \( g \parallel h \).

For the case of \( \mid \) we use the same notation as above. We have to prove

\[
g \parallel h \equiv_{\tau r} g' \parallel h'.
\]
An $\tau\tau$-bisimulation between $g \parallel h$ and $g' \parallel h'$ can now be constructed as follows from $S \times T$. The graph $g \parallel h$ is now the sum of the $c_i \cdot (g \parallel h)_{(s_i,t_i)}$ ($i = 1, 2$) as in the definition of $|$ and as indicated in Fig. 8(a).

![Fig. 8.](image)

For the sake of clarity, we will formally distinguish the ‘diagonal’ edges from the other ones; this can be done by a suitable renaming of the alphabet and adapting the communication function. Thus, if $a \parallel b = c$, we adopt a fresh symbol $\tilde{c}$ and postulate $a \parallel b = \tilde{c}$. Now the underlined symbols do not occur in $g, h$ which makes it possible to speak in a formal way about ‘diagonal’ steps. Note that the bisimulation $S \times T$ is also a bisimulation when diagonal steps are marked as such.

Now given a summand $p = c_i \cdot (g \parallel h)_{(s_i,t_i)}$ of $g \parallel h$, we can find via $S \times T$ a corresponding summand $p' = c_i \cdot (g' \parallel h')_{(s_i,t_i)}$. It is easy to see that the step $c_i$ in $g' \parallel h'$ is also maximal in the sense of the definition of $|$. Clearly, $p$ bisimulates with $p'$ via the restriction of $S \times T$ to the appropriate area. In this way we find that $g \parallel h$ bisimulates with $g' \parallel h'$.

(ii) The proof that $\mathcal{G}\models \mathcal{ACP}_\tau$ is a model of ACP$_\tau$ is tedious and routine. We will sketch some of it: the soundness of the axioms A1–7 is easy; e.g., associativity of $+$, $\cdot$ and commutativity of $+$ follow at once from properties of graphs; soundness of A3, $x + x = x$, is a simple consequence of properties of bisimulation and A6, 7 follow because the graphs in $\mathcal{G}$ are in $\delta$-normal form. The axiom groups for $\delta_H$ and $\tau_I$ are trivially sound. The $\tau$-laws T1–3 are proved sound by constructing the appropriate $\tau\tau$-bisimulation. For an axiom as CM1 an $\tau\tau$-bisimulation between the graphs $g \parallel h$ and $g \parallel h + h \parallel g + g \parallel h$ is constructed by connecting nodes in $g \parallel h$, $h \parallel g$, $g \parallel h$ to corresponding nodes in $g \parallel h$, where ‘corresponding’ refers to the way in which $g \parallel h$, $h \parallel g$, $g \parallel h$ are directly constructed from $g \parallel h$. Finally, axioms as CM2–9, TM1, 2, TC1–4 are easily dealt with.

We will now analyse $\equiv_{\tau\tau}$ into an equivalence generated by certain elementary graph reductions. This is done in [3] for $\tau$-bisimulation (without the condition ‘rooted’) and in the absence of $\delta$; these results will be the basis for the sequel. We repeat from [3] the main definitions.
2.6. Definition. Let $g \in G$.

(i) A subgraph $g'$ of $g$ consists of an arbitrary subset of the set of edges of $g$ (plus their labels $\in A_r$) together with the nodes belonging to these edges.

(ii) Let $s \in \text{NODES}(g)$. Then $(g)_s$ is the subgraph of $g$ consisting of all nodes and edges which are accessible from $s$ (including $s$, the root of $(g)_s$). We will call $(g)_s$ a full subgraph.

(iii) An arc in $g$ is a subgraph of the form as in Fig. 9(a), where $u \in A_r$. The $u$-edge at the left is called the primary edge of the arc. If, in Fig. 9(a), $n = m = 0$, the arc has the form as in Fig. 9(b) and is called of type I. If $n + m = 1$, the arc has the form as in Fig. 9(c) or (d) and is called of type II, III respectively. Arcs of type I, II, III are called elementary arcs.

2.7. Definition. On $G$ we define the following reduction procedures:

[i] Sharing. Let $g \in G$ contain nodes $s_1, s_2$ such that $(g)_{s_1}$ is isomorphic to $(g)_{s_2}$. Then $g$ reduces to $g'$ where $s_1, s_2$ are identified.

[ii] Removal of a non-initial deterministic $\tau$-step. If $s_1 \xrightarrow{\tau} s_2$ occurs in $g$ and the outdegree of $s_1$ is one (so the displayed $\tau$-step has no brothers), and if, moreover, $s_1$ is not the root of $g$, then the nodes $s_1, s_2$ may be identified after removal of the $\tau$-step.

[iii] Arc reduction. In an arc, the primary edge may be deleted. The arc reduction is called of type I, II, III if the arc is of that type. Such arc reductions are also called elementary.

So the subgraph as in Fig. 10(a) may be replaced by that in Fig. 10(b):
[iv] Nondeterministic $\delta$-removal, as explained in the beginning of this section.
[v] $\delta$-shift; also defined above.

If none of the reduction possibilities in [i]-[v] applies to $g$, then we call $g$ a normal process graph.

Notation. If $g$ reduces to $g'$ by one application of [i]-[v], we write $g \rightarrow g'$. The transitive reflexive closure of $\rightarrow$ is denoted by $\rightarrow\rightarrow$.

2.8. Example

(i)

![Diagrams for 2.8. Example (i)]

Fig. 11.

(ii)

![Diagrams for 2.8. Example (ii)]

Fig. 12.
2.8.1. Remark. As the last example suggests, the process graph reduction $\rightarrow$ is in fact confluent (has the Church-Rosser property). A proof of the confluency can be obtained by the following trivial proposition (2.9) together with an analysis of the 'elementary diagrams' as in Example 2.8(iii) above, showing the weak confluency property: if $g_1 \rightarrow g_2$ and $g_1 \rightarrow g_3$, then there is a $g_4$ such that $g_2 \rightarrow g_4$ and $g_3 \rightarrow g_4$. Establishing this weak confluency directly, is rather complicated though; much easier is the following way, indicated in Remark 2.14. We will not need the confluency of the graph reductions in the sequel.

The following fact is trivial.

2.9. Proposition. Every process graph reduction $g_1 \rightarrow g_2 \rightarrow \cdots$ must terminate eventually.

Without the routine proof we state the 'soundness' of the reduction procedure $\rightarrow$ w.r.t. $\Leftrightarrow_r$. 
2.10. **Lemma.** Let $g_1, g_2 \in G$. Then $g_1 \leftrightarrow g_2$ implies $g_1 \Leftrightarrow_{rr} g_2$.

2.11. **Definition.** (i) Let $g \in G$ be in $\delta$-normal form. Let $R$ be an $rr$-bisimulation between $g$ and itself. Then $R$ is called an **autobisimulation** of $g$.

(ii) $g$ is **rigid** if it can only be in autobisimulation with itself via the identity relation.

2.11.1. **Example.** The process graph depicted in Fig. 14 is not rigid since it admits the displayed nontrivial autobisimulation:

![Process Graph](image)

Fig. 14.

Here $R = \{(s_1, s_1), (s_2, s_3), (s_3, s_2), (s_4, s_3), (s_3, s_4), (s_5, s_6), (s_6, s_6)\}$.

2.11.2. **Proposition.** If $g, h$ are rigid and $R$ is an $rr$-bisimulation from $g$ to $h$, then $R$ is in fact a bijection from $\text{NODES}(g)$ to $\text{NODES}(h)$.

**Proof.** Suppose there are $s_1, s_2 \in \text{NODES}(g), t \in \text{NODES}(h)$ such that $(s_1, t) \in R$, $(s_2, t) \in R$. Now if $R$ is a bisimulation from $g$ to $h$, the converse of $R$, $R^{-1}$, is a bisimulation from $h$ to $g$ and the composition $R^{-1} \circ R$ is a bisimulation from $g$ to $g$, i.e., an autobisimulation of $g$. Since $(s_1, s_2) \in R^{-1} \circ R$, it follows from the rigidity of $g$ that $s_1 = s_2$. \[\square\]

2.12. **Theorem.** (i) Normal graphs are rigid.

(ii) If $g_1, g_2$ are normal process graphs and $g_1 \Leftrightarrow_{rr} g_2$, then $g_1$ and $g_2$ must be identical.

**Proof.** We will prove (i), (ii) simultaneously with induction on the size of the process graphs involved. To be precise: Let $|g|$ be the number of edges of $g$. Consider the statements:
(i)$n$: if $g$ is a normal process graph, and $|g| \leq n$, then $g$ is rigid.
(ii)$n$: if $g_1$, $g_2$ are normal process graphs such that $|g_1|, |g_2| \leq n$ and $g_1 \equiv_{\tau} g_2$, then $g_1 = g_2$.

We will prove (i)$n$ & (ii)$n$ with induction on $n$. The basis, (i)$_1$ & (ii)$_1$, is trivial. (Note here that the one edge graph $\rightarrow_1 \circ_1$ is rigid.)

**Induction step**: suppose as induction hypothesis that (i)$_k$ & (ii)$_k$ holds for $k < n$.

To prove: (i)$_n$ & (ii)$_n$. We first prove (i)$_n$.

So let $g$ with $|g| = n$ be normal. Suppose, for a proof by contradiction, that $g$ is not rigid; then there is an $r\tau$-autobisimulation of $g$ relating unequal nodes $s$, $t$. By definition of $r\tau$-bisimulation, none of $s$, $t$ can be the root of $g$. But then the subgraphs $(g)_s$, $(g)_t$ have at least two edges less than $g$, i.e., $|(g)_s|, |(g)_t| \leq n - 2$. Clearly $(g)_s \equiv_{\tau} (g)_t$, and hence $\tau(g)_s \equiv_{\tau} \tau(g)_t$. (Here $\tau(g)_s$ results from prefixing a $\tau$-edge to $(g)_s$.) Moreover $(g)_s$, $(g)_t$ are normal since they are subgraphs of a normal graph; and since $s$, $t$ are non-root nodes, $(g)_s$, $(g)_t$, do not start with a 'deterministic' $\tau$-step and hence also $\tau(g)_s$, $\tau(g)_t$, are normal.

Now, since $|\tau(g)_s|, |\tau(g)_t| \leq n - 1$, we may apply the induction hypothesis and conclude that $\tau(g)_s = \tau(g)_t$, and hence $(g)_s = (g)_t$. But then $g$ would admit a $\tau$-step, contradicting the normality. Hence $g$ is rigid and we have proved (i)$_n$.

Next we prove (ii)$_n$, using the induction hypothesis (i)$_k$ & (ii)$_k$ ($k < n$) and (i)$_n$. So let $g_1$, $g_2$ be normal such that $g_1 \equiv_{r\tau} g_2$ and $|g_1|, |g_2| = n$. By (i)$_n$, the graphs $g_1$, $g_2$ are rigid. Let $R$ be an $r\tau$-bisimulation from $g_1$ to $g_2$. By Proposition 2.11.2, $R$ is a bijection from NODES($g_1$) to NODES($g_2$). Furthermore, we claim that $R$ maps the edges of $g_1$ bijectively to those of $g_2$; more precisely:

Claim. (1) If $s \xrightarrow{\tau} t$, $u \in A_n$ is an edge of $g_1$ and $(s, s') \in R$, then there is an edge $s' \xrightarrow{\tau} t'$ in $g_2$ for some $t'$ with $(t, t') \in R$.

(2) Likewise vice versa.

With the claim we are through, since $R$ is then an isomorphism between labeled graphs. (Intuitively, this can easily be seen by noting that a process graph $g$ without double edges can be considered as an algebraic structure, in the sense of model theory, with universe NODES($g$), a constant ROOT($g$) and binary relations $a$, $b$, $c$, ..., the labels of the edges of $g$.)

**Proof of the Claim.** (1) Let $s \xrightarrow{\tau} t$ be an edge as in (1) of the Claim. Let $(s, s') \in R$ (see Fig. 15). Suppose there is not a 'direct' step $s' \xrightarrow{\tau} t'$, $(t, t') \in R$ as we want. Then, since $R$ is an $r\tau$-bisimulation, there is a path

$$s' \xrightarrow{\tau^n} s'' \xrightarrow{u} t'' \xrightarrow{\tau^m} t'$$

from $s'$ to $t'$, $(t, t') \in R$ (see Fig. 15) such that $n + m \neq 0$. Say $n \neq 0$ (the other case, $m \neq 0$, is similar). Going 'backwards' from $s''$ with $R$ we find a node $s'''$ in $g_1$ such that $s \xrightarrow{\tau^m} s'''$, $(s'', s') \in R$. Since $n \neq 0$ and because $R$ is a bijection between the node sets of $g_1$, $g_2$, we have $s \neq s'''$, i.e., $n' \neq 0$. Likewise, the path $s'' \xrightarrow{\tau^m} t'' \xrightarrow{\tau^m} t'$ in $g_2$ is carried via $R$ backwards to $g_1$ to yield a path

$$s''' \xrightarrow{\tau^m} t$$.
By the bijectivity of $R$, $t = t^*$. But then there is an arc in $g_1$, in contradiction with the normality of $g_1$. Hence, there is a direct step $s' \rightarrow t', (t, t') \in R$.

Part (2) of the Claim is like (1), with $g_1, g_2$ interchanged. □

2.13. **Corollary.** Let $g_1, g_2 \in G$. Then the following are equivalent:

(i) $g_1 \simeq_{rr} g_2$,
(ii) $g_1, g_2$ reduce (by [i]-[v]) to the same normal graph,
(iii) $g_1, g_2$ are convertible via applications of [i]-[v].

**Proof.** Suppose (i). Reduce $g_1, g_2$ to normal $g_1', g_2'$; this is possible by Proposition 2.9. Since reduction $\rightarrow$ is sound w.r.t. $\simeq_{rr}$, also $g_1' \simeq_{rr} g_2'$. By Theorem 2.12(ii) it follows that $g_1'$ and $g_2'$ are identical; hence (ii). From (ii) we trivially have (iii). From (iii), since reduction is sound, we have again (i). □

2.14. **Remark.** As a further corollary (which we do not need here) one obtains the confluency of the graph reductions [i]-[v]. This immediately follows from the termination property of the graph reductions (Proposition 2.9), together with Lemma 2.10 and Theorem 2.12(ii).

2.15. **Corollary.** Let $g_1, g_2 \in G$. Then $g_1 \simeq_{rr} g_2$ iff $g_1, g_2$ are convertible by means of the following reductions:

[i] sharing (as in Definition 2.7);
[ii] removal of a non-initial deterministic $\tau$-step (as in Definition 2.7);
The elementary arc reductions:

Proof. Every arc can be filled up with elementary arcs, e.g.:

Therefore, every arc reduction \( g_1 \xrightarrow{\text{[iii]}} g_2 \) can be replaced by a conversion consisting of elementary arc reductions of type [iii]II or [iii]III:

In the sequel, when closed terms in the signature \((+, \cdot, a \in A,\) are mentioned, we will always mean terms modulo the basic congruence given by the axioms A1, 2, 5 in Table 2 (associativity of +, \cdot, and commutativity of +). To such terms we will refer as ‘+,--terms’ or as ‘basic terms’. 
E.g., \(a(b + c)d\) and \(a(c + b)d\) are (representations of) the same basic term; \(a(bd + cd)\) is (a representation of) a different basic term.

2.16. Definition. Let \(t\) be a basic term.

(i) Then \([t]\) denotes the interpretation of \(t\) in \(\mathcal{G}\); so \([t]\) is a process graph.

(ii) \([\llbracket t \rrbracket]\) denotes the interpretation of \(t\) in \(\mathcal{G}/\equiv_{\tau}\); so \([\llbracket t \rrbracket]\) is a process graph modulo \(\tau\)-bisimulation.

(iii) Let \(g \in G\). Let \(g'\) be the process tree obtained from \(g\) by 'unraveling' the shared subgraphs. Then \(\llbracket g \rrbracket\) is the basic term corresponding to the tree \(g'\).

Example. If \(g\) is

\[
\begin{array}{c}
\text{Example: If } g \\
\end{array}
\]

then \(g'\) is \(\frac{d}{c+b+c+e}\) and \(\llbracket g \rrbracket = dc + a(bc + e)\).

2.17. Proposition. Let \(g_1, g_2 \in G\) and suppose \(g_1 \rightarrow g_2\) via an elementary graph reduction \([i], [ii], [iii], [iv], [v]\). Then the basic terms \(\llbracket g_1 \rrbracket\) and \(\llbracket g_2 \rrbracket\) can be proved equal using the A-axioms (about \(+, \cdot, \delta\)) in Table 2, A1-7, and the \(\tau\)-laws T1-3 (see the diagram below).

\[
\begin{array}{c}
\text{Proof. In case } [i], t_1 \equiv t_2. \text{ Case } [ii] \text{ translates into an application of T1 (or several such). Case } [iii]: \text{ removal of a double edge. This translates into applications of } x + x = x \text{ (A3).}
\end{array}
\]

Case [iiiIII] translates to terms as an application of \(\tau(x + y) + x = \tau(x + y)\), where \(x = uz\) (see Fig. 16(a)), or, if \(y\) is empty, \(\tau x + x = \tau x\) (T2). The former equation follows from T2 and A3:

\[
\tau(x + y) + x = \tau(x + y) + x + y + x = \tau(x + y) + x + y = \tau(x + y).
\]

Case [iiiIII] translates to terms as an application of

\[
u(\tau z + y) = u(\tau z + y) + uz \quad (u \in A,)
\]
(see Fig. 16(b)). The case that \( u = \tau \) follows from T2; the case that \( u \neq \tau \) is just the third \( \tau \)-law T3; for \( z \) or \( y \) empty, an application of T1 is needed. \( \square \)

![Fig. 16.](image)

Now we can prove an important fact.

2.18. Lemma. Suppose \( t, s \) are basic terms. Then:

\[
\mathcal{G}/ \iff_{\mathcal{G}} t = s \Rightarrow A1-7, T1-3 \vdash t = s.
\]

Proof. Suppose \( \mathcal{G}/ \iff_{\mathcal{G}} t = s \). Then \([t]\iff_{\mathcal{G}} [s] \). By Corollary 2.15, the graphs \([t]\), \([s]\) are convertible via elementary graph reductions:

\[
[t] = g_0 \rightarrow g_1 \rightarrow \cdots \rightarrow g_n \equiv [s]. \quad \text{(Here} \rightarrow \text{is} \rightarrow \text{or} \leftarrow \text{.)}
\]

Now Proposition 2.17 states that

\[
A1-7, T1-3 \vdash [t] = [s].
\]

Since \( A1-7 \vdash [t] = t \) and likewise for \( s \), we have \( A1-7, T1-3 \vdash t = s \). \( \square \)

By a similar method (essentially by leaving out all reference to \( \tau \)) one proves the following lemma.

2.19. Lemma. Suppose \( t, s \) are basic terms not containing \( \tau \). Then:

\[
\mathcal{G}/ \iff_{\mathcal{G}} t = s \Rightarrow A1-7 \vdash t = s.
\]

2.20. Elimination Theorem. Let \( t \) be a closed term in the signature of ACP\( _\tau \). Then, using the axioms of ACP\( _\tau \), except A1-7 and the \( \tau \)-laws T1-3 as rewrite rules from left to right, \( t \) can be rewritten to a basic term \( t' \).

For the proof, see Appendix A.
Combining the previous results we now have, writing AT for the set of axioms A1-7, T1-3, the following result.

2.21. Lemma

(i) \[ t_1 \quad \text{ACP} \quad t_2 \]
\[ \text{ACP} - AT \quad \exists \quad \text{AT} \quad t_3 \quad t_4 \]

I.e., if \( \text{ACP} \vdash t_1 = t_2 \), then \( t_1 \) and \( t_2 \) can be reduced by means of the rewrite rules (from left to right) associated to the axioms in \( \text{ACP} - AT \) to basic terms \( t_3, t_4 \) which are convertible via the AT-axioms.

(ii) Every term \( t \) can be proved equal in \( \text{ACP} \) to a basic term \( t' \); moreover, \( t' \) is unique modulo AT.

Proof. (i) Suppose \( \text{ACP} \vdash t_1 = t_2 \). By the Elimination Theorem 2.20 we can rewrite \( t_1, t_2 \) to respectively basic terms \( t_3, t_4 \) using the axioms in \( \text{ACP} - AT \) as rewrite rules. By the fact that \( \mathcal{G} / \equiv \tau \) is a model of \( \text{ACP} \), we have \( \mathcal{G} / \equiv \tau \models t_3 = t_4 \). Hence (Lemma 2.18) \( \text{AT} \vdash t_3 = t_4 \).

(ii) Immediate from (i). \( \square \)

2.22. Examples. The following examples illustrate Lemma 2.21(i):

(i) \[(\tau a + a) | b \quad \tau a | b\]
\[\tau a | b + a | b \]
\[a | b + a | b \quad a | b\]

(ii) \[a \parallel b \quad a \parallel b \]
\[a(\tau \parallel b) \]
\[a(\tau \parallel b + b \parallel \tau + \tau \parallel b) \]
\[a(\tau b + b\tau + \delta) = a(\tau b + b\tau) = a(\tau b + b) = a\tau b = ab\]
Here, (*) is an instance of the (from AT) derivable rule $\tau(x + y) + x = \tau(x + y)$.

As a further corollary we have the following.

2.23. Theorem. (i) $\mathcal{G}/ \equiv_{rr}$ is isomorphic to $A_{rr}^\omega$, the initial algebra of $ACP_{rr}$.

(ii) $ACP_{rr}$ is conservative over $ACP$ (the latter over the alphabet $A$). I.e., for $τ$-less terms $t_1, t_2$:

$$ACP_{rr} \vdash t_1 = t_2 \Rightarrow ACP \vdash t_1 = t_2.$$

Proof. (i) We have to prove

$$\mathcal{G}/ \equiv_{rr} \vdash s = t \iff ACP_{rr} \vdash s = t.$$

($\Leftarrow$) is Theorem 2.5(ii).

For ($\Rightarrow$), suppose $\mathcal{G}/ \equiv_{rr} \vdash s = t$. Then also $\mathcal{G}/ \equiv_{rr} \vdash s' = t'$ for some basic terms $s', t'$ such that $ACP_{rr} \vdash s = s', t = t'$. The result now follows by Lemma 2.18.

(ii) Suppose $t_1, t_2$ are closed terms in the signature of $ACP$ (so $τ$-less and $τ_{rr}$-less), and suppose $ACP_{rr} \vdash t_1 = t_2$. Let $t_3, t_4$ be basic terms such that $ACP_{rr} \vdash t_1 = t_3, t_2 = t_4$. Since $t_3, t_4$ can be obtained by rewrite rules $ACP_{rr} - AT$, we have $ACP \vdash t_1 = t_3, t_2 = t_4$. Now, by Lemma 2.19, $A1-7 \vdash t_3 = t_4$. Hence, $ACP \vdash t_1 = t_2$. □

3. The Expansion Theorem for $ACP_{rr}$

The Expansion Theorem is an important algebraic tool since it helps in breaking down a merge expression $x_1 || x_2 || \ldots || x_k$. For CCS, an Expansion Theorem is proved in [12]. For $ACP$ (i.e., $ACP_{rr}$ without $τ$), the analogous theorem is proved in [5]. As an example we mention the Expansion Theorem for $ACP$ in the case $k = 3$:

$$x || y || z = x || (y || z) + y || (z || x) + z || (x || y) + (y || z) || x + (z || x) || y + (x || y) || z.$$

In [5], the Expansion Theorem is proved by a straightforward induction on $k$ starting from the following assumptions:

(a) the handshaking axiom $x | y | z = \delta$ (i.e., communications are binary),
(b) the axioms of standard concurrency for $ACP$ (see Table 3).
Table 3.

<table>
<thead>
<tr>
<th>Expression</th>
</tr>
</thead>
<tbody>
<tr>
<td>$(x \parallel y) \parallel z = x \parallel (y \parallel z)$</td>
</tr>
<tr>
<td>$(x</td>
</tr>
<tr>
<td>$x</td>
</tr>
<tr>
<td>$x \parallel y = y \parallel x$</td>
</tr>
<tr>
<td>$x</td>
</tr>
<tr>
<td>$x \parallel (y</td>
</tr>
</tbody>
</table>

The standard concurrency axioms are fulfilled in the main models of ACP, to wit
the term model (initial algebra) $A_\omega$ of ACP, the projective limit model $A^\infty$ and the
graph model $A^\omega$ (see [4]).

For ACP, this is no longer true; all axioms of standard concurrency hold in the
initial algebra $A_\omega$ of ACP, except the second one.

**Example**

$$(a | \tau b) \parallel c = (a | b)c \quad \text{and} \quad a | (\tau b \parallel c) = (a | b)c + (a | c)b + a | b | c.$$  

For a proof of the validity of some of the axioms of standard concurrency in $A^\omega$, see Appendix B.

Fortunately, the Expansion Theorem carries over from ACP to ACP, in exactly
the same form. This is what we will prove in this section. The underlying intuition
is that $\parallel$ and $\parallel$ behave in ACP, just like in ACP, with the convention that $\tau$ cannot
communicate. For "\parallel" the same is true if its arguments $x, y$ are 'saturated' in the
sense that they have been maximally exposed to the rewrite rule associated to
$T2: \tau x \rightarrow \tau x + x$. As an example, consider $\tau a | b$. Evaluated according to ACP, we have

$$\tau a | b = (\tau | b)a = \delta a = \delta.$$  

However, according to ACP$\tau$,

$$\tau a | b = a | b,$$

which may be different from $\delta$. Now suppose that $\tau a$ is made 'saturated' in the
above sense, i.e., replaced by $\tau a + a$. Then, also by ACP,

$$(\tau a + a) | b = \tau a | b + a | b = (\tau | b)a + a | b = \delta + a | b = a | b,$$

just as in ACP$\tau$.

Below, the proof of the Expansion Theorem will also entail the associativity of $\parallel$. Nevertheless, we have given in Appendix B a totally different proof of the
associativity of $\parallel$ in $A^\omega$, by means of an induction to term complexity. This is done,
because the latter proof yields some useful identities (some of the axioms of standard concurrency) and for the curious fact that the proof requires an application of the
third $\tau$-law (T3). (In computations with and applications of ACP$\tau$ the first two
$\tau$-laws turn up frequently; this seems not to be the case for the third $\tau$-law.)
3.1. **Definition.** \( T \) is the set of basic terms in normal form w.r.t. the rewrite rule associated to \( A_4 : (x + y)z \to xz + yz \). (This means that if \( t \in T \), then \([t]\), the interpretation of \( t \) in the domain of process graphs \( G \) in Section 2, is a process tree.)

3.2. **Notation.** Let \( s, t \in T \). We write \( s \equiv t \), if \( s \) is a summand of \( s \), i.e., if \( t = s \) or \( t = s + r \) for some \( r \).

*Example.* \( a(\tau b + c) \equiv a(\tau b + c) + ab \).

3.3. **Definition.** Let \( x \in T \). Then \( x \) is **saturated** if

\[
\tau y \equiv x \Rightarrow y \equiv x.
\]

*Example.* (i) \( b + \tau a \) is not saturated but becomes so after an application of the \( \tau \)-law \( T2 : b + \tau a + a \).
(ii) \( b + \tau (a + \tau c) + a + \tau c + c \) is saturated.

3.4. **Proposition.** Let \( x \in T \). Then there exists a saturated \( y \in T \) such that \( ACP_{\tau} \vdash x = y \) (in fact, even \( T2 \vdash x = y \)).

3.5. **Notation.** We will denote by \( \hat{x} \) a saturated \( y \) as in Proposition 3.4. For definiteness, we take \( y \) of minimal length. So, e.g., \( b + \tau a = b + \tau a + a \).

The next proposition says that a merge in \( ACP_{\tau} \) (anyway in its initial algebra \( A_\tau^w \)) can be carried out by treating the atom \( \tau \) as if it were an 'ordinary', noncommunicating atom. Formally, this can be expressed by extending the alphabet with a fresh symbol \( t \) (acting as a stand-in for \( \tau \)) which does not communicate, replacing all \( \tau \)'s in a merge by \( t \) and after evaluating the merge restoring the \( \tau \)'s by means of the operator \( \tau_{(t)} \). The same is true for \( \parallel \); for \( \mid \) it is true under the condition that the arguments are saturated. Thus, we have the following proposition.

3.6. **Proposition.** Let \( x, y \in T \) be terms over the alphabet \( A_\tau \). Let \( t \notin A_\tau \) and extend the communication function on \( A_\tau \) to \( (A \cup \{ t \}) \), such that \( t \) does not communicate. Further, let \( x' \) be the term resulting from replacing all occurrences of \( \tau \) by \( t \). Then:

(i) \( ACP_{\tau} \vdash x \parallel y = \tau_{(t)}(x' \parallel y') \),
(ii) \( ACP_{\tau} \vdash x \| y = \tau_{(t)}(x' \| y') \),
(iii) \( ACP_{\tau} \vdash \hat{x} \parallel \hat{y} = \tau_{(t)}(\hat{x}' \parallel \hat{y}') \).

**Proof.** (i) Let

\[
x = (\tau) + \sum a_i + \sum b_j x'_j + \sum \tau x''_k
\] and

\[
y = (\tau) + \sum c_i + \sum d_m y'_m + \sum \tau y''_p
\]
where \( a_n, b_j, c_n, d_m \in A \). Then

\[
x \parallel y = x \parallel y + y \parallel x + x \parallel y =
\]

\[
(\tau y) + \sum a_i y + \sum b_i (x'_i \parallel y) + \sum \tau(x'_{i'} \parallel y) + \sum \tau(x'_{i''} \parallel y) + \\
(\tau x) + \sum c_i x + \sum d_m (y'_m \parallel x) + \sum \tau(y'_{p} \parallel x) + \\
(\tau | \tau) + (\sum \tau | c_i) + (\sum \tau | d_m y'_m) + (\sum \tau | \tau y''_p) + \\
(\sum a_i | \tau) + \sum a_i | c_i + \sum a_i | d_m y'_m + \sum \sum a_i | \tau y''_p + \\
(\sum b_j x'_j | \tau) + \sum b_j x'_j | c_i + \sum b_j x'_j | d_m y'_m + \sum b_j x'_j | \tau y''_p + \\
(\sum \tau x'_k | \tau) + \sum \tau x'_k | c_i + \sum \tau x'_k | d_m y'_m + \sum \tau x'_k | \tau y''_p + \\.
\]

Here the five enclosed summands can be skipped, in view of the following claim.

**Claim.** \( x' \equiv x \& y' \equiv y \Rightarrow x' \parallel y' \equiv x \parallel y \equiv \tau(x \parallel y) \).

**Proof of the Claim.** If \( x' \equiv x, y' \equiv y \), then by the linearity laws CM8, 9 for "|" at once: \( x' | y' \equiv x | y \). Further, \( x \parallel y \equiv \tau(x \parallel y) \) follows since

\[
ACP, \tau \vdash \tau(x \parallel y) = \tau(x \parallel y + y \parallel x + x \parallel y) = \tau(x \parallel y + y \parallel x + y \parallel x + x \parallel y) + x \parallel y.
\]

So, e.g., the summand \( \sum a_i | \tau y''_p = \sum a_i | y''_p \equiv \sum \tau(y''_p \parallel x) \) (since \( a_i \equiv x \)); likewise, the other four enclosed summands can be shown to be summands of non-enclosed summands. On the other hand, the give corresponding summands in \( \tau(x' \parallel y') \) are equal to \( \delta \), since \( t \) does not communicate. The remaining summands pose no problem, e.g.:

\[
\sum b_j (x' \parallel y) = \tau(x' \parallel y) \sum b_j (x'_j \parallel y')
\]

follows by

\[
\tau(x') \sum b_j (x'_j \parallel y') = \sum b_j \tau(x'_j \parallel y')
\]

and the induction hypothesis

\[
x'_j \parallel y = \tau(x'_j \parallel y')
\]

(induction on the sum of the term complexities).

(ii) The case of \( \parallel \) is similar to that of \( \parallel \).

(iii) It is easy to show that a saturated term \( \bar{x} \in T \) can be decomposed as follows:

\[
\bar{x} = (\tau) + \sum a_i + \sum b_j y_j + \sum \tau \bar{x}_k,
\]

where \( a_n, b_j \in A, n, m, l \geq 0 \), and the \( \bar{x}_k \) are again saturated. Note that the length of \( \bar{x}_k \) is less than that of \( \bar{x} \). We will use this for an induction on the lengths of \( \bar{x}, \bar{y} \) in the statement to prove.
We consider a typical example; the general proof involves only greater notational complexity. Let
\[
\bar{x} = a + bx_1 + \tau \bar{x}_2 + \bar{x}_2,
\]
\[
\bar{y} = \tau + c + dy_1 + \tau \bar{y}_2 + \bar{y}_2.
\]

Then
\[
\bar{x} \mid \bar{y} = \begin{align*}
\bar{x} & \mid a \mid \tau + a \mid c + a \mid dy_1 + a \mid \tau \bar{y}_2 + a \mid \bar{y}_2 + \\
\bar{x} & \mid bx_1 \mid \tau + bx_1 \mid c + bx_1 \mid dy_1 + bx_1 \mid \tau \bar{y}_2 + bx_1 \mid \bar{y}_2 + \\
\bar{x} & \mid \tau \bar{x}_2 \mid \tau + \tau \bar{x}_2 \mid c + \tau \bar{x}_2 \mid dy_1 + \tau \bar{x}_2 \mid \tau \bar{y}_2 + \tau \bar{x}_2 \mid \bar{y}_2 + \\
\bar{x} & \mid \bar{x}_2 \mid \tau + \bar{x}_2 \mid c + \bar{x}_2 \mid dy_1 + \bar{x}_2 \mid \tau \bar{y}_2 + \bar{x}_2 \mid \bar{y}_2 + \\
\end{align*}
\]

Note that the enclosed summands can be skipped, since (by virtue of the saturation requirement) they are equal to other summands: e.g., \(a \mid \tau \bar{y}_2 = a \mid \bar{y}_2\) (by axiom TC4), \(bx_1 \mid \tau \bar{y}_2 = bx_1 \mid \bar{y}_2\). Now these are just the terms which are 'lost' when evaluating \(\tau_{(t)}(\bar{x} \mid \bar{y})\) (since \(t\) does not communicate). Namely:
\[
\bar{x} \mid \bar{y}' = \begin{align*}
\bar{x} & \mid t + a \mid c + a \mid dy_1' + \delta + a \mid \bar{y}_2' + \\
\bar{x} & \mid bx_1 \mid t + bx_1 \mid c + bx_1 \mid dy_1' + \delta + bx_1 \mid \bar{y}_2' + \\
\delta & + \delta + \delta + \delta + \delta + \\
\bar{x} & \mid t + \bar{x}_2 \mid c + \bar{x}_2 \mid dy_1' + \delta + \bar{x}_2 \mid \bar{y}_2' +
\end{align*}
\]

To see that \(\tau_{(t)}(\bar{x} \mid \bar{y}') = \bar{x} \mid \bar{y}\) we can inspect the summands separately (since \(\tau_{(t)}\) distributes over \(+\)). Indeed, \(a \mid \tau = \tau_{(t)}(a \mid t) = \delta\); and, e.g., \(\bar{x}_2 \mid dy_1 = \tau_{(t)}(\bar{x}_2 \mid dy_1')\) follows by the induction hypothesis, using the fact that \(dy_1' = dy_1\).

In the same way one can prove the following proposition which generalises Proposition 3.6(i) and is of independent interest.

3.7. Proposition. (i) Let \(I \subseteq A\) be such that \(I \mid A = \{\delta\}\). (Here \(I \mid A = \{c \mid \exists i \in I, a \in A, i \mid a = c\}\). Then, in \(A_w^\tau\),
\[
\tau_I(x \parallel y) = \tau_I(\tau_I(x) \parallel \tau_I(y)).
\]

(ii) Moreover, let \((A \mid A) \cap I = \emptyset\). Then, in \(A_w^\tau\),
\[
\tau_I(x \parallel y) = \tau_I(x) \parallel \tau_I(y).
\]

3.8. Corollary. \(A_w^\tau = x \parallel (y \parallel z) = (x \parallel y) \parallel z\).
Proof. Let \( t \) be as in Proposition 3.6. Note that Proposition 3.6(i) entails \( (x \parallel y)' = x' \parallel y' \). Now:

\[
x \parallel (y \parallel z) = \tau_{(t)}(x' \parallel (y \parallel z')) = \tau_{(t)}((x' \parallel y') \parallel z') \tag{*} = (x \parallel y) \parallel z.
\]

Here, \((*)\) follows from the associativity of \( \parallel \) in ACP (see [2]). \( \square \)

3.9. Expansion Theorem for ACP. Let communication be binary. Then, in \( A^\omega_r \),

\[
x_1 \parallel \ldots \parallel x_k = \sum_{1 \leq i \leq k} x_i \parallel X^{i}_k + \sum_{1 \leq i < j \leq k} (x_i | x_j) \parallel X^{ij}_k,
\]

where \( X^i_k \) is the merge of \( x_i, \ldots, x_k \) except \( x_i \), and \( X^{ij}_k \) is the merge of \( x_i, \ldots, x_k \) except \( x_i, x_j \) \((k \geq 3)\).

Proof

\[
x_1 \parallel \ldots \parallel x_k = \bar{x}_1 \parallel \ldots \parallel \bar{x}_k = \tau_{(t)}(\bar{x}^{i}_1 \parallel \ldots \parallel \bar{x}^{i}_k) \\
= \tau_{(t)}(\sum_{(\ast)} \bar{x}^{i}_1 \parallel (\bar{X}^{i}_k)' + \sum_{(\ast)} (\bar{x}^{i}_1 | \bar{x}^{i}_j) \parallel (\bar{X}^{ij}_k)') \\
= \sum_{(\ast)} \tau_{(t)}(\bar{x}^{i}_1 \parallel (\bar{X}^{i}_k)') + \sum_{(\ast)} \tau_{(t)}((\bar{x}^{i}_1 | \bar{x}^{i}_j) \parallel (\bar{X}^{ij}_k)') \\
= \sum_{(\ast)} \tau_{(t)}(\bar{x}^{i}_1 \parallel \tau_{(t)}(\bar{X}^{i}_k)') + \sum_{(\ast)} \tau_{(t)}(\bar{x}^{i}_1 \parallel \tau_{(t)}(\bar{X}^{ij}_k)'). \\
= \sum_{(\ast)} \bar{x} \parallel \bar{X}^{i}_k + \sum_{(\ast)} (x_i | x_j) \parallel X^{ij}_k \\
= \sum_{(\ast)} x_i \parallel X^{i}_k + \sum_{(\ast)} (x_i | x_j) \parallel X^{ij}_k.
\]

Here, \((\ast)\) is the Expansion Theorem for ACP (see [5]) and \((\ast\ast)\) is by Proposition 3.6. \( \square \)

Appendix A. Termination of ACP reductions proved by recursive path orderings

In this appendix we will prove the termination result in the Elimination Theorem 2.20 by the method of recursive path orderings as in [7]. Since we will give a slightly different presentation of recursive path orderings, a short account of this method will be given. Our presentation replaces Dershowitz's inductive definition of the recursive path ordering by a reduction procedure (which may be seen as an 'operationalisation' of that inductive definition). This reduction procedure provides a somewhat easier notation in applications.

We start with the basis of the recursive path ordering method, the Kruskal Tree Theorem. First we need a definition.

A.1. Definition. (i) Let \( D \) be the domain of finite commutative rooted trees whose nodes are labeled with natural numbers; alternatively one may consider an element
t of \( D \) as a partially ordered multiset of natural numbers such that \( t \) has a least element.

**Example**

\[
t = 3(5, 7(9), 8(0(1, 5))).
\]

We will use the self-explaining notation \( t = 3(5, 7(9), 8(0(1, 5))) \). This notation is ambiguous since the 'arguments' of the 'operators' may be permuted, e.g., also \( t = 3(8(0(5, 1)), 5, 7(9)) \).

(ii) Let \( t, s \in D \). We say that \( s \) is covered by \( t \), notation \( s \sqsubseteq t \), if there is an injection \( \varphi : \text{NODES}(s) \to \text{NODES}(t) \) which is an order-preserving isomorphism and such that for all nodes \( \alpha \in \text{NODES}(s) \) we have: \( \text{label}(\alpha) \leq \text{label}(\varphi(\alpha)) \) where \( \leq \) is the ordering on \( \mathbb{N} \).

**Example.** \( s = 2(9, 7(4, 0)) \sqsubseteq t \) as in (i):

\[
s = \begin{array}{c}
2
\end{array} \begin{array}{c}
\varphi
\end{array} \begin{array}{c}
3
\end{array} = \begin{array}{c}
t
\end{array}
\]

Clearly, \( \sqsubseteq \) is a p.o. on \( D \). Now there is the following beautiful theorem.

**A.2. Kruskal Tree Theorem.** Let \( t_1, t_2, t_3, \ldots \) be a sequence in \( D \). Then for some \( i < j \): \( t_i \sqsubseteq t_j \).

In fact, this is not the most general formulation of the theorem (see [7]). The formulation there is stronger in two respects: the linear ordering of the labels (in our case \( \mathbb{N} \)) can be taken to be a partial order which is well-founded; and secondly, Kruskal's original formulation concerns noncommutative trees and an embedding \( \varphi \) as above must also respect the 'left-to-right' ordering. Clearly, that version implies immediately the above statement of the Tree Theorem. For a short proof, see [8].

The next definition is from [7].

**A.3. Definition.** The p.o. \( \triangleright \) on \( D \) is defined inductively as follows: \( t = n(t_1, \ldots, t_k) \triangleright m(s_1, \ldots, s_l) = s \) \( (k, l \geq 0) \) iff
(i) $n > m$ and $t \triangleright s_i$ for all $i = 1, \ldots, l$, or
(ii) $n = m$ and $\{t_1, \ldots, t_k\} \triangleright \triangleright \{s_1, \ldots, s_l\}$ where $\triangleright \triangleright$ is the p.o. on multisets of elements of $D$ induced by $\triangleright$, or
(iii) $n < m$ and $t_i \triangleright s$ for some $i \in \{1, \ldots, k\}$.

It is implicit in [7] that an equivalent definition of $\triangleright$ is the following.

A.4. **Definition.** The p.o. $\triangleright$ on $D$ is defined inductively as follows:

(a) $t = n(t_1, \ldots, t_k) \triangleright m(s_1, \ldots, s_l) = s$ ($k, l \geq 0$) iff
   (i) as above, or
   (ii) as above, or
   (iii)' $s = t_i$ for some $i \in \{1, \ldots, k\}$.

(b) $\triangleright$ is transitive.

(Here the cases (i), (ii), (iii)' may overlap. The transitivity has to be required explicitly now.)

A.5. **Example**

\[
\begin{array}{c}
\begin{array}{c}
 t = \\
 5 \\
 6 \\
 6 \\
 8
\end{array} \\
\begin{array}{c}
 \triangleright \\
 4 \\
 6 \\
 6 \\
 6
\end{array} \\
\begin{array}{c}
 = s \\
 8 \\
 8 \\
 8 \\
 8
\end{array}
\end{array}
\]

**Proof.** By (i) from Definition A.3, $t \triangleright s$ if

(a) $t \triangleright 6$ and (b) $t \triangleright 5$ and (c) $t \triangleright 4$

\[
\begin{array}{c}
\begin{array}{c}
 t = \\
 5 \\
 6 \\
 6 \\
 8
\end{array} \\
\begin{array}{c}
 \triangleright \\
 4 \\
 6 \\
 6 \\
 8
\end{array} \\
\begin{array}{c}
 = s \\
 8 \\
 8 \\
 8 \\
 8
\end{array}
\end{array}
\]

(a) follows by (iii) of Definition A.3;

(b) follows by (ii) and $7 \triangleright 8$ (by (iii)).

(c) follows from (d) $t \triangleright 6$ and (e) $t \triangleright 6$

\[
\begin{array}{c}
\begin{array}{c}
 t = \\
 5 \\
 6 \\
 6 \\
 8
\end{array} \\
\begin{array}{c}
 \triangleright \\
 4 \\
 6 \\
 6 \\
 8
\end{array} \\
\begin{array}{c}
 = s \\
 8 \\
 8 \\
 8 \\
 8
\end{array}
\end{array}
\]
(d) is by (iii) and (e) is so by (iii) since

\[
\begin{array}{c|c|c|c|c|c|c|c}
7 & 6 & 8 & 8 & 8 & 8 & 8 & 8 \\
\end{array}
\]
(by i), (iii).

So establishing that \( t \Rightarrow s \) requires a miniature proof. Another presentation may be more convenient: instead of by the inductive definition above we can also define \( \Rightarrow \) by an auxiliary reduction procedure as follows.

Let \( D^* \) be \( D \) where some nodes of \( t \in D \) may be marked with \( * \). E.g.,

\[
3^*(1, 2^*(4)) = \quad 3^* \quad \in D^*.
\]

\[
\begin{array}{c}
1 \\
\end{array}
\begin{array}{c}
2^* \\
4
\end{array}
\]

\[
\begin{array}{c}
3 \\
\end{array}
\]

**Notation.** If \( t = n(t_1, \ldots, t_k) \) or \( t = n^*(t_1, \ldots, t_k) \), then \( t^* = n^*(t_1, \ldots, t_k) \).

(The marker \( * \) can be understood as a command to replace the marked term by a lesser term.)

**A.6. Definition.** On \( D^* \) a reduction relation \( \Rightarrow \) is defined as follows:

1. \( n(t_1, \ldots, t_k) \Rightarrow n^*(t_1, \ldots, t_k) \) \( (k \geq 0) \),
2. if \( n > m \), then \( n^*(t_1, \ldots, t_k) \Rightarrow m(n^*(i), \ldots, n^*(i)) \) \( (k \geq 0, s \geq 0 \text{ copies of } n^*(i)) \),
3. \( n^*(t_1, \ldots, t_k) \Rightarrow t_i \) \( (i \in \{1, \ldots, k\}, k \geq 1) \),
4. if \( t \Rightarrow s \), then \( n(-, t, -) \Rightarrow n(-, s, -) \).

Furthermore, \( \Rightarrow \Rightarrow \) is the transitive reflexive closure of \( \Rightarrow \).

(In fact, (4) is superfluous for the definition of \( \Rightarrow \Rightarrow \); without it one easily derives: if \( t \Rightarrow s \), then \( n(-, t, -) \Rightarrow n(-, s, -) \).)

We are only interested in \( * \)-free \( t \in D \subseteq D^* \). Now we have, by a tedious but routine proof which is omitted, the following proposition.

**A.7. Proposition.** Let \( t, s \in D \) (i.e., not containing \( * \)). Then:

\[
t \Rightarrow \Rightarrow s \text{ iff } t \Rightarrow s.
\]

**A.8. Example.** (i) \( 4 \Rightarrow 4^* \Rightarrow 3(4^*, 4^*) \Rightarrow 3(2(4^*), 4^*) \Rightarrow 3(2(1), 4^*) \Rightarrow 3(2(1), 0) \).
(ii) (Cf. Example A.5):

In [7], the following facts about $\triangleright$ are proved.

**A.9. Proposition.** $\triangleright$ *is a partial order.*

The proof requires a simple induction to show the irreflexivity.

**A.10. Proposition**

(i) $n(t_1, \ldots, t_k) \triangleright n(t_2, \ldots, t_k)$,

(ii) $n(t_1, \ldots, t_k) \triangleright t_i$ \hspace{1mm} $(1 \leq i \leq k)$,

(iii) $t > s \Rightarrow n(\ldots, t, \ldots) \triangleright n(\ldots, s, \ldots)$,

(iv) if $n > m$ then $n(t_1, \ldots, t_k) \triangleright m(t_1, \ldots, t_k)$. 
Proof. Using Proposition A.7, (i)–(iii) are immediate; e.g., (ii): \( n(\vec{f}) = n^*(\vec{f}) \Rightarrow t_i \) and (i): \( n(t_1, \ldots, t_k) \Rightarrow n^*(t_1, \ldots, t_k) \Rightarrow n(t_2, \ldots, t_k) \).

As to (iv): \( n(\vec{f}) = n^*(\vec{f}) \Rightarrow m(n^*(\vec{f}), \ldots, n^*(\vec{f})) \Rightarrow m(t_1, \ldots, t_k). \)

Using Proposition A.10 one easily shows the following.

A.11. Proposition. \( s \subseteq t \Rightarrow t \trianglerighteq s. \)

From this we have the following theorem.

A.12. Theorem (Dershowitz) (The termination property for the recursive path ordering \( \trianglerighteq \)). \( \trianglerighteq \) is a well-founded partial order.

Proof. Suppose \( t_0 \trianglerighteq t_1 \trianglerighteq t_2 \trianglerighteq \ldots \) is an infinite descending chain w.r.t. \( \trianglerighteq \). Then, by the Kruskal Tree Theorem A.2, \( t_i \leq t_j \) for some \( i < j \). So by Proposition A.11, \( t_j \trianglerighteq t_i \).

However, since \( \trianglerighteq \) is a p.o., this contradicts \( t_i \trianglerighteq t_j \). \( \square \)

A.13. Application to \( \text{ACP}_r \). We want to prove that the rewrite rules (from left to right) associated to the axioms of \( \text{ACP}_r \) except A1, 2, 5, C1, 2 and T1, 2, 3 are terminating. These rewrite rules have, in tree notation, the form as shown in Table 4 below.

Note that the occurrence of \( \parallel \) in the RHS of the rules CM3, CM7 prevents us to order the operators directly in a way suitable for an application of the termination property of recursive path orderings.

Therefore, we will rank the operators \( \parallel, \sqsupseteq, \mid \) in the following way. Define the weight \( |T| \) of a term \( T \) as follows:

\[
|a| = |\tau| = 1, \\
|x \parallel y| = |x| + |y| \quad \text{for} \quad \parallel = \cdot, \parallel, \mid, \\
|x + y| = \max\{|x|, |y|\}, \\
|\partial_H(x)| = |\tau_I(x)| = |x|.
\]

Now the rank of an operator \( \parallel, \sqsupseteq, \mid \) is the weight of the subterm of which it is the leading operator. Operators other than \( \parallel, \sqsupseteq, \mid \) need no rank.

The ranked operators \( \parallel_{\trianglerighteq}, \sqsupseteq_m, \mid_m, +, \cdot, \partial_H, \tau_I \) are partially ordered as follows:

\[
\parallel_{\trianglerighteq} > \sqsupseteq_m > \mid_m > \parallel_{\trianglerighteq-1} > \mid_{\trianglerighteq-1} > + > \partial_H > \tau_I > .
\]

(see Fig. 17).

Now consider a closed \( \text{ACP}_r \)-term \( T \) and obtain the ranked term \( T_r \) by assigning to all operators in \( T \) their rank.

Example

\[
T = (ab \parallel cd) \parallel (\tau q \mid (r + uv))
\]
will be ranked as

\[ T_r = (ab \parallel c d) \parallel_s (\tau q |_4 (r + uv)). \]

To \( T_r \) we associate an element \( t \in D \) by writing down the formation tree of \( T_r \):

(In fact, we must assign to the \( a, \tau, \parallel_m, \parallel_m, +, \cdot, \partial_H, \tau_I \) natural numbers corresponding to the p.o. in Fig. 17 above. To all atoms we assign, say, 0.)

It is important to note that the definition of the rank of \( \parallel, \parallel \) is such that a rewriting in term \( T \) does not cause the rank of operators 'higher' in the formation tree of \( T \) to increase (it may decrease). This is effectuated by the clause for \( + \) in the definition of 'weight'. Indeed, if \( T \rightarrow T' \) is a rewriting by one of the rewrite rules in Table 4, then \( |T| \geq |T'| \), i.e., the weight cannot increase in a rewriting. Moreover, if \( |T| \geq |T'| \), then for each context \( C[ ] \): \( |C[T]| \geq |C[T']| \).

Now we have the following theorem.

A.13.1. Theorem. The rewrite rules in Table 4 have the termination property.
Table 4. Rewrite rules associated to the axioms of ACP, \{-A1, 2, 5; C1, 2; T1, 2, 3\}.

<table>
<thead>
<tr>
<th>Rule</th>
<th>Diagram</th>
</tr>
</thead>
<tbody>
<tr>
<td>A3.  + \rightarrow x</td>
<td>CM5, 6. b \rightarrow x</td>
</tr>
<tr>
<td>A4.  + \rightarrow x</td>
<td>CM7. a \rightarrow a, b</td>
</tr>
<tr>
<td>A6.  + \rightarrow x</td>
<td>CM8, 9. + \rightarrow x</td>
</tr>
<tr>
<td>A7.  \delta \rightarrow \delta</td>
<td>D1, 2. \partial_H \rightarrow a, \delta</td>
</tr>
<tr>
<td>C3.  \delta \rightarrow \delta</td>
<td>D3. \partial_H \rightarrow +</td>
</tr>
<tr>
<td>CM1. | \rightarrow +</td>
<td>D4. \partial_H \rightarrow |</td>
</tr>
<tr>
<td>CM2. | \rightarrow |</td>
<td>TI1-5: analogous to DT, D1-4.</td>
</tr>
<tr>
<td>CM3. | \rightarrow |</td>
<td>TC1, 2. | \rightarrow \delta</td>
</tr>
<tr>
<td>CM4. | \rightarrow |</td>
<td>TC3, 4. | \rightarrow |</td>
</tr>
</tbody>
</table>

Likewise TM1, TM2.
Proof. Let be the recursive path ordering induced by the p.o. on the ranked operators as defined above. We will show that for each closed instance $t \rightarrow s$ of the rewrite rules, we have $t \triangleright s$. In order to do so, we use the alternative definition of $\triangleright$ as $\Rightarrow^*$ (the transitive closure of $\Rightarrow$). We will treat some typical cases (see Tables 5 and 6). 

Table 5.

<table>
<thead>
<tr>
<th>Case</th>
<th>Rewrite Rules</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>A3.</td>
<td>$+ \Rightarrow +^*$</td>
<td>$\rightarrow x$</td>
</tr>
<tr>
<td>A4.</td>
<td>$\cdot \Rightarrow \cdot^*$</td>
<td>$\Rightarrow + \Rightarrow + \Rightarrow +$</td>
</tr>
<tr>
<td>CM1.</td>
<td>$x^t + y^t \rightarrow x^{t+1} + y^{t+1}$</td>
<td>$\Rightarrow x^{t+1} + y^{t+1}$</td>
</tr>
</tbody>
</table>

Diagram:

[Diagram showing the proof process with nodes and edges representing the rewrite rules and their implications.]

\[\text{Diagram:} \]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]

\[\begin{array}{c}
\mathbb{L}_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\mathbb{L}^*_{x+y} \\
\end{array}\]
Table 6.

CM3.

\[
\begin{array}{c}
\text{-} \\
\downarrow \\
\text{a} \quad \text{x} \\
\downarrow \\
\text{y} \\
\end{array}
\quad \quad
\begin{array}{c}
\text{-} \\
\downarrow \\
\text{a} \quad \text{x} \\
\downarrow \\
\text{y} \\
\end{array}
\quad \quad
\begin{array}{c}
\text{-} \\
\downarrow \\
\text{a} \quad \text{x} \\
\downarrow \\
\text{y} \\
\end{array}
\quad \quad
\begin{array}{c}
\text{-} \\
\downarrow \\
\text{a} \quad \text{x} \\
\downarrow \\
\text{y} \\
\end{array}
\]
Appendix B. An inductive proof of associativity of merge in ACP~

We will prove that in ACP~, the identities as shown in Table 7 between closed terms are derivable. These are the axioms of standard concurrency as in Table 3 (Section 3), except for (2) which is a special case of the second axiom of standard concurrency. (Alternatively, (2) may be replaced by:

\[(x|y)\parallel z = x|(y\parallel z)\] if \(y\) is stable.

Here \(y\) is ‘stable’, in the terminology of Milner [12], if it does not start with a \(\tau\)-step.)

<table>
<thead>
<tr>
<th>Table 7.</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1) ((x</td>
</tr>
<tr>
<td>(2) ((x</td>
</tr>
<tr>
<td>(3) (x</td>
</tr>
<tr>
<td>(4) (x\parallel y = y\parallel x)</td>
</tr>
<tr>
<td>(5) (x</td>
</tr>
<tr>
<td>(6) (x\parallel (y\parallel z) = (x\parallel y)\parallel z)</td>
</tr>
</tbody>
</table>

In Corollary 3.8 a different proof of (6) is given. The present proof uses an essentially straightforward induction to the lengths of the terms involved; the induction has to be simultaneously applied to several of (1)–(6). These identities, however, are interesting in their own right.

The proof has two main parts; in the first and easiest part, identities (3), (4), (5) are proved. The second part takes care of the main identity, (6); the proof is complicated by the fact that we have in ACP~ only the weak version (2) of the second axiom of standard concurrency.

All identities (1)–(6) are proved for basic terms \(\in T\) (see Definition 3.1). In view of the Elimination Theorem 2.20 this entails the identities for all closed ACP~-terms \(x, y, z\).

B.1. Proposition. Let \(x, y, z \in T\). Then:

(i) ACP~ \(\vdash x|y = y|x\)

(ii) ACP~ \(\vdash x\parallel y = y\parallel x\).

Proof. Let \(|x|\) be the length in symbols of \(x\). The proof uses an induction on \(|x| + |y|\).

We prove (i), (ii) simultaneously.

The induction hypothesis is: (i), (ii) are proved for all \(x', y'\) such that \(|x'| + |y'| < |x| + |y|\). First we will prove the induction step of (i), \(x|y = y|x\).

Case 1. \(x = x_i + x_2\). So \(|x_i| < |x|, i = 1, 2\). Then \(x|y = (x_i + x_2)\parallel y = x_1|y + x_2|y = (induction hypothesis) y|x_1 + y|x_2 = y|(x_1 + x_2) = y|x.\)

Case 2. \(y = y_1 + y_2\): similar.

Case 3. \(x = \tau: x|y = \tau|y = \delta = y|\tau = y|x.\)

Case 4. \(y = \tau: similar.\)
Case 5. \(x = \tau x': x \parallel y = \tau x' \parallel y = x' \parallel y \parallel x' = y \parallel x\).

Case 6. \(x = a, y = b: x \parallel y = a \parallel b \parallel a = y \parallel x\).

Case 7. \(x = ax', y = by': x \parallel y = ax' \parallel by' = (a \parallel b)(x' \parallel y') = (b \parallel a)(y' \parallel x') = y \parallel x\).

Case 8. \(x = a, y = by': x \parallel y = (a \parallel b)y' = (b \parallel a)y' = y \parallel x\).

Case 9. \(x = ax', y = b: \) similar.

(Note that in Case 7 the induction hypothesis for (ii) is used.)

Next to show (ii) \(x \parallel y = y \parallel x\):

\[
x \parallel y = x \parallel y \parallel y \parallel x \parallel y = y \parallel x \parallel y \parallel y \parallel x = y \parallel x. \quad \Box
\]

B.2. Proposition. Let \(x, y, z \in T\). Then \(ACP_\tau \vdash (x \parallel y \parallel z) = (x \parallel y) \parallel z\).

Proof. Induction on \(|x| + |y| + |z|\).

Case 1. \(x = x_1 + x_2\). Then \(x \parallel (y \parallel z) = (x_1 \parallel (y \parallel z) + x_2 \parallel (y \parallel z) = (x_1 \parallel y) \parallel z + (x_2 \parallel y) \parallel z = ((x_1 \parallel y) + (x_2 \parallel y)) \parallel z = ((x_1 + x_2) \parallel y) \parallel z = (x \parallel y) \parallel z\).

Case 2. Similar with \(y\) and \(z\) sums of smaller terms.

Case 3. \(x, y, z\) have one of the forms \(a, \tau, au, ru\). We mention one of the \(4^3\) cases: \((\tau x' \parallel ay') \parallel b = (x' \parallel ay') \parallel b = x' \parallel (ay' \parallel b) = \tau x' \parallel (ay' \parallel b)\). Note that one of the cases is just axiom C2 from \(ACP_\tau\) (Table 2). \(\Box\)

For the second half of the proof we need two preparatory propositions.

B.3. Definition. Let \(x, y\) be closed \(ACP_\tau\)-terms. Then we define: \(ACP_\tau \vdash x \sqsubseteq y\) if, for some closed term \(z\), \(ACP_\tau \vdash y = x + z\).

B.3.1. Remark. Note the difference with \(\sqsubseteq\) as defined for \(T\), in Definition 3.2. The present 'summand inclusion', \(ACP_\tau \vdash \cdot \sqsubseteq \cdot \cdot \cdot\), is just \(\sqsubseteq\) modulo \(ACP_\tau\)-equality. In the sequel, we will sometimes write \(x \sqsubseteq y\) where \(ACP_\tau \vdash x \sqsubseteq y\) is meant, if it is clear that we are working modulo \(ACP_\tau\)-equality.

B.4. Example

(i) \(ACP_\tau \vdash a \sqsubseteq \tau a\) (since \(a = a + \tau a\)),

(ii) \(ACP_\tau \vdash a \sqsubseteq a \parallel \tau\) (since \(a \parallel \tau = \tau a + a \parallel \tau + a \parallel \tau = \tau a + a\)),

(iii) \(ACP_\tau \vdash \delta \sqsubseteq x\) for all \(x\),

(iv) \(ACP_\tau \vdash a + \tau a + \tau b \sqsubseteq b + \tau a + \tau b\).

B.5. Proposition. Let \(x, y\) be closed terms. Then:

\(ACP_\tau \vdash x \sqsubseteq y \& ACP_\tau \vdash y \sqsubseteq x \Rightarrow ACP_\tau \vdash x = y\).

Proof. We may suppose, by the Elimination Theorem 2.20, that \(x, y \in T\). Suppose \(ACP_\tau \vdash y = x + z\) for some \(z \in T\) and \(ACP_\tau \vdash x = y + u\) for some \(u \in T\). Then \(ACP_\tau \vdash x = x + z + u\). Therefore, the process trees corresponding to \(x\) and \(x + z + u\) are
bisimulate: \([x] \leftrightarrow_{\tau} [x+z+u]\). (Here, \([x]\) is the interpretation of \(x\) in the graph domain \(G\) as in Section 2; since \(x \in T\) this is a process tree.) Say \(R\) is an \(r\tau\)-bisimulation between \([x]\) and \([x+z+u]\) = \([x]+[z]+[u]\). Let \(R'\) be the restriction of \(R\) to (the node sets of) \([x]\) and \([x]+[z]\). Now \(R'\) need not be a bisimulation between these trees; however, if \(I\) is the trivial (identity) bisimulation between \([x]\) with itself, then it is not hard to see that \(R' \cup I\) is an \(r\tau\)-bisimulation between \([x]\) and \([x]+[z]\) = \([x+z]\). (Alternatively: let \(R\) be a bisimulation as indicated which is maximal w.r.t. inclusion. Then the restriction \(R'\) is a bisimulation as desired.)

Hence \(ACP_{\tau} \vdash x = x+z = y\).

**B.6. Proposition.** Let \(x\) be a closed term. Then \(ACP_{\tau} \vdash x \parallel \tau = x\).

**Proof.** We may suppose \(x \in T\), and use induction on \(|x|\).

If \(x = x_1 + x_2\), then \(x \parallel \tau = x_1 \parallel \tau + x_2 \parallel \tau = x_1 + x_2 = x\).

If \(x = a\), then \(a \parallel \tau = a\tau = a\).

If \(x = ax'\), then
\[
ax' \parallel \tau = a(x' \parallel \tau) = a(x' \parallel \tau + \tau \parallel x' + x' \parallel \tau)
\]
\[
= a(x' \parallel \tau + \tau x' + \delta) = a(x' + \tau x') = a\tau x' = ax'.
\]

The cases \(x = \tau\), \(x = \tau x'\) are similar. □

We will now start the simultaneous proof of (1), (2), (6) in Table 7.

**B.7. Theorem.** Let \(x, y, z\) be closed \(ACP_{\tau}\)-terms and \(a \in A\). Then:

(i) \(ACP_{\tau} \vdash (x \parallel y) \parallel z = x \parallel (y \parallel z)\),

(ii) \(ACP_{\tau} \vdash (x \parallel ay) \parallel z = x \parallel (ay \parallel z)\),

(iii) \(ACP_{\tau} \vdash x \parallel (y \parallel z) = (x \parallel y) \parallel z\).

**Proof.** We may assume \(x, y, z \in T\); this makes an induction to \(|x|+|y|+|z|\) possible. We will prove (i)–(iii) by a simultaneous induction. Let the induction hypothesis be that (i)–(iii) are proved for all \(x', y', z' \in T\) such that \(|x'|+|y'|+|z'| < |x|+|y|+|z|\).

First we prove the induction step (i): \((x \parallel y) \parallel z = x \parallel (y \parallel z)\).

**Case (i)1.** \(x = x_1 + x_2\). Then \((x \parallel y) \parallel z = (x_1 \parallel y) \parallel z + (x_2 \parallel y) \parallel z = (x_1 + x_2) \parallel (y \parallel z)\) (induction hypothesis).

**Case (i)2.** \(x = \tau\). Then: \((x \parallel y) \parallel z = \tau y \parallel z = \tau (y \parallel z) = \tau \parallel (y \parallel z) = x \parallel (y \parallel z)\).

**Case (i)3.** \(x = \tau x'\). Then: \((x \parallel y) \parallel z = \tau (x' \parallel y) \parallel z = \tau ((x' \parallel y) \parallel z) = \tau (x' \parallel (y \parallel z)) = \tau x' \parallel (y \parallel z) = x \parallel (y \parallel z)\).

The cases \(x = a, x = ax'\) are similar. This ends the proof of the induction step (i).

Next consider the induction step (ii): \((x \parallel ay) \parallel z = x \parallel (ay \parallel z)\). This will again be proved by a case distinction according to the formation of \(x \in T\): \(x = x_1 + x_2, x = \tau, \tau x', b, or bx'\).
Case (ii)1. \( x = x_1 + x_2 \). Then 
\[
\begin{align*}
x \mid (ay) \parallel z &= (x_1 \mid ay) \parallel z + (x_2 \mid ay) \parallel z \\
&= (x_1 \mid x_2) \mid (ay) \parallel z = x_1 \mid (ay) \parallel z
\end{align*}
\]
Case (ii)2. \( x = \tau \). Then 
\[
(x \mid ay) \parallel z = x \mid (ay) \parallel z = \delta.
\]
Case (ii)3. \( x = x' \tau \). Then 
\[
\begin{align*}
(x \mid ay) \parallel z &= (x' \tau) \mid ay \parallel z = (x' \mid ay) \parallel z = x' \mid (ay) \parallel z \\
&= \tau x' \mid (ay) \parallel z = x \mid (ay) \parallel z.
\end{align*}
\]
Case (ii)4. \( x = b \). Then 
\[
(x \mid ay) \parallel z = (b \mid ay) \parallel z = (b \mid ay) \parallel z = (b \mid ay) \parallel z,
\]
and also 
\[
(x \mid ay) \parallel z = (b \mid ay) \parallel z = (b \mid ay) \parallel z = (b \mid ay) \parallel z.
\]
Case (ii)5. \( x = bx' \). Then 
\[
\begin{align*}
(x \mid ay) \parallel z &= (bx' \mid ay) \parallel z = (b \mid x' \mid ay) \parallel z \\
&= (b \mid a) \mid (x' \mid ay) \parallel z = (b \mid a) \mid (x' \mid ay) \parallel z
\end{align*}
\]
\[
\begin{align*}
(\tau x' \mid ay) \parallel z &= ((x' \mid ay) \parallel z) \\
&= (x' \mid ay) \parallel z = (x' \mid ay) \parallel z
\end{align*}
\]
By the induction hypothesis for statement (iii) therefore 
\[
(x \mid ay) \parallel z = x \mid (ay) \parallel z.
\]
This ends the proof of the induction step (ii).

Now consider the induction step (iii): \( L = x \parallel (y \parallel z) = (x \parallel y) \parallel z = R \). By the axioms in \( ACP \), we have
\[
L = x \parallel (y \parallel z) = x \parallel (y \parallel z) + (y \parallel z) \parallel x + x \parallel (y \parallel z)
\]
Likewise, \( R \) can be expanded. We will use the following abbreviations: \( L = \sum_{i=1}^{17} l_i \) and \( R = \sum_{i=1}^{17} r_i \), where
\[
\begin{align*}
l_1 &= x \parallel (y \parallel z), & r_1 &= (x \parallel y) \parallel z, \\
l_2 &= (y \parallel z) \parallel x, & r_2 &= (x \parallel y) \parallel z, \\
l_3 &= (y \parallel z) \parallel x, & r_3 &= (y \parallel x) \parallel z, \\
l_4 &= (z \parallel y) \parallel x, & r_4 &= z \parallel (x \parallel y), \\
l_5 &= x \parallel (y \parallel z), & r_5 &= (x \parallel y) \parallel z, \\
l_6 &= x \parallel (z \parallel y), & r_6 &= (y \parallel x) \parallel z, \\
l_7 &= x \parallel (y \parallel z), & r_7 &= (x \parallel y) \parallel z.
\end{align*}
\]
Claim. \( l_i \subseteq R \), for \( i = 1, \ldots, 7 \).

From the Claim the induction step (iii) follows at once. Namely, we then have:
\[
x \parallel (y \parallel z) \subseteq (x \parallel y) \parallel z, \text{ hence by Proposition B.1(ii): } x \parallel (y \parallel z) \subseteq (x \parallel y) \parallel z.
\]
Now 
\[
z \parallel (x \parallel y) = z \parallel (y \parallel x) \subseteq x \parallel (z \parallel y) = x \parallel (y \parallel z), \text{ where } "\subseteq" \text{ follows from } (*).
\]
So we have 
\[
x \parallel (y \parallel z) \subseteq (x \parallel y) \parallel z, \text{ and, by Proposition B.5: } x \parallel (y \parallel z) = (x \parallel y) \parallel z.
\]
The remainder of the proof is devoted to the proof of the above claim.

Proof of the Claim
(a) \( l_7 = r_7 \subseteq R \) by Proposition B.2.
(b) \( l_1 = r_1 \subseteq R \) is statement (i) of this theorem; this induction step has already been proved. Likewise for \( l_2 = r_3 \subseteq R \) and \( l_4 = r_4 \subseteq R \).

(c) \( l_5 \subseteq r_6 \subseteq R \). Here, \( l_1 = (z | y) \upharpoonright x \) and \( r_6 = z \upharpoonright (y \upharpoonright x) \).

Induction on \( z \):

**Case (iii)(c)1.** \( z = z_1 + z_2 \). Then \( l_3 = ((z_1 + z_2) | y) \upharpoonright x = (z_1 | y) \upharpoonright x + (z_2 | y) \upharpoonright x \subseteq (z_1 | y) \upharpoonright x + z_2 | (y \upharpoonright x) = (z_1 + z_2) | (y \upharpoonright x) = z \upharpoonright (y \upharpoonright x) \).

**Case (iii)(c)2.** \( z = \tau \). Then \( l_3 = r_6 = \delta \).

**Case (iii)(c)3.** \( z = \tau \tau' \). Then \( l_3 = (\tau \tau' | y) \upharpoonright x = (\tau' | y) \upharpoonright x \subseteq \tau' \upharpoonright (y \upharpoonright x) = \tau \upharpoonright (y \upharpoonright x) \).

**Case (iii)(c)4.** \( z = a \). Similar to the next case.

**Case (iii)(c)5.** \( z = az' \). To prove \( (az' | y) \upharpoonright x \subseteq az' (y \upharpoonright x) \). We use an induction on \( y \):

**Case (iii)(c)5.1.** \( y = y_1 + y_2 \). Then \( (az' | (y_1 + y_2)) \upharpoonright x = (az' | y_1) \upharpoonright x + (az' | y_2) \upharpoonright x = az' | ((y_1 + y_2) \upharpoonright x) = az' | (y \upharpoonright x) \).

**Case (iii)(c)5.2.** \( y = \tau \): \( (az' | \tau) \upharpoonright x = \delta \upharpoonright x \subseteq az' | (\tau \upharpoonright x) \).

**Case (iii)(c)5.3.** \( y = \tau \tau' \): \( (az' | \tau \tau') \upharpoonright x = (az' | y') \upharpoonright x \subseteq (az') | (y' \upharpoonright x) = (az') | (\tau \upharpoonright x) \).

(\( x \upharpoonright (y \upharpoonright z) \subseteq (x | y) \upharpoonright z + (x \upharpoonright y) | z + x \upharpoonright (y \upharpoonright z) \).

The proof is again by induction on \(|x| + |y| + |z|\). We start with an induction on \( x \):

**Case (iii)(d)1.** \( x = x_1 + x_2 \). Then \( x \upharpoonright (y \upharpoonright z) = x_1 \upharpoonright (y \upharpoonright z) + x_2 \upharpoonright (y \upharpoonright z) \)

\( \subseteq (x_1 | y) \upharpoonright z + (x_1 \upharpoonright y) | z + x_1 | (y \upharpoonright z) + (x_2 | y) \upharpoonright z + (x_2 \upharpoonright y) | z = (x \upharpoonright y) \upharpoonright z + (x \upharpoonright y) | z + x \upharpoonright (y \upharpoonright z) \).

**Case (iii)(d)2.** \( x = \tau \). Then \( x \upharpoonright (y \upharpoonright z) = \delta \upharpoonright (x | y) \upharpoonright z + (x \upharpoonright y) | z + x \upharpoonright (y \upharpoonright z) \).

**Case (iii)(d)3.** \( x = \tau \tau' \). Then \( \tau \tau' | (y \upharpoonright z) = \tau \tau' | (y \upharpoonright z) \)

\( \subseteq (\tau' | y) \upharpoonright z + (\tau' \upharpoonright y) | z + \tau' | (y \upharpoonright z) = (\tau \tau' | y) \upharpoonright z + (\tau \tau' \upharpoonright y) | z + \tau \tau' | (y \upharpoonright z) = (\tau \tau' | y) \upharpoonright z + (\tau \tau' \upharpoonright y) | z + \tau \tau' | (y \upharpoonright z) = (\tau \tau' | y) \upharpoonright z + (\tau \tau' \upharpoonright y) | z + \tau \tau' | (y \upharpoonright z) = (x \upharpoonright y) \upharpoonright z + (x \upharpoonright y) | z + x \upharpoonright (y \upharpoonright z) \).

**Case (iii)(d)4.** \( x = a \): similar to the next case.

**Case (iii)(d)5.** \( x = ax' \). To prove:

\( * \) \( ax' | (y \upharpoonright z) \subseteq (ax' | y) \upharpoonright z + (ax' \upharpoonright y) | z + ax' | (y \upharpoonright z) \).
Subinduction to \( y \): write \( y = (\tau) + \sum c_i + \sum b_j y'_j + \sum \tau y''_i \). Clearly \( ax'|(y \parallel z) \) can be decomposed as a sum analogous to the sum expression for \( y \). Each of these summands of \( ax'|(y \parallel z) \) will now be proved to be \( \subseteq \) the RHS of (*)

**Case (iii)(d)5.1.** Summands \( b_j y'_j \): \( (ax')|(b_j y'_j \parallel z) = (by statement (ii) of this theorem) \( (ax' | b_j y'_j) \parallel z \subseteq (ax' | y) \parallel z \subseteq \text{RHS}(*) \).

**Case (iii)(d)5.2.** Summands \( c_i \): as the previous case.

**Case (iii)(d)5.3.** Summand \( \tau \): \( (ax'|(\tau \parallel z) = ax'|\tau z = ax'|z = (ax' \parallel \tau)|z \) since \( ax' = ax' \parallel \tau \) by Proposition B.6.

**Case (iii)(d)5.4.** Summands \( \tau y''_i \) (for convenience we drop the subscript \( l \) and write \( y = \tau y'' + y^* \)):

Now \( ax'|(\tau y'' \parallel z) = ax'|\tau(y'' \parallel z) = ax'|(y'' \parallel z) \)

\[ = ax'|((y'' \parallel z) + ax'|((z \parallel y'') + ax'|((y''|z) \subseteq \text{(induction hypothesis)} \]

\[ \subseteq (ax'|y'') \parallel z + (ax'|y'') \parallel z + ax'|((y''|z) \]

\[ + (ax'|z) \parallel y'' + (ax'|z) \parallel y'' + ax'|((y''|z) + ax'|((y''|z) \]

\[ = (\text{Here the first summand equals the fifth by (ii) of this theorem, and likewise the second equals the fourth.}) \]

\[ = (ax'|y'') \parallel z + (ax'|y'') \parallel z + ax'|((y''|z) \]

\[ = (ax'|y'' \parallel z) + ax'|((y''|z) \]

This matches the RHS of (*) except for the second summand. So it remains to prove:

| If \( y = \tau y'' + y^* \), then \( (ax'|y'' \parallel z) \subseteq (ax'|y) \parallel z \) (**)|

**Proof of (**):** induction on \( z \).

**Case (iii)(d)5.4.1.** \( z = z_1 + z_2 \). Then \( (ax'|y'' \parallel z_1 + z_2) = (ax'|y'' \parallel z_1) + (ax'|y'' \parallel z_2) \)

\[ + (ax'|y'') \parallel z_1 \subseteq (ax'|y) \parallel z_1 + (ax'|y) \parallel z_2 = (ax'|y) \parallel z. \]

**Case (iii)(d)5.4.2.** \( z = \tau \): \( (ax'|y'') \parallel \tau = \delta \subseteq \text{RHS}(**) \).

**Case (iii)(d)5.4.3.** \( z = \tau z' \): \( (ax'|y'') \parallel (\tau z') = (ax'|y'') \parallel z' \subseteq (ax'|y) \parallel z' \)

\[ = (ax'|y') \parallel (\tau z'). \]

**Case (iii)(d)5.4.4.** \( z = b \): \( (ax'|y'') \parallel b = a(x' \parallel y') \parallel b = (a \parallel b)(x' \parallel y') \).

Now \( x' \parallel y' = x' \parallel ((\tau y'' + y^*) = x' \parallel (\tau y'' + y^*) + (\tau y'' + y^*) \parallel x' \]

\[ + x'|((\tau y'' + y^*) = \tau(y'' \parallel x') + T. \]

So: \( (ax'|y) \parallel b = (a \parallel b)(x' \parallel y) \)

\[ = (a \parallel b)(\tau(y'' \parallel x') + T) + (a \parallel b)(y'' \parallel x'). \]

Here \( \triangleq = \) is an application of the third \( \tau \)-law, T3. Therefore,

\[ (ax'|y') \parallel b = (a \parallel b)(x' \parallel y') \subseteq (ax'|y) \parallel b. \]

**Case (iii)(d)5.4.5.** \( z = b z' \): similar.

This ends the proof of induction step (iii), and thereby of the theorem. □
References


